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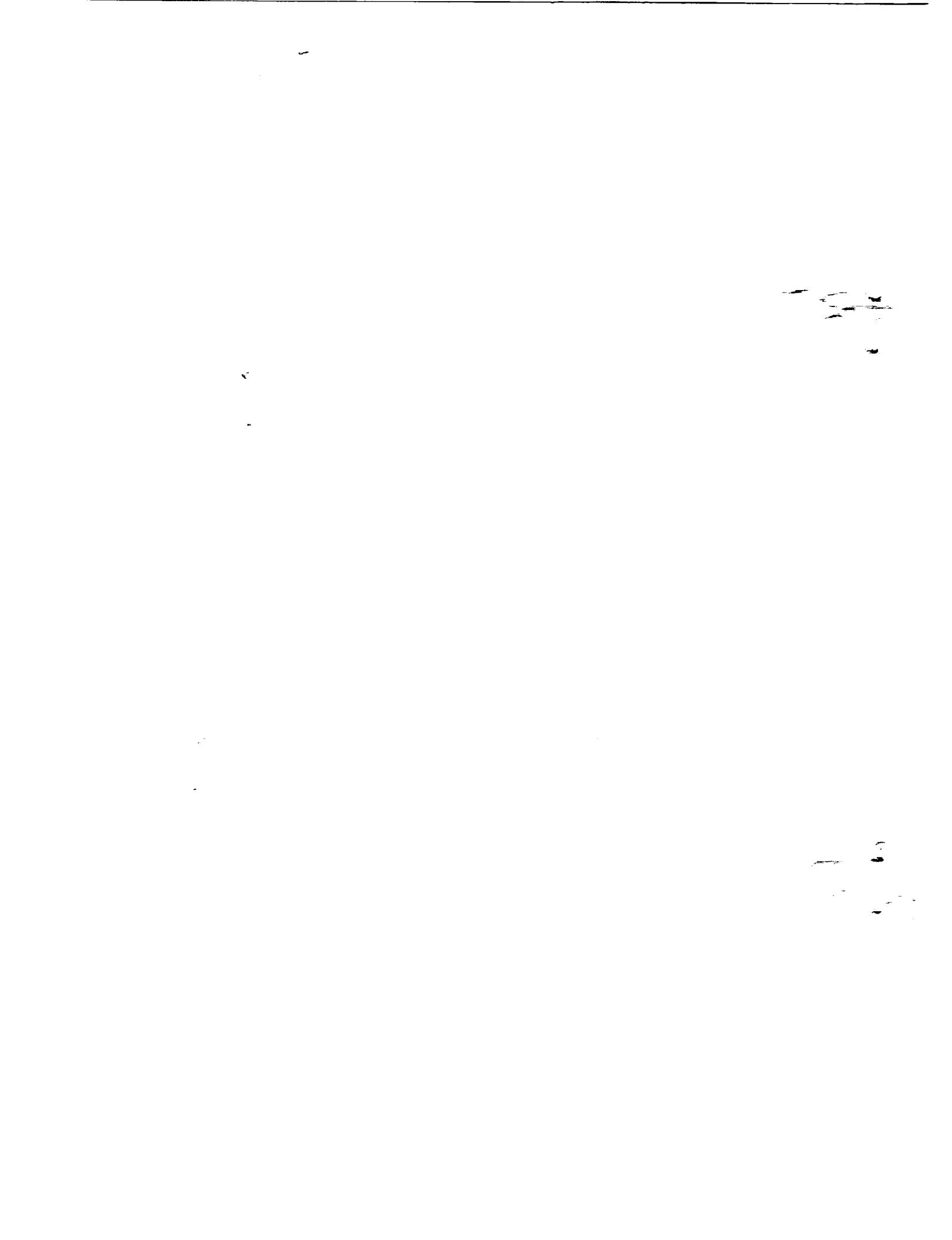
AN IMPROVED METHOD FOR THE AERODYNAMIC
ANALYSIS OF WING-BODY-TAIL CONFIGURATIONS
IN SUBSONIC AND SUPERSONIC FLOW

Part II - Computer Program Description

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16. Abstract A new method has been developed for calculating the pressure distribution and aerodynamic characteristics of wing-body-tail combinations in subsonic and supersonic potential flow. A computer program has been developed to perform the numerical calculations.			
<p>The configuration surface is subdivided into a large number of panels, each of which contains an aerodynamic singularity distribution. A constant source distribution is used on the body panels, and a vortex distribution having a linear variation in the streamwise direction is used on the wing and tail panels. The normal components of velocity induced at specified control points by each singularity distribution are calculated and make up the coefficients of a system of linear equations relating the strengths of the singularities to the magnitude of the normal velocities.</p> <p>The singularity strengths which satisfy the boundary condition of tangential flow at the control points for a given Mach number and angle of attack are determined by solving this system of equations using an iterative procedure. Once the singularity strengths are known, the pressure coefficients are calculated, and the forces and moments acting on the configuration determined by numerical integration.</p> <p>This report describes the computer program developed to perform the numerical calculations.</p>			
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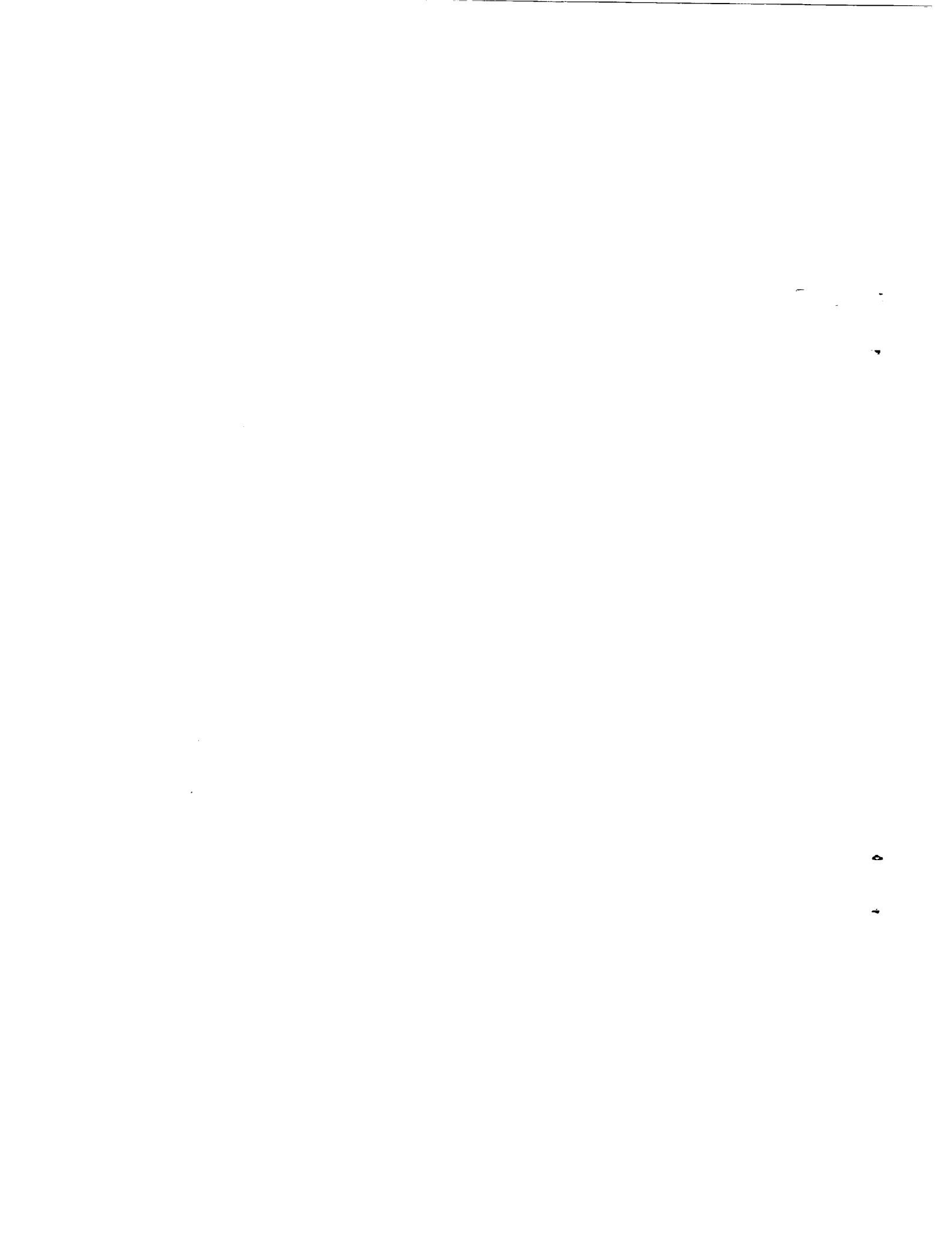


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INTRODUCTION

A new method has been developed for calculating the pressure distribution and aerodynamic characteristics (lift, drag, and pitching moment) of wing-body-tail combinations in subsonic and supersonic potential flow. This report describes the computer program developed to perform the numerical calculations.

METHOD OF SOLUTION

The configuration surface is subdivided into a large number of panels, each of which contains an aerodynamic singularity distribution. A constant source distribution is used on the body panels, and a vortex distribution having a linear variation in the streamwise direction is used on the wing and tail panels. The normal components of velocity induced at specified control points by each singularity distribution are calculated and make up the coefficients of a system of linear equations relating the strengths of the singularities to the magnitude of the normal velocities.

The singularity strengths which satisfy the boundary condition of tangential flow at the control points for a given Mach number and angle of attack are determined by solving this system of equations using an iterative procedure. Once the singularity strengths are known, the pressure coefficients are calculated, and the forces and moments acting on the configuration determined by numerical integration. A detailed description of the method is given in Part I of this report.

PROGRAM DESCRIPTION

The computer program is written in CDC FORTRAN IV, version 2.3 for a SCOPE 3.0 operating system and library file. It is designed for the CDC 6000 series of computers, occupies 70,000 (octal) words, and operates in OVERLAY mode. The program requires five peripheral disc files in addition to the input and output files.

PROGRAM INPUT DATA

The input to this program consists of two basic parts, namely, the numerical description of the configuration geometry as adapted from reference 1, and an auxiliary data set specifying the singularity paneling scheme, program options, Mach number, and angle of attack. The program input is illustrated by the sample case presented in Appendix III.

Description of Input Geometry Cards

The configuration is defined to be symmetrical about the xz plane, therefore only one side of the configuration need be described. The convention used in this program is to present that half of the configuration located on the positive y side of the xz plane. The number of input cards depends on the number of components used to describe the configuration, and the amount of detail used to describe each component.

Card 1 - Identification.- Card 1 contains any desired identifying information in columns 1-80.

Card 2 - Control integers.- Card 2 contains 24 integers, each punched right justified in a 3-column field. Columns 73-80 may be used in any desired manner. Card 2 contains the following:

Columns	Variable	Value	Description
1-3	J0	0	No reference area
		1	Reference area to be read
4-6	J1	0	No wing data
		1	Cambered wing data to be read
		-1	Uncambered wing data to be read
7-9	J2	0	No fuselage data
		1	Data for arbitrarily shaped fuselage to be read
		-1	Data for circular fuselage to be read (With J6=0, fuselage will be cambered. With J6=-1, fuselage will be symmetrical with xy-plane. With J6=1, entire configuration will be symmetrical with xy-plane)
10-12	J3	0	No pod (nacelle) data
		1	Pod (nacelle) data to be read

Columns	Variable	Value	Description
13-15	J4	0 1	No fin (vertical tail) data Fin (vertical tail) data to be read
16-18	J5	0 1	No canard (horizontal tail) data Canard (horizontal tail) data to be read
19-21	J6	0 1 -1	A cambered circular or arbitrary fuselage if J2 is nonzero Complete configuration is sym- metrical with respect to xy-plane, which implies an uncambered circu- lar fuselage if there is a fuse- lage Uncambered circular fuselage with J2 nonzero
22-24	NWAF	2-20	Number of airfoil sections used to describe the wing
25-27	NWAFOR	3-30	Number of ordinates used to define each wing airfoil section. If the value of NWAFOR is input with a negative sign, the program will expect to read lower surface ordinates also
28-30	NFUS	1-4	Number of fuselage segments
31-33	NRADX(1)	3-30	Number of points used to represent half-section of first fuselage segment. If fuselage is circular, the program computes the indicated number of y- and z-ordinates
34-36	NFORX(1)	2-30	Number of stations for first fuse- lager segment
37-39	NRADX(2)	3-30	Same as NRADX(1), but for second fuselage segment
40-42	NFORX(2)	2-30	Same as NFORX(1), but for second fuselage segment
43-45	NRADX(3)	3-30	Same as NRADX(1), but for third fuselage segment

Columns	Variable	Value	Description
46-48	NFORX(3)	2-30	Same as NFORX(1), but for third fuselage segment
49-51	NRADX(4)	3-30	Same as NRADX(1), but for fourth fuselage segment
52-54	NFORX(4)	2-30	Same as NFORX(1), but for fourth fuselage segment
55-57	NP	0-9	Number of pods described
58-60	NPODOR	4-30	Number of stations at which pod radii are to be specified
61-63	NF	0-6	Number of fins (vertical tails) to be described
64-66	NFINOR	3-10	Number of ordinates used to describe each fin (vertical tail) airfoil section
67-69	NCAN	0-2	Number of canards (horizontal tails) to be described
70-72	NCANOR	3-10	Number or ordinates used to define each canard (horizontal tail) airfoil section. If the value of NCANOR is input with a negative sign, the program will expect to read lower surface ordinates also, otherwise the airfoil is assumed to be symmetrical

Cards 3, 4, . . . - remaining input data cards. - The remaining input data cards contain a detailed description of each component of the configuration. Each card contains up to 10 values, each value punched in a 7-column field with a decimal point and may be identified in columns 73-80. The cards are arranged in the following order: reference area, wing data cards, fuselage data cards, pod data cards, fin (vertical tail) data cards, and canard (horizontal tail) data cards.

Reference area card: The reference area value is punched in columns 1-7 and may be identified as REFA in columns 73-80.

Wing data cards: The first wing data card (or cards) contains the locations in percent chord at which the ordinates of

all the wing airfoils are to be specified. There will be exactly NWAFOR locations in percent chord given. Each card may be identified in columns 73-80 by the symbol XAFJ where J denotes the last location in percent chord given on that card.

The next wing data cards (there will be NWAFO cards) each contain four numbers which give the origin and chord length of each of the wing airfoils that is to be specified. The card representing the most inboard airfoil is given first, followed by the cards for successive airfoils. These cards contain the following:

Columns	Contents
1-7	x-ordinate of airfoil leading edge
8-14	y-ordinate of airfoil leading edge
15-21	z-ordinate of airfoil leading edge
22-28	airfoil streamwise chord length
73-80	card identification, WAFORGJ where J denotes the particular airfoil, thus WAFORG1 denotes the most inboard airfoil

If a cambered wing has been specified, the next set of wing data cards is the mean camber line cards. There will be NWAFOR values of delta z referenced to the z-ordinate of the airfoil leading edge, each value corresponding to a specified percent chord location on the airfoil. These cards are arranged in the order which begins with the most inboard airfoil and proceeds outboard. Each card may be identified in columns 73-80 as TZORDJ where J denotes the particular airfoil. Note that the z-ordinates are dimensional.

Next are the wing ordinate cards. There will be NWAFOR values of half-thickness specified for each airfoil expressed as percent chord. These cards are arranged in the order which begins with the most inboard airfoil and proceeds outboard. Each card may be identified in columns 73-80 as WAFORDJ where J denotes the particular airfoil.

Fuselage data cards: The first card (or cards) specifies the x values of the fuselage stations of the first segment. There will be NFORX(1) values and the cards may be identified in columns 73-80 by the symbol XFUSJ where J denotes the number of the last fuselage station given on that card.

If the fuselage is circular, the next card (or cards) gives the fuselage cross sectional areas, and may be identified in columns 73-80 by the symbol FUSARDJ where J denotes the number of the last fuselage station given on that card. If the fuselage is of arbitrary shape, NRADX(1) values of the y-ordinates for a half-section are given and identified in columns 73-80 as YJ where J is the station number. Following the y-ordinates are the NRADX(1) values of the corresponding z-ordinates for the half-section identified in columns 73-80 as ZJ where J is the station number. Each station will have a set of y and z, and the convention of ordering the ordinates from bottom to top is observed.

For each fuselage segment a new set of cards as described must be provided. The segment descriptions should be given in order of increasing values of x.

Pod data cards: The first pod (nacelle) data card specifies the location of the origin of the first pod. The card contains the following:

Columns	Contents
1-7	x-ordinate of origin of first pod
8-14	y-ordinate of origin of first pod
15-21	z-ordinate of origin of first pod
73-80	card identification, PODORGJ where J denotes the pod number

The next pod input data card (or cards) contains the x-ordinates, referenced to the pod origin, at which NPODOR values of the pod radii are to be specified. The first x value must be zero and the last x value is the length of the pod. These cards may be identified in columns 73-80 by the symbol XPODJ where J denotes the pod number.

For each additional pod, new PODORG, XPOD, and PODR cards must be provided. Only single pods are described but the program assumes that if the y-ordinate is not zero an exact duplicate is located symmetrically with respect to the xz-plane, a y-ordinate of zero implies a single pod.

Fin data cards: Exactly three data input cards are used to describe a fin (vertical tail). The first fin data card contains the following:

Columns

Contents

1-7	x-ordinate on inboard airfoil leading edge
8-14	y-ordinate of inboard airfoil leading edge
15-21	z-ordinate of inboard airfoil leading edge
22-28	chord length of inboard airfoil
29-35	x-ordinate of outboard airfoil leading edge
36-42	y-ordinate of outboard airfoil leading edge
43-49	z-ordinate of outboard airfoil leading edge
50-56	chord length of outboard airfoil
73-80	card identification, FINORGJ where J denotes the fin number

The second fin input data card contains NFINOR values of x expressed in percent chord at which the fin airfoil ordinates are to be specified. The card may be identified in columns 73-80 as XFINJ where J denotes the fin number.

The third fin input data card contains NFINOR values of the fin airfoil half-thickness expressed in percent chord. Since the fin airfoil must be symmetrical, only the ordinates on the positive y side of the fin chord plane are specified. The card identification FINORDJ may be given in columns 73-80 where J denotes the fin number.

For each fin, new FINORG, XFIN, and FINORD cards must be provided. Only single fins are described but the program assumes that if the y-ordinate is not zero an exact duplicate is located symmetrically with respect to the xz-plane, a y-ordinate of zero implies a single fin.

Canard data cards: If the canard (or horizontal tail) airfoil is symmetrical, exactly three cards are used to describe a canard, and the input is given in the same manner as for a fin. If, however, the canard airfoil is not symmetrical

(indicated by a negative value of NCANOR), a fourth canard input data card will be required to give the lower ordinates. The information presented on the first canard input data card is as follows:

Columns	Contents
1-7	x-ordinate of inboard airfoil leading edge
8-14	y-ordinate of inboard airfoil leading edge
15-21	z-ordinate of inboard airfoil leading edge
22-28	chord length of inboard airfoil
29-35	x-ordinate of outboard airfoil leading edge
36-42	y-ordinate of outboard airfoil leading edge
43-49	z-ordinate of outboard airfoil leading edge
50-56	chord length of outboard airfoil
73-80	card identification, CANORGJ where J denotes the canard number

The second canard input data card contains NCANOR values of x expressed in percent chord at which the canard airfoil ordinates are to be specified. The card may be identified in columns 73-80 as XCANJ where J denotes the canard number.

The third canard input data card contains NCANOR values of the canard airfoil half-thickness expressed in percent chord. This card may be identified in columns 73-80 as CANORDJ where J denotes the canard number. If the canard airfoil is not symmetrical, the lower ordinates are presented on a second CANORD card. The program expects both upper and lower ordinates to be punched as positive values in percent chord.

For another canard, new CANORG, XCAN, and CANORD cards must be provided.

Description of Auxiliary Input Cards

Card 1.1 - Identification.- Card 1.1 contains any desired identifying information in columns 1-80.

Card 1.2 - Boundary condition and control point definition.- Non planar boundary conditions are always applied on a body, however card 1.2 permits the selection of boundary conditions to apply on a wing, fin (vertical tail), or canard (horizontal tail). This card also selects the output print options. This card contains the following:

Columns	Variable	Value	Description
1-3	LINBC	0	Control points on surface of wing, fin (vertical tail), and canard (horizontal tail). This is referred to as the nonplaner boundary condition option.
		1	Control points in plane of wing, fin (vertical tail), and canard (horizontal tail). This is referred to as the planar boundary condition option.
4-6	THICK	0	Do not calculate wing thickness matrix
		1	Calculate wing thickness matrix if LINBC = 1
7-9	PRINT	0	Print out the pressures and the forces and moments
		1	Print out option 0 and the spanwise loads on the wing, fins, and canards
		2	Print out option 1 and the velocity components and source and vortex strengths
		3	Print out option 2 and the steps in the iterative solution
		4	Print out option 3 and the axial and normal velocity matrices

A negative value of print adds the panel geometry print out to the output indicated for options 1 through 4.

LINBC, THICK, and PRINT are punched as right justified integers. THICK is not used if LINBC = 0.

Card 2.1 - Revised configuration paneling description control integers. - The contents of card 2.1 are punched as right justified integers as follows:

Columns	Variable	Value	Description
1-3	K0	0 1	No reference lengths Reference length data to be read
4-6	K1	0 1 3	No wing data Wing data to be read, wing has a sharp leading edge Wing data to be read, wing has a round leading edge
7-9	K2	0 1	No body data Body data follows
10-12	K3		Not used
13-15	K4	0 1 3	No fin (vertical tail) data Fin (vertical tail) data to be read, fin has a sharp leading edge Fin (vertical tail) data to be read, fin has a round leading edge
16-18	K5	0 1 3	No canard (horizontal tail) data Canard (horizontal tail) data to be read, canard has a sharp leading edge Canard (horizontal tail) data to be read, canard has a round leading edge
19-21	K6		Not used
22-24	KWAF	0, 2-20	Number of wing sections used to define the inboard and outboard panel edges. If KWAF = 0, the panel edges are defined by NWAF in the geometry input
25-27	KWAFOR	0, 3-30	Number of ordinates used to define the leading and trailing edges of the wing panels. If KWAFOR = 0, the panel edges are defined by NWAFOR in the geometry input

Columns	Variable	Value	Description
28-30	KFUS		The number of fuselage segments. The program sets KFUS = NFUS
31-33	KRADX(1)	0, 3-20	Number of meridian lines used to define panel edges on first body segment. There are three options for defining the panel edges. If KRADX(1) = 0, the meridian lines are defined by NRADX(l) in the geometry input. If KRADX(1) is positive, the meridian lines are calculated at KRADX(1) equally spaced PHIks. If KRADX(1) is negative, the meridian lines are calculated at specified values of PHIk
34-36	KFORX(1)	0, 2-30	Number of axial stations used to define leading and trailing edges of panels on first body segment. If KFORX(1) = 0, the panel edges are defined by NFORX(l) in the geometry input
37-39	KRADX(2)	0, 3-20	Same as KRADX(1), but for second body segment
40-42	KFORX(2)	0, 2-30	Same as KFORX(1), but for second body segment
43-45	KRADX(3)	0, 3-20	Same as KRADX(1), but for third body segment
46-48	KFORX(3)	0, 2-30	Same as KFORX(1), but for third body segment
49-51	KRADX(4)	0, 3-20	Same as KRADX(1), but for fourth body segment
52-54	KFORX(4)	0, 2-30	Same as KFORX(1), but for fourth body segment

The program is restricted to 600 body singularity panels. For this program there is an additional restriction that the total number of singularity panels in the axial direction on the body (fuselage) cannot exceed 30. The arbitrary body (fuselage) capability of this program is limited to those shapes for which the radius is a single-valued function of PHIk for each cross section of the body.

Card 2.2 - Additional revised configuration paneling description control integers. - The contents of card 2.2 are punched as right justified integers as follows:

Columns	Variable	Value	Description
1-3	KF(1)	0, 2-20	Number of fin sections used to define the inboard and outboard panel edges on the first fin. If KF(1) = 0, the root and tip chords define the panel edges
4-6	KFINOR(1)	0, 3-30	Number of ordinates used to define the leading and trailing edges of the fin panels on the first fin. If KFINOR(1) = 0, the panel edges are defined by NFINOR
7-9	KF(2)	0, 2-20	Same as for KF(1), but for second fin
10-12	KFINOR(2)	0, 3-30	Same as for KFINOR(1), but for second fin
13-15	KF(3)	0, 2-20	Same as for KF(1), but for third fin
16-18	KFINOR(3)	0, 3-30	Same as for KFINOR(1), but for third fin
19-21	KF(4)	0, 2-20	Same as for KF(1), but for fourth fin
22-24	KFINOR(4)	0, 3-30	Same as for KFINOR(1), but for fourth fin
25-27	KF(5)	0, 2-20	Same as for KF(1), but for fifth fin
28-30	KFINOR(5)	0, 3-30	Same as for KFINOR(1), but for fifth fin
31-33	KF(6)	0, 2-20	Same as for KF(1), but for sixth fin
34-36	KFINOR(6)	0, 3-30	Same as for KFINOR(1), but for sixth fin

Columns	Variable	Value	Description
37-39	KCAN(1)	0, 2-20	Number of canard sections used to define the inboard and outboard panel edges on the first canard. If KCAN(1) = 0, the root tip chords define the panel edges. If KCAN(N) negative, no vortex sheets carry through the body and concentrated vortices are shed from the inboard edge of the canard or tail surface
40-42	KCANOR(1)	0, 3-30	Number of ordinates used to define the leading and trailing edges of the first canard. If KCANOR(1)=0, the panel edges are defined by NCANOR
43-45	KCAN(2)	0, 2-20	Same as for KCAN(1), but for second canard
46-48	KCANOR(2)	0, 3-30	Same as for KCANOR(1), but for second canard
49-51	KCAN(3)	0, 2-20	Same as for KCAN(1), but for third canard
52-54	KCANOR(3)	0, 3-30	Same as for KCANOR(1), but for third canard
55-57	KCAN(4)	0, 2-20	Same as for KCAN(1), but for fourth canard
58-60	KCANOR(4)	0, 3-30	Same as for KCANOR(1), but for fourth canard
61-63	KCAN(5)	0, 2-20	Same as for KCAN(1), but for fifth canard
64-66	KCANOR(5)	0, 3-30	Same as for KCANOR(1), but for fifth canard
67-69	KCAN(6)	0, 2-20	Same as for KCAN(1), but for sixth canard
70-72	KCANOR(6)	0, 3-30	Same as for KCANOR(1), but for sixth canard

The program is restricted to a total of 600 singularity panels on the wing-fin-canard combination.

For this program there is an additional restriction that the total number of singularity panels in the spanwise direction on the wing-fin-canard combination cannot exceed 20.

Cards 3, 4, . . . - remaining input data cards. - The remaining input data cards contain a detailed description of the singularity paneling of each component of the configuration. Each card contains up to 10 values, each value punched in a 7-column field with a decimal point and may be identified in columns 73-80. The cards are arranged in the following order: reference lengths, wing data cards, fin (vertical tail) data cards, canard (horizontal tail) data cards, fuselage (body) data cards, and finally Mach number and angle of attack case cards. Note that the present program will not handle a pod and therefore there are no pod panel inputs. However, if the geometry input contains a pod description it will be read and ignored.

Reference length card: This card may be identified as REFL in columns 73-80 and contains the following:

Columns	Variable	Description
1-7	REFA	Wing reference area. If REF A = 0, the reference area is defined by the value of REF A in the geometry input
8-14	REFB	Wing semispan. If REF B = 0, a value of 1.0 is used for the reference semispan
15-21	REFC	Wing reference chord. If REF C = 0, a value of 1.0 is used for the reference chord
22-28	REFD	Body (fuselage) reference diameter. If REF D = 0, a value of 1.0 is used for the reference diameter
29-35	REFL	Body (fuselage) reference length. If REF L = 0, a value of 1.0 is used for the reference length
36-42	REFX	X coordinate of moment center
43-49	REFZ	Z coordinate of moment center

Wing data cards: The first wing data card is the wing leading edge radius card and is required only when $K1 = 3$. This card contains NWAF values of leading edge radius expressed in percent chord. It may be identified in columns 73-80 as RHOJ where J denotes the number of the last radius given on that card.

Next is the wing panel leading edge card. This card contains KWAFOR values of wing panel leading edge locations expressed in percent chord. This card may be identified in columns 73-80 as XAFKJ where J denotes the last location in percent chord given on that card. Omit if KWAFOR = 0.

The last wing data card gives the wing panel side edge data. This card contains KWAF values of the y ordinate of the panel inboard edges. This card may be identified in columns 73-80 as YKJ where J denotes the last y ordinate on that card. These values are arranged in the order which begins with the most inboard panel edge and proceeds outboard. Omit if KWAF = 0.

Fin (vertical tail) data cards: The first fin data card is the fin leading edge radius card and is required only when $K4 = 3$. This card contains NF values of leading edge radius expressed in percent chord, one value for each fin. It may be identified in columns 73-80 as RHOFIN.

Next is the fin panel leading edge card for the first fin. This card contains KFINOR(1) values of fin panel leading edge locations expressed in percent chord. This card may be identified in columns 73-80 as XFINKJ where J denotes the fin number. Repeat this card for each fin.

The last fin data card gives the fin panel side edge data for the first fin. This card contains KF(1) values of the z ordinate of the panel inboard edges. This card may be identified in columns 73-80 as ZFINKJ where J denotes the fin number. These values are arranged in the order that begins with the most inboard panel edge and proceeds outboard. Repeat this card for each fin.

Canard (horizontal tail) data cards: The first canard data card is the canard leading edge radius card and is required only when $K5 = 3$. This card contains NCAN values of leading edge radius expressed in percent chord, one value for each canard. It may be identified in columns 73-80 as RHOCAN.

Next is the canard panel leading edge card for the first canard. This card contains KCANOR(1) values of canard panel leading edge locations expressed in percent chord. This card may be identified in columns 73-80 as XCANKJ where J denotes the canard number. Repeat this card for each canard.

The last canard data card gives the canard panel side edge data for the first canard. This card contains KCAN(1) values of the y ordinate of the panel inboard edges. This card may be identified in columns 73-80 as YCANKJ where J denotes the canard number. These values are arranged in the order that begins with the most inboard panel edge and proceeds outboard. Repeat this card for each canard.

Fuselage (body) data cards: The first body card is the body meridian angle card. This card contains KRADX(1) values of body meridian angle expressed in degrees and may be identified in columns 73-80 as PHIJK where J denotes the body segment number. The convention is observed that PHIJK = 0. at the bottom of the body and PHIJK = 180. at the top of the body. Omit unless KRADX(1) is negative. Repeat this card for each fuselage segment.

The second body card is the body axial station card. This card contains KFORX(1) values of the x ordinate of the body axial stations and may be identified in columns 73-80 as XFUSKJ where J denotes the body segment number. Omit if KFORX(1) = 0. Repeat this card for each fuselage segment.

Mach number and angle of attack card: This card may be identified in columns 73-80 as MALPHA and contains the following:

Columns	Variable	Description
1-7	MACH	The subsonic Mach number (including the value MACH = 0.) or the supersonic Mach number at which it is desired to calculate the aerodynamic data
8-14	ALPHA	The angle of attack expressed in degrees at which it is desired to calculate the aerodynamic data

A series of Mach number and angle of attack combinations for the same geometry may be calculated by repeating this card with the desired values.

A value of MACH = -1. on this card signifies the termination of the present case. Geometry cards for a new case can follow such a terminal card.

PROGRAM OUTPUT DATA

All output is processed by a standard 132 characters-per-line printer. The output from each run is always preceded by a complete list of the input data cards. The amount and type of the remaining output depend on the PRINT option selected, the number of panels used, and whether the configuration being analyzed is an isolated wing, an isolated body, or a complete wing-body-tail combination. The program output options are described below:

- PRINT = 0 The program prints the case description, Mach number and angle of attack, followed by a table listing the panel number, control point coordinates (both dimensional and non-dimensional), pressure coefficient, normal force, axial force, and pitching moment. Separate tables are printed for the body and wing panels, noting that any tail, fin or canard panels are included with the wing output. If the planar boundary condition option has been selected, the results for the wing upper surface are given in one table, followed by a separate table giving the results for the wing lower surface. Additional tables giving the total coefficients on the body, the wing and the complete configuration follow the pressure coefficient tables. These include the reference area, reference span and reference chord, the normal force, axial force, pitching moment, lift, and drag coefficients, and the center of pressure of the component.
- PRINT = 1 In addition to the output described for PRINT = 0, the program prints out additional tables giving the normal force, axial force, pitching moment, lift and drag coefficients, and the center of pressure of each column of panels on the wing and tail surfaces. In addition, the indices of the first and last panel in the column are listed, together with the span, chord and origin of the column.
- PRINT = 2 In addition to the output described for PRINT = 1, the program prints out tables listing the panel number, the source or vortex strength of that panel, and the axial velocity u , lateral velocity v , and vertical velocity w at the panel control point. The normal velocity is also calculated for

body panels. Separate tables are printed for the body and wing panels, noting again that any tail, fin, or canard panels are included with the wing output. If the planar boundary condition option has been selected, separate tables are given for the wing upper and lower surfaces.

PRINT = 3 In addition to the output described for PRINT = 2, the program prints out the iteration number, and the source and vortex strength arrays obtained at each step of the iterative solution procedure.

PRINT = 4 In addition to the output described for PRINT = 3, the program prints out tables of the axial and normal velocity components which make up the elements of the aerodynamic matrices. The program prints out the matrix row number, and gives the number of elements in that row. A maximum of four matrix partitions will be printed if this option is selected, each of which is identified by number and its influence description prior to printing the velocity component tables.

If a negative value of PRINT is selected, the program prints all the information described above for the positive values, together with the complete panel geometry description of the configuration following the list of input cards. This consists of tables giving the wing panel corner points, control points, inclination angles, areas, and chords. If the configuration has a horizontal tail, fin or canard, additional tables are printed giving the same information as listed above for the wing. Finally, if the configuration includes a body, the body panel corner points, control points, areas, and inclination angles are listed.

The program output is illustrated by the sample case presented in Appendix III.

PROGRAM STRUCTURE

The program is designed to operate in OVERLAY mode. The main overlay program is designated USSAERO, and calls the three primary overlay programs GEOM, VELCMP, and SOLVE. In turn, GEOM calls seven secondary overlay programs CONFIG, NEWORD, WNGPAN, NEWRAD, BODPAN, NUTORD, and TALPAN; while VELCMP calls three secondary overlay programs BODVEL, LINVEL, and WNGVEL. The overlay structure is illustrated on Figure 1.

The complete program consists of 14 overlay programs and 19 subroutines. Detailed descriptions of each program and subroutine are given in Appendix I. These descriptions give the purpose of the program or subroutine, outline the method used, and list the names of the principal variables and constants.

AUXILIARY FILES

The program designates TAPE 5 as the input file and TAPE 6 as the output file. In addition, five auxiliary files are utilized for temporary storage and data transfer within the program. These files are designated TAPE 7, TAPE 8, TAPE 9, TAPE 10, and TAPE 11.

TAPE 7 is used primarily for the storage of the panel geometry data. The first three records are written by program WNGPAN, and contain the wing panel geometry data. If the configuration has a fin, canard, or horizontal tail, the first three records are rewritten by program TALPAN, and subsequently contain all wing and tail panel geometry data. The fourth record is written by program BODPAN, and contains the body panel geometry data. Additional records are written on this file in program VELCMP if the aerodynamic matrix partitions are further subdivided into blocks. The elements of the diagonal block matrices are stored in individual records on this file, behind the panel geometry data.

TAPE 8 is used exclusively to store the u, v, w velocity component arrays, and each record in this file contains one row of the velocity component arrays from a given matrix partition. In the first partition, NBODY records are written on this file by program BODVEL. In the second partition, another NBODY records are written by either program LINVEL or WNGVEL. However,

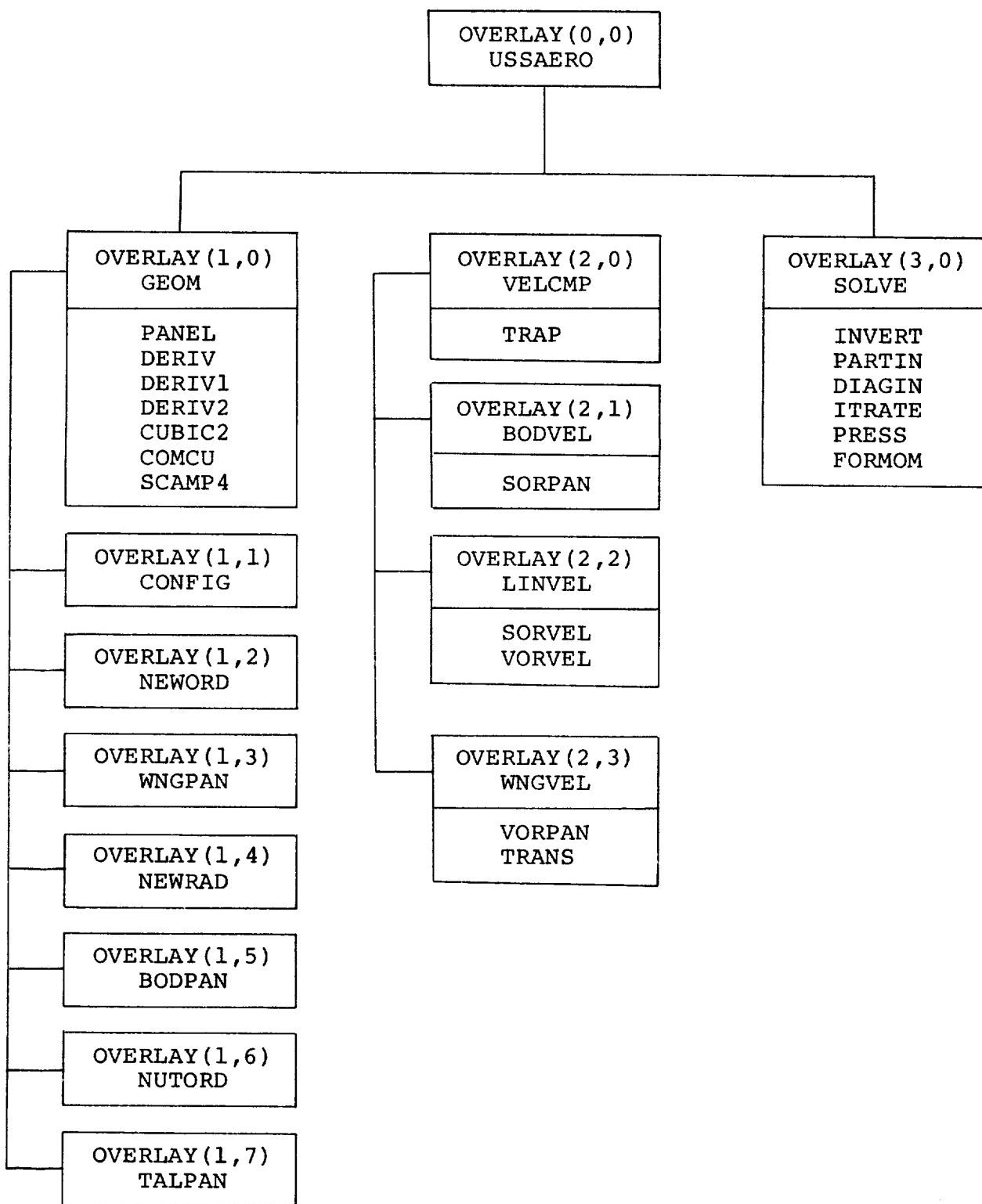


Figure 1 - Program Overlay Structure

if the planar boundary condition option with thickness is selected, program LINVEL writes an additional NBODY records on the file. In the third partition, NWING records are written by program BODVEL, and in the fourth partition, another NWING records are written by programs LINVEL or WNGVEL. As before, LINVEL writes an additional NWING records on this file if the planar boundary condition option with thickness is selected. Thus, a total of $2(NBODY + NWING)$ records are always written on TAPE 8, and a maximum of $3(NBODY + NWING)$ records if the planar boundary condition option with wing thickness is selected.

TAPE 9 is first used in program CONFIG to store the configuration geometry data. Five records are written on this file, containing the reference area, wing geometry data, body geometry data, fin geometry data, and canard or horizontal tail geometry data. Dummy records are written for missing components. TAPE 9 is re-initialized in program VELCMP, and used to store the normal velocity arrays. Each record contains one row of normal velocities from a given matrix partition. In the first partition, NBODY records are written on this file by program BODVEL. In the second partition, another NBODY records are written by program LINVEL or WNGVEL. In the third partition, NWING records are written by program BODVEL, and in the fourth partition, an additional NWING records are written by program LINVEL or WNGVEL. Thus, a total of $2(NBODY + NWING)$ records are written on TAPE 9.

TAPE 10 is first used in program NEWRAD as temporary storage for the body panel corner point coordinates. It is re-initialized by program VELCMP, and then used to store the elements of the diagonal block matrices, if the matrix partitions are further subdivided into blocks. Each record contains one row of normal velocities from a given diagonal block matrix partition. The records are written at the same time the normal velocity arrays for the remainder of the row are written on TAPE 9. Thus, a total of $2(NBODY + NWING)$ records are also written on TAPE 10. These records are subsequently read by program VELCMP, transferred to TAPE 7, and the file re-initialized a second time. TAPE 10 is finally used to store the elements of the inverse diagonal block matrices, or the inverse diagonal partition matrices, if the matrix is not subdivided into blocks. In the former case, the elements of each inverse diagonal block matrix are written as a single record on TAPE 10 by subroutine DIAGIN, or in the latter case, the elements of each inverse diagonal partition matrix are written on the file by subroutine PARTIN.

TAPE 11 is used to transfer two geometry parameter arrays, written as a single record in program VELCMP, to program SOLVE. No further use is made of this file.

OPERATING INSTRUCTIONS

The program deck and data deck are loaded in the following sequence: job card, system control cards, end-of-record card, program deck, end-of-record card, data deck, end-of-file card. The data deck is described above in the Program Input Data section.

APPENDIX I

PROGRAM AND SUBROUTINE DESCRIPTIONS

(Arranged in Alphabetical Order)

This appendix contains a brief outline of the purpose, method, and use of each program or subroutine. The principal variables and constants in each are listed in the order of their first appearance, and identified as input or output data.

PROGRAM BODPAN

PURPOSE: To revise the axial spacing on the body and compute the body panel geometry.

METHOD: For each body segment, the x, y, and z coordinates of the cross sections are read from TAPE 10. If the value of KFORX of the segment is positive, an array of new axial stations for the segment is read in; otherwise the original axial stations are retained.

The body panel geometry is established by a linear interpolation along body meridian lines of the y and z coordinates at the new axial stations. The interpolation is started with the first ring of panels at the nose and continued until the last ring of panels on the last segment is reached. The corner point coordinates, the control point coordinates, the inclination angles, and area are calculated for each panel in sequence.

The panel control point coordinates, the panel dihedral angle θ , the panel inclination angle δ , the corner point coordinates and the panel areas are stored in the COMMON block POINT, and the entire sequence of arrays written as a single record on TAPE 7 following the wing and tail panel geometry arrays. The remaining body geometry parameters are stored in COMMON blocks PARAM and BTHET. Finally, if the print option is negative, the corner point coordinates, control point coordinates, inclination angles, and areas are written on the output file.

USE: CALL OVERLAY (LWB, 1, 5)

Input:

PRINT Print option

NFUS Number of body segments

KFORX, Number of axial stations on segment
NFORX,
JMAX

KRADX, Number of meridian lines on segment
NRADX,
KRAD

XB, Array of original axial stations on
XFUS segment

XJ Array of revised axial stations on
segment

YB, Arrays of y and z coordinates on
ZB segment

Output:

NBODY Total number of body panels

NFU Body segment number

NP Panel number

IP, Panel identification constants
IQ

XC, Arrays of panel corner points
YC,
ZC

XPT, Arrays of panel control points
YPT,
ZPT

THET, Array of panel dihedral angles
THETA

DELTA Array of panel inclination angles

AP, Array of panel areas
AREA

SUBROUTINES
CALLED: PANEL

ERROR
RETURNS: The program calls EXIT if NBODY > 600.

PROGRAM BODVEL

PURPOSE: To compute the three components of velocity induced at specified control points by the body panels.

METHOD: The x, y, and z coordinates of the control point, and the corresponding panel inclination angles θ and δ are read from COMMON block POINT.

Starting with the first body segment, the body panel corner point coordinates and inclination angles are also read from COMMON block POINT for each row and column of panels. Considering a single body panel, the corner point and control point coordinates are transformed to a new coordinate system with origin at the first corner of the panel and inclined at an angle θ with respect to the horizontal. The velocity components induced by this inclined constant source panel at the given control point are computed in the panel coordinate system by subroutine SORPAN, which is called twice to obtain the influence of panels located on both right and left sides of the body. These velocity components are combined and transformed back to the reference coordinate system to obtain the final u, v, and w components of velocity, and the velocity normal to the panel at the control point. This process is repeated for each panel on the body, following which the u, v, and w velocity component arrays are written on TAPE 8, and the array of normal velocities on TAPE 9.

If the control point is in the same ring of panels on the body as the influencing panel and the body has more than 60 panels, the normal velocity at the control point is written on TAPE 10, and its value set to zero in the array written on TAPE 9. This procedure sets up the diagonal blocks of the aerodynamic matrix for later use in the iterative solution procedure. If the print option is selected, the axial and normal velocity arrays are written on the output tape.

The process is repeated for each control point.

USE: CALL OVERLAY (LWB, 2, 1)

Input:

EM,	Mach number
MACH	
NBODY	Number of body panels
LBC	Planar boundary condition option parameter (logical)
PRINT	Print option parameter
NPART	Matrix partition number
NMAX	Maximum order of diagonal block matrices
KFUS	Number of body segments
KRADX	Number of body panel meridian lines in segment
KFORX	Number of body axial stations in segment
JMAX,	Total number of axial stations on body
MAX	
NPOINT	Number of control points
IT	Array of wing supersonic trailing edge indicators
THET	Array of panel inclination angles at control point
THETA	Array of body panel inclination angles
DELTA	Array of body panel incidence angles
DELTI	Array of wing panel incidence angles
XPT, YPT, ZPT	Arrays of wing control point coordinates
XBT, YBT, ZBT	Arrays of body panel control point coordinates

XC, Arrays of body panel corner points
YC,
ZC

Output:

I Control point index
J Body panel index
ISKIP Wing supersonic trailing edge indicator
KF Body segment index
L, Column index
NC
N Row index
NROW, Number of rows of panels on body
NS
NCOL Number of columns of panels on body
J1, Body panel numbers in diagonal block matrices
J2,
JS1,
JS2
K Panel corner index
SINTI $\sin \theta(I)$
COSTI $\cos \theta(I)$
XPTI, Coordinates of control point I
YPTI,
ZPTI
DI $\tan \delta(I)$
DA $\tan \delta(J)$
SINT $\sin \theta(J)$
COST $\cos \theta(J)$
SINTR $\sin(\theta(J) - \theta(I))$

SINTL	$\sin(\theta(J) + \theta(I))$
COSTR	$\cos(\theta(J) - \theta(I))$
COSTL	$\cos(\theta(J) + \theta(I))$
XCOR, YCOR, ZCOR	Coordinates of panel corner points in panel coordinate system
CX	Panel chord length
XI, YI, ZI	Coordinates of control point I in panel coordinate system
XJ, YJ, ZJ	Coordinates of body panel J control point in panel coordinate system
UR, VR, WR	Velocity components at control point I induced by body panel J on right side of body, in body panel coordinate system
UL, VL, WL	Velocity components at control point I induced by body panel J on left side of body, in body panel coordinate system
UB, VB, WB	Arrays of velocity components at control point I in reference coordinate system
VI, WI	Arrays of velocity components at control point I in control point panel co- ordinate system
AN	Array of velocities normal to control point panel I
DN	Array of normal velocities in diagonal block matrices

SUBROUTINES
CALLED: SORPAN

ERROR
RETURNS: None

SUBROUTINE COMCU

PURPOSE: To fit a composite cubic through n points (x_i, y_i) i.e., a separate cubic between each pair of adjacent points, such that the $n-1$ cubics are so determined that each matches its neighbors in function value and in the first two derivatives.

METHOD: Rather than solve simultaneously for the $4(n-1)$ cubic coefficients, the approach here is to solve simultaneously for the slopes of the composite cubic at the given n points. Thus a linear system of order n , rather than $4n-4$ is involved. It can be shown that a necessary and sufficient condition for continuity of the second derivative is that

$$(x_{i+1} - x_i) y'_{i-1} + 2(x_{i+1} - x_{i-1}) y'_i + (x_i - x_{i-1}) y'_{i+1} \\ = \frac{3}{(x_i - x_{i-1})(x_{i+1} - x_i)} \left[(x_i - x_{i-1})^2 (y_{i+1} - y_i) + (x_{i+1} - x_i)^2 (y_i - y_{i-1}) \right]$$

for $i = 2, 3, \dots, n-1$

This yields $n-2$ equations in the n unknowns, y'_i , $i = 1, 2, \dots, n$. For the 1st and n th equations of the linear system, the boundary conditions on y'_1 and y'_n are used. This has been generalized to permit any combination of a given y' or y'' at the end points, e.g., y'_1 and y''_n can be given as the boundary conditions. The second derivative of a cubic through two points can be expressed as a function of the first derivatives and of the given point coordinates as follows:

$$\frac{x_2 - x_1}{2} y''_1 = 3 \frac{y_2 - y_1}{x_2 - x_1} - 2y'_1 - y'_2$$

and

$$\frac{x_n - x_{n-1}}{2} y''_n = -3 \frac{y_n - y_{n-1}}{x_n - x_{n-1}} + y'_{n-1} + 2y'_n$$

Whether the boundary conditions involve first or second derivatives (or both) and no matter what the spacing of the x_i so long as the x_i form a strictly monotone sequence, the coefficient matrix of the linear system is tridiagonal (all elements are zero except on the principal diagonal, the first subdiagonal, and the first superdiagonal). When n is large, a considerable time saving and an enormous storage saving can result if the special structure of this matrix is taken advantage of. Hence, this subroutine stores the matrix elements in $4n$ locations (as opposed to n^2) and then solves the system.

The actual coefficients of the $n-1$ cubics of the composite cubic are not found by COMCU. Since on any subinterval x_i, x_{i+1} , a cubic is uniquely determined by the known two points and two slopes, the calling program can find the four coefficients of each cubic independently and may often need to do so for only one of the $n-1$ cubics. In any case, the subroutine CUBIC2 specifically finds a cubic, given two points and the slope at each point.

USE:

```
CALL COMCU (DA, DB, S, X, Y, L, M, N, NDA,NDB)
```

Input:

X	Array of x-abscissae of input points
Y	Array of y-ordinates of input points
N	Number of input points
NDA	Order (1 or 2) of derivative at X(1)
NDB	Order (1 or 2) of derivative at X(N)
DA	Value of derivative at X(1)
DB	Value of derivative at X(N)
L	Code = 1, if single precision is to be used = 2, if double precision is to be used

Output:

S Array of first derivatives

M Error return

= 0 - success

≠ 0 - error detected

SUBROUTINES

CALLED: None

ERROR

RETURNS: If overflow occurred, M = 1. Otherwise, M = 0.

RESTRICTIONS: The x-abscissae must form a strictly monotone sequence. N ≤ 400.

PROGRAM CONFIG

PURPOSE: To input the geometrical description of the configuration using the same input data as program START of reference 1.

METHOD: The configuration reference area is read from the input file if $J_0 \neq 0$, otherwise the reference area is set equal to unity. The reference area is then written on TAPE 9. If $J_1 \neq 0$, the wing geometry data is read from the input file in the order specified in reference 1. The program computes the upper and lower surface coordinates of the wing airfoils, and writes the entire wing geometry array as one record on TAPE 9.

If $J_2 \neq 0$, the body geometry data is also read from the input file in the order specified in reference 1 for each body segment. For arbitrary cross-sections, the y and z ordinates of the body segment are read in, but for circular cross-sections, the body cross-sectional area is read in and the corresponding radius calculated by the program. The entire body geometry array is then written as one record on TAPE 9.

If $J_3 \neq 0$, the pod geometry is read in, but no further use is made of this data.

If $J_4 \neq 0$, the fin geometry data is read in. The program computes the coordinates of the fin airfoils and writes the fin geometry array as one record on TAPE 9. Similarly, if $J_5 \neq 0$, the tail or canard geometry data is read in, the tail airfoil coordinates calculated, and the tail geometry array written on TAPE 9.

If one or more of the above components is missing, the program writes a dummy record on TAPE 9 and continues.

USE: CALL OVERLAY (LWB, 1, 1)

Input:

J_0 Reference area parameter

J_1 Wing definition parameter

J2	Body definition parameter
J3	Pod definition parameter
J4	Fin definition parameter
J5	Canard or tail definition parameter
J6	Body camber parameter
REFA	Reference area
ABCD	Dummy array
NWAF	Number of wing airfoil sections
NWAFOR	Number of ordinates used to define each wing airfoil section
WAFORG	Origin and chord length of each wing airfoil (x, y, z, c)
XAF	Array of percent chords for wing airfoil ordinates
WAFORD	Array of half-thickness ordinates in percent chord
TZORD	Array of mean camber line ordinates
NFUS	Number of body segments
NRADX , NRAD	Number of points used to define half-section of body segment
NFORX , NFUSOR	Number of axial stations on body segment
XFUS	Array of axial stations on body segment
ZFUS	Array of body camber ordinates
SFUS	Array of y and z ordinates used to define half-section of arbitrary body segment
FUSARD	Array of body cross-sectional areas
NP	Number of pods
NPODOR	Number of axial stations on pod

NF	Number of fins
NFINOR	Number of ordinates used to define fin airfoil sections
FINORG	Origin and chord lengths of fin airfoils (x, y, z, c)
XFIN	Array of percent chords for fin airfoils
FINORD	Array of fin airfoil half-thickness ordinates in percent chord
NCAN	Number of tails or canards
NCANOR	Number of ordinates used to define tail or canard airfoil sections
CANORG	Origin and chord lengths of tail or canard airfoils (x, y, z, c)
XCAN	Array of percent chords for tail or canard airfoils
CANORD	Array of airfoil half-thickness ordinates
<u>Output:</u>	
REFA	Reference area
WAFOR	Array of wing half-thickness ordinates (percent chord)
TZORD	Array of wing camber line ordinates
WAFORD	Array of x, y, z, coordinates defining upper and lower surfaces of wing (not used)
J2TEST	Parameter to specify body camber and cross-section definition
FUSRAD	Array of body radii (circular cross-sections only)
FINOR	Array of fin half-thickness ordinates (percent chord)

FINCR Array of fin camber line ordinates (set zero)
FINORD, FINX2,
FINX3 Arrays of x, y, z coordinates defining left and right surfaces of fin (not used)
CANOR Array of tail or canard half-thickness ordinates
CANCR Array of tail or canard camber line ordinates
CANORX,
CANORD,
CANOR1 Arrays of x, y, z coordinates defining upper and lower surfaces of tail or canard (not used)
BLOCK Dummy array used for storing geometry data on TAPE 9

SUBROUTINES

CALLED: None

ERROR

RETURNS: None

SUBROUTINE CUBIC2

PURPOSE: To fit a cubic to two points, being given the slope at each.

METHOD: The subroutine sets up the system of four simultaneous equations expressing the four given conditions and solves it for the coefficients of the cubic.

USE: CALL CUBIC2 (X, Y, D, C, M)

Input:

X Array of x-coordinates

Y Array of y-coordinates

D Array of first derivatives

Output:

C Array of cubic coefficients

M {
 | Error return
 |= 1 - success
 | ≠ 1 - error detected

SUBROUTINES

CALLED: None

ERROR

RETURNS: If M = 2, overflow occurred. If M = 3,
X(1) = X(2). Otherwise, call is successful,
and M = 1

RESTRICTIONS X(1) ≠ X(2)

SUBROUTINE DERIV

PURPOSE: To fit a chain of cubic curves through a set of N points (x_i, y_i) having continuous first and second derivatives at the intermediate points and specified first or second derivative at the end points.

METHOD: The method outlined in subroutine SCAMP4 is applied.

USE: CALL DERIV (X, Y, N, NDA, DA, FD)

Input:

X Array of x values

Y Array of y values

N Number of points

NDA The order of the derivative to be specified at the first point

DA The value of the derivative to be specified at the first point

Output:

FD Array of first derivatives at the points

SUBROUTINES

CALLED: SCAMP4

ERROR

RETURNS: None

FUNCTION DERIV1

PURPOSE: To find the first derivative of the quadratic through three given points at a specified one of these points. This provides a good approximation to the slope of a function at a point, particularly if the other two points used are nearby.

METHOD: The subroutine simply finds the unique polynomial of degree two through the given points then evaluates its first derivative at the specified point.

USE: $D = \text{DERIV1} (X, Y, N)$

Input:

X Array of x-coordinates
Y Array of y-coordinates
N {
 | Code
 | = 1, 2, or 3 indicating point at which
 } derivative is desired

SUBROUTINES
CALLED: None

ERROR
RETURNS: None

RESTRICTIONS The x-coordinates must be distinct, but need not be in any order or evenly spaced

FUNCTION DERIV2

PURPOSE: To find the second derivative of the cubic through four given points (x_i, y_i) at an arbitrary point whose x coordinates if given.

METHOD: The subprogram simply finds the unique polynomial of degree three through the given points, then evaluates its second derivative at the desired x , which need not be one of the four given x_i .

USE: $D = \text{DERIV2 } (X, Y, XX)$

Input:

X Array of x coordinates

Y Array of y coordinates

XX x coordinate of point at which second derivative is desired

SUBROUTINES

CALLED: None

ERROR

RETURNS: None

RESTRICTIONS: The x coordinates must be distinct but can be in any order and unevenly spaced.

SUBROUTINE DIAGIN

PURPOSE: To invert the diagonal blocks of the matrix and store the results on TAPE 10.

METHOD: If the order of the body matrix partition exceeds 60, the diagonal blocks of the body matrix are read from TAPE 7, the block matrices inverted, and the inverse matrices stored on TAPE 10. Otherwise, the complete body matrix partition is read from TAPE 9, the matrix inverted, and the inverse stored on TAPE 10.

A similar procedure is followed for the wing matrix partition.

USE: CALL DIAGIN

Input:

NWING Number of wing panels
NBODY Number of body panels
NMAX Maximum order of diagonal block matrices (60)
NDIM Matrix dimension statement size
NBBLOK Number of diagonal blocks in body matrix partition
NWBLOK Number of diagonal blocks in wing matrix partition
NBROW Order of diagonal blocks in body matrix partition
NWROW Order of diagonal blocks in wing matrix partition
D Array of matrix elements

Output:

NB Body diagonal block number

NW Wing diagonal block number
NROW Number of rows in diagonal block
NCOL Number of columns in diagonal block
D Array of inverse matrix elements

**SUBROUTINES
CALLED:** None

**ERROR
RETURNS:** None

SUBROUTINE FORMOM

PURPOSE: To calculate the force and moment coefficients on body, wing and tail components.

METHOD: Depending on the component being analyzed and the boundary condition option selected, execution of this subroutine follows one of three paths. In all three paths, the panel inclination angles, control point coordinates, areas and chords are obtained from COMMON block POINT. The pressure coefficients are obtained from COMMON block SCRAT.

If the component is a body, the normal force, axial force, and moment about the origin of coordinates is computed for each panel and the results summed. The total axial force, normal force and pitching moment of the body are stored in COMMON block FORM. The body panel force and moment arrays are written on the output file, together with the panel number, control point coordinates, and pressure coefficient. The control point coordinates are non-dimensionalized by dividing by the body reference length or diameter, and both dimensional and non-dimensional coordinates are presented in this array. Finally, the normal and axial force coefficients, the pitching moment coefficient about the origin of coordinates, the lift and drag coefficients, and the center of pressure of the body expressed as a fraction of the reference chord are computed and written on the output file.

If the component is a wing or tail, and the non-planar boundary condition option has been selected, the subroutine first calculates the chord length of each column of panels, and assigns the chord length and the axial coordinate of the leading edge to each panel in the column. The normal force, axial force and moment about the origin of coordinates is computed for each panel, and the results summed. The wing panel force and moment arrays are then written on the output file, together with the panel number, control point coordinates, and pressure coefficient. The control point coordinates are non-dimensionalized

by dividing them by the chord length or reference semi-span, and both dimensional and non-dimensional coordinates are presented in the array. Next, the normal and axial force coefficients, the pitching moment coefficient about the origin of coordinates, the lift and drag coefficients and the center of pressure of the wing, expressed as a fraction of the reference chord, are computed and written on the output file. If a non-zero print option has been selected, the subroutine proceeds to calculate the spanwise load distribution on the wing and tail. The forces and moment acting on each panel in a given column are summed, and the force and moment coefficients and center of pressure of the column computed and written on the output file. The summation includes panels on both the upper and lower surfaces of the column.

If the component is a wing or tail and the planar boundary condition option has been selected, the subroutine is called twice. On the first pass, the forces and moment acting on the upper surface is calculated, followed by the forces and moment on the lower surface in the second pass. In this case, the subroutine performs an interpolation to determine the wing or tail panel slope, pressure coefficient, and control point at the panel centroid prior to the panel force and moment calculations. The remainder of the calculation procedure is similar to that described above for the wing with non-planar boundary condition option. The axial force, normal force, and pitching moment of the wing upper surface are stored in COMMON block FORM on the first pass, and added to those calculated on the lower surface in the second pass to obtain the total forces and moments acting on the wing. This information is then used to calculate the total force and moment coefficients, lift, drag, and center of pressure of the wing and tail, and the results stored on the output file. The spanwise load distribution on the wing and tail is also calculated if the print option is other than zero, using the procedure described above.

USE: CALL FORMOM (NPAN, NPASS, ALFA, COMPT)

Input:

NPAN	Number of panels on the component being analyzed
NPASS	Pass number
COMPT	Component identification integer { COMPT = 1 Body component COMPT = 2 Wing or tail component
ALFA	Angle of attack (radians)
ALPHA	Angle of attack (degrees)
PRINT	Print option (integer)
LBC	Planar boundary condition option parameter (logical)
MACH	Mach number
NBODY	Number of body panels
NWING	Number of wing and tail panels
ARRAY	Array of panel geometrical parameters
CHORD	Array of wing panel chord lengths
DZTDX	Array of wing panel half-thickness slopes
XC	Array of panel corner point coordinates
TITLE1, Case identification arrays	
TITLE2	
DELTA	Array of panel incidence angles, or panel camber slopes on wing with planar boundary condition option
THET	Array of panel inclination angles
NSEG	Number of wing and tail segments

NCOL	Number of columns of panels in segment
NROW	Number of rows of panels in segment
SINS, COSS	Array of sines and cosines of segment inclination angle
XCPT	Array of chord fractions for control point location
LOCPT	Array of control point location indicators
CP	Array of panel pressure coefficients
XPT, YPT, ZPT	Arrays of control point coordinates
XLEW	Array of wing column leading edge origins
SPNW	Array of wing column spanwise widths
AREA	Array of panel areas
REFA	Reference wing area
REFB	Reference wing span
REFC	Reference wing chord
REFD	Reference body diameter
REFL	Reference body length
REFX, REFZ	Coordinates of moment reference point

Output:

XON	x coordinate of body nose
SGN	Wing upper and lower surface sign parameter array
SIND, COSD	Trigonometric function arrays of panel incidence angle δ
SINT, COST	Trigonometric function arrays of panel inclination angle θ

SIAL,	Trigonometric functions of angle of attack α
COAL	
NC	Number of columns of panels in segment
NR	Number of rows of panels in segment
NRL	NR + 1
TAND	Slope of wing upper or lower surface at centroid, planar boundary condition option
XS, PT	Control point location in chord fractions
RL	Chord fraction of control point from leading edge
RT	Chord fraction of control point from trailing edge
CHD	Array of wing column chord lengths
XLE	Array of wing column leading edge origins
NP	Number of panels on component
IP	Panel number
CN	Normal force coefficient
CT	Axial force coefficient
CM	Pitching moment coefficient
XP, YP, ZP	Panel control point coordinates
F1, F2, F3	Direction cosines of panel normal vector
FAK	Panel area factor
DCN	Panel normal force

DCT	Panel axial force
DCM	Panel pitching moment
XQ, YQ, ZQ	Non-dimensional panel control point coordinates
CL	Lift coefficient
CD	Drag coefficient
DXN	Distance of center of pressure from origin, in reference chord lengths
I1	Number of first panel in wing column
I2	Number of last panel in wing column
IZ	Index counter
DELY	Wing column spanwise width
XL	Wing column leading edge origin
CNS	Normal force on wing upper surface
CTS	Axial force on wing upper surface
CMS	Pitching moment on wing upper surface
SUBROUTINES CALLED:	None
ERROR RETURNS :	None

PROGRAM GEOM

PURPOSE: To input configuration geometry and specify panel subdivision of the components. A complete description of the input geometry cards is given in the program listing.

METHOD: The case identification and initial configuration parameters are read from the input file. The secondary overlay program CONFIG is then called to complete the input of the configuration description. The auxiliary case identification is then read, followed by the boundary condition and print option. Finally, the revised configuration parameters used for specifying the panel subdivisions are read. Depending on the values of the revised configuration parameters, the program calls the secondary overlay programs NEWORD, WNGPAN, NEWRAD, BODPAN, NUTORD or TALPAN, which interpolate the input geometry and calculate the corner points, control points and inclination angles of the panels on the wing, body, or tail.

USE: CALL OVERLAY (LWB, 1, 0)

Input:

TITLE1	Case description.
TITLE2	Auxiliary case description.
J0, K0	Reference area and length parameters.
J1, K1	Wing definition parameters.
J2, K2	Body definition parameters.
J3, K3	Pod definition parameters.
J4, K4	Fin definition parameters.
J5, K5	Canard or tail definition parameters.
J6, K6	Body camber parameters.
NWAF	Number of wing airfoil sections.
NWAFOR	Number of ordinates used to define each wing airfoil section.

NFUS, KFUS	Number of body segments
NRADX	Number of points used to define half-section of body segment
NFORX	Number of axial stations on body segment
NP	Number of pods
NPODOR	Number of axial stations on pod
NF	Number of fins
NFINOR	Number of ordinates used to define each fin airfoil section
NCAN	Number of tails (canards)
NCANOR	Number of ordinates used to define each tail airfoil section
KWAF	Number of streamwise panel edges on wing
KWAFOR	Number of ordinates used to define the leading and trailing edges of the wing panels
KRADX	Number of meridian lines used to define panel edges on body segment
KFORX	Number of axial stations used to define leading and trailing edges of panels on body segment
KF	Number of sections used to define the streamwise panel edges on fin
KFINOR	Number of ordinates used to define the leading and trailing edges of the panels on fin
KAN	Number of ordinates used to define the leading and trailing edges of the panels on tail or canard
REFA, REFAR	Wing reference area
REFB	Wing reference span
REFC	Wing reference chord

REFD	Body reference diameter
REFL	Body reference length
REFX, REFZ	Coordinates of moment reference point
LINBC	Boundary condition selection parameter (integer)
THICK	Wing thickness selection parameter (integer)
PRINT	Output print selection parameter (integer)

Output:

NBODY	Number of body panels
NWING	Number of wing and tail panels
NTAIL	Number of tail panels (not used)
NCPT	Number of control points on wing and tail
LBC	Boundary condition parameter (logical)
THK	Wing thickness parameter (logical)
TAIL	Tail parameter (logical)
KOL	Number of columns of panels on wing and tail
NSEG	Number of wing and tail segments
BLOCK	Dummy array used for storing geometry data on TAPE 9

**PROGRAMS
CALLED:**

OVERLAY (LWB, 1, 1)	(CONFIG)
OVERLAY (LWB, 1, 2)	(NEWORD)
OVERLAY (LWB, 1, 3)	(WNGPAN)
OVERLAY (LWB, 1, 4)	(NEWRAD)
OVERLAY (LWB, 1, 5)	(BODPAN)
OVERLAY (LWB, 1, 6)	(NUTORD)
OVERLAY (LWB, 1, 7)	(TALPAN)

ERROR

RETURNS:

The program is terminated if:

- (a) An end of file is read on TAPE 5
- (B) KOL > 20
- (c) KRADX(1) > 21

SUBROUTINE ITRATE

PURPOSE: To solve the boundary condition equations by an iterative procedure and determine the strengths of the body sources, and wing and tail vortices.

METHOD: The first approximation to the body panel source strengths is obtained by post-multiplying the inverted body diagonal block matrices written on TAPE 10 by the body normal velocity array. The first approximation to the wing and tail panel vortex strengths is obtained in a similar manner. If the absolute value of the print option is greater than two, the approximate source and vortex strengths are written on the output file.

The body normal velocity array is then revised by subtracting an incremental normal velocity array from the original normal velocity array. The incremental values are obtained in two steps. In the first step, the matrix giving the influence of the body sources on the body panel control points is read from TAPE 9 and multiplied by the approximate body source strengths. In the second step, the matrix giving the influence of the wing and tail vortices on the body panel control points is read from TAPE 9 and post-multiplied by the approximate wing and tail vortex strengths. The incremental normal velocity array on the body control points is the sum of these two contributions.

The wing and tail normal velocity array is revised in a similar manner. The revised normal velocity arrays are then used to obtain a second approximation to the source and vortex strengths by repeating the above procedure. This iteration procedure is repeated until the maximum number of iterations has been completed.

If the order of the body partition does not exceed 60, the same procedure is followed except that the first step in the determination of the incremental normal velocities on the body is omitted. If the order of the wing partition does not exceed 60, the same procedure is followed except that the second step in the determination of the incremental normal velocities on the wing is omitted.

USE: CALL ITRATE

Input:

IMAX Maximum number of iterations
NBODY Number of body panels
NWING Number of wing panels
NBBLOK Number of diagonal blocks in body matrix partition
NWBLOK Number of diagonal blocks in wing matrix partition
NBROW Number of rows in diagonal blocks in body matrix partition
NWROW Number of rows in diagonal blocks in wing matrix partition
NB Array of body normal velocities
NW Array of wing normal velocities
D Array of diagonal block matrix elements
A Array of normal velocity matrix elements
PRINT Print option parameter

Output:

RB Array of revised normal velocities on body
RW Array of revised normal velocities on wing
NBLOK Number of diagonal block matrices
NROW Number of rows in diagonal block matrix
NCOL Number of columns in diagonal block matrix
GB Array of body source strengths
GW Array of wing vortex strengths

DNB Incremental normal velocities on body
DNW Incremental normal velocities on wing
TIME Elapsed time

SUBROUTINES
CALLED: SECOND

ERROR
RETURNS: None

SUBROUTINE INVERT

PURPOSE: Matrix inversion subroutine

METHOD: Subroutine INVERT is a simple matrix inversion procedure based on Gauss-Jordan elimination without pivoting.

USE: CALL INVERT (A, IA, NMAX)

Input:

A Name of matrix to be inverted

IA Number of rows and columns in matrix A

NMAX Maximum dimensions specified for A in calling subroutine

Output:

A Inverse of A

SUBROUTINES

CALLED: None

RESTRICTIONS: NMAX not greater than 115

ERROR

RETURNS: Subroutine calls EXIT if matrix is singular

PROGRAM LINVEL

PURPOSE: To calculate the three components of velocity induced at specified control points by source and vortex distributions on panels located in the plane of the wing or tail surfaces.

METHOD: The x, y, and z coordinates of the control point, and the corresponding panel inclination angles θ and δ are read from COMMON block POINT.

Starting with the first wing segment, the panel leading and trailing edge slopes are calculated and stored. The program then computes the velocity components induced by the panel corner points along the inboard edge of the first column of panels. These calculations are performed by subroutines VORVEL and SORVEL, which return the three components of velocity induced by constant and linearly varying vortex and source distributions. These subroutines are called twice to obtain the contributions of both left and right wing panels. In addition, a second call to subroutine VORVEL is required at panel trailing edge corner points if the panel spacing is not uniform.

To compute the velocity components induced by the panel corner points along the outboard edge of this and the remaining columns of panels, the procedure is repeated. However, for the remaining columns of panels, advantage is taken of the fact that the velocity components along the inboard edges of a given column of panels are the same as those computed at the outboard edges of the previous column of panels. Therefore, the inboard velocity components are not recomputed, but stored in temporary arrays prior to the calculation of the outboard velocity component arrays.

Once the velocity components induced by the panel corner points along the outboard edge of a given column of panels are computed, the inboard and outboard influences of each panel in the column are combined to obtain the resultant panel velocity components. First the velocity components

induced by the right and left wing panels are calculated, using appropriate combination rules for the source and vortex panels, and applying special rules for leading and trailing edge panels. Finally the contributions of the left and right wing panels are combined, the velocity components transformed back to the reference coordinate system, and the velocity normal to the panel at the control point computed.

The procedure is repeated for each column of panels in each wing segment, until all wing panels are accounted for. At this point the u, v, and w components of velocity induced by the source panels are written as a single record on TAPE 8, followed by the u, v, and w components of velocity induced by the vortex panels. If the thickness option is not requested, only the vortex panel arrays are written on this tape. The normal velocities are then written as a single record on TAPE 9. If the control point is in the same column of panels on the wing as the influencing panel, and the wing has more than 60 panels, the normal velocity at the control point is written on TAPE 10 and its value set to zero in the array written on TAPE 9. This procedure sets up the diagonal blocks of the aerodynamic matrix for later use in the iterative solution procedure. Finally, if the print option is selected, the axial and normal velocity component arrays induced by the vortex panels and source panels are written on the output tape.

The process is repeated for each control point.

USE:

CALL OVERLAY (LWB, 2, 2)

Input:

Note: The word wing includes any tail, fin, or canard in the following descriptions

MACH Mach number

PRINT Print option parameter

THK Wing thickness option parameter
(logical)

NPART	Matrix partition number
NMAX	Maximum order of diagonal block matrices
NWING	Number of wing panels
NSEG	Number of wing segments
NROW	Number of rows of panels in segment
NCOL	Number of columns of panels in segment
NWT	Tail segment identification parameter
NPOINT	Number of control points
IT	Array of wing supersonic trailing edge indicators
XPT, YPT, ZPT	Arrays of control point coordinates
THET	Array of panel inclination angles at control points
DELTA	Array of panel incidence angles at control points
XC, YC, ZC	Arrays of wing panel corner point coordinates
COSS	$\cos \theta(J)$
SINS	$\sin \theta(J)$
CHORD	Array of wing panel chords

Output:

I, II	Control point index
J, JSAVE	Wing panel index (vortex panels)
K, KSAVE	Wing panel index (source panels)
L	Panel row index

M	Panel column index
N	Wing segment index
NP, NPSAVE	Panel number
NWTHK	Number of wing panel source distributions
BETA	Mach number parameter
SUB	Subsonic flow parameter (logical)
SUPTE	Supersonic trailing edge parameter (logical)
CON, BCON	Constants for vortex panel velocity components
CONT, BCONT	Constants for source panel velocity components
ISKIP	Wing supersonic trailing edge indicator
NR,NS	Number of rows of panels in segment
NC	Number of columns of panels in segment
NT	Tail segment identification parameter
J1,J2, JS1, JS2	Wing panel numbers of diagonal block matrices
SINTI	$\sin \theta(I)$
COSTI	$\cos \theta(I)$
XI,YI, ZI	Coordinates of control point I
DI	$\tan \delta(I)$
BLE,BL	Array of panel leading edge slopes
BTE	Panel trailing edge slope
FLAG	Logical variable denoting presence of additional column of vortex panels extending from the center line to the inboard edge of the wing

BPOS	Panel leading edge slope sign parameter (logical)
COST	$\cos \theta(J)$
SINT	$\sin \theta(J)$
SINTR	$\sin(\theta(J) - \theta(I))$
COSTR	$\cos(\theta(J) - \theta(I))$
SINTL	$\sin(\theta(J) + \theta(I))$
COSTL	$\cos(\theta(J) + \theta(I))$
XC, YC, ZC	Arrays of panel corner point coordinates
DX, DY, DZ	Control point coordinates in panel reference system
AL, AB, AT	Difference between panel leading and trailing edge slopes
CL, CT, CC	Panel chord length along edge
ABA	Absolute value of $(AL - AT)$
ACL	Absolute value of $(CL - CT)$
ML	Panel edge indicator
AMP	Reciprocal of panel chord
X	Dummy variable
UCOR, VCOR, WCOR	Velocity components induced by outboard corners of right wing panels containing constant vortex distributions
ULOR, VLOR, WLOR	Velocity components induced by outboard leading edge corner of right wing panels containing linearly varying vortex distributions

UTOR,	Velocity components induced by outboard trailing edge corner of right wing panels containing linearly varying vortex distributions
VTOR,	
WTOR	
RCOR,	Velocity components induced by outboard corners of right wing panels containing constant source distributions
SCOR,	
TCOR	
RLOR,	Velocity components induced by outboard corners of right wing panels containing linearly varying source distributions
SLOR,	
TLOR	
UCOL,	Same as UCOR, VCOR, WCOR for outboard corners of left wing panels
VCOL,	
WCOL	
ULOL,	Same as ULOR, VLOR, WLOR for outboard corners of left wing panels
VLOL,	
WLOL	
UTOL,	Same as UTOR, VTOR, WTOR for outboard corners of left wing panels
VTOL,	
WTOL	
RCOL,	Same as RCOR, SCOR, TCOR for outboard corners of left wing panels
SCOL,	
TCOL	
RLOL,	Same as RLOR, SLOR, TLOR for outboard corners of left wing panels
SLOL,	
TLOL	
UCIR,	Same as UCOR, VCOR, WCOR for inboard corners of right wing panels
VCIR,	
WCIR	
ULIR,	Same as ULOR, VLOR, WLOR for inboard corners of right wing panels
VLIR,	
WLIR	
UTIR,	Same as UTOR, VTOR, WTOR for inboard corners of right wing panels
VTIR,	
WTIR	
RCIR,	Same as RCOR, SCOR, TCOR for inboard corners of right wing panels
SCIR,	
TCIR	

RLIR,	Same as RLOR, SLOR, TLOR for inboard corners of right wing panels
SLIR,	
TLIR	
UCIL,	Same as UCOR, VCOR, WCOR for inboard corners of left wing panels
VCIL,	
WCIL	
ULIL,	Same as ULOR, VLOR, WLOR for inboard corners of left wing panels
VLIL,	
WLIL	
UTIL,	Same as UTOR, VTOR, WTOR for inboard corners of left wing panels
VTIL,	
WTIL	
RCIL,	Same as RCOR, SCOR, TCOR for inboard corners of left wing panels
SCIL,	
TCIL	
RLIL,	Same as RLOR, SLOR, TLOR for inboard corners of left wing panels
SLIL,	
TLIL	
ULR, RCR, VLR, SCR, WLR, TCR	Velocity components induced by right wing panels containing linearly varying vortex distributions with zero strength along leading edge
ULL, RCL, VLL, SCL, WLL, TCL	Same as above for left wing panels
UCR, VCR, WCR	Velocity components induced by right wing panels containing linearly varying vortex distributions with zero strength along trailing edge
UCL, VCL, WCL	Same as above for left wing panels

RLR,	Velocity components induced by right wing panels containing linearly varying source distributions with zero strength along leading edge
RTR,	
SLR,	
STR,	
TLR,	
TTR	
RLL,	Same as above for left wing panels
RTL,	
SLL,	
STL,	
TLL,	
TTL	
UTR,	Velocity components induced by right wing panels containing linearly varying source distributions with zero strength along trailing edge
VTR,	
WTR	
UTL,	Same as above for left wing panels
VTL,	
WTL	
UC ,	Arrays of velocity components induced
VC ,	by vortex panels at control point I
WC	
USAVE ,	Velocity component storage arrays
VSAVE ,	
WSAVE	
AC	Array of normal velocities induced by vortex panels at control point I
ASAVE	Normal velocity storage array
BC ,	Velocity tangential to control point
BT	panel I
UT ,	Arrays of velocity components induced
VT ,	by source panels at control point I
WT	
AT	Array of normal velocities at control point I induced by source panels
DC	Array of normal velocities induced by vortex panels in diagonal block matrices

SUBROUTINES
CALLED: VORVEL, SORVEL

ERROR
RETURNS: None

PROGRAM NEWORD

PURPOSE: To revise chordwise panel spacing on the wing and to compute new airfoil ordinates by interpolation.

METHOD: The program first checks the input data to determine if the wing has a round leading edge. If so, an array of wing leading edge radii are read in. The program then checks if the percent chord locations of the panel edges are to be redefined. If so, an array of revised chordwise locations are read in, otherwise the panel edges are used as originally defined.

For each wing section, the original camber and thickness distributions are rewritten as one dimensional arrays. A chain of cubic curves having continuous first derivatives is fitted between each pair of points on these two curves, and the four coefficients of the cubic curve calculated within each interval. For wing sections having round leading edges with infinite leading edge slope, the slope at the second percent chord location is calculated by fitting the curve $z = \sqrt{2\rho x} + ax + bx^2$ through the first three points. The program then calculates the coefficients of the cubic curves through the remaining points in the usual way, starting with the slope determined from the first derivative of the above formula.

The revised camber and thickness ordinates and slopes are then calculated at the new chordwise locations by the formulas

$$z = c_1 + c_2x + c_3x^2 + c_4x^3$$

$$\frac{dz}{dx} = c_2 + 2c_3x + 3c_4x^2$$

where the coefficients correspond to the interval of the curve under consideration. For wings having round leading edges, the formula given in the previous paragraph is used in the first interval.

USE: CALL OVERLAY (LWB, 1, 2)

Input:

K1 Wing leading edge definition parameter
NWAF Number of wing airfoil sections
NWAFOR Number of ordinates used to define wing airfoil section
KWAFOR Number of ordinates used to define wing panel leading and trailing edges. If KWAFOR = 0, NWAFOR ordinates are used.
XAF Array of percent chords for airfoil ordinates (NWAFOR values)
XAFK Array of percent chords for panel leading and trailing edges (KWAFOR values)
TZORD Array of camber line ordinates
WAFORD Array of half-thickness ordinates
RHO Array of leading edge radii

Output:

NWAR Number of intervals in curve
ZORD Array of camber line ordinates
TORD Array of half-thickness ordinates
NDA, DA Number and value of derivative at initial point on curve
DZC, DZCDX Array of camber line slopes
DZT, DZTDX Array of half-thickness slopes
A, B Coefficients of leading edge curve
C, CC Coefficients of cubic curves in each interval

TZORK Array of revised camber line ordinates
DZCDXK Array of revised camber slopes ordinates
WAFORK Array of revised half-thickness ordinates
DZTDXK Array of revised half-thickness slopes

SUBROUTINES
CALLED: DERIV

ERROR
RETURNS: None

PROGRAM NEWRAD

PURPOSE: To revise the body meridian line spacing.

METHOD: For each body segment, there are three options for redefining the meridian lines. Considering the first segment, if KRADX(1) = 0, the meridian lines are not changed. If KRADX(1) is positive, the meridian lines are relocated at KRADX(1) equally spaced values of the meridian angle ϕ . If KRADX(1) is negative, an array of arbitrary meridian angles is read in.

If the body has a circular cross section, the y and z coordinates are calculated at each axial station as follows:

$$y = r \cos\phi$$

$$z = z_C + r \sin\phi$$

where the body radius r and camber z_C have been previously calculated in program CONFIG.

If the body has an arbitrary cross section, the y and z coordinates are obtained by linear interpolation at the new values of ϕ of the original y and z coordinates read in program CONFIG.

The x, y, and z coordinates are written on TAPE 10, and the procedure repeated for the remaining body segments.

USE: CALL OVERLAY (LWB, 1, 4)

Input:

J2TEST Parameter to specify body cross section and camber definition

NFUS Number of body segments

NRADX, Number of meridian lines on segment
KRADX

PHIK Array of meridian angles on segment

NFORX, Number of axial stations on segment
NFUSOR

XFUS Array of axial stations on segment

FUSRAD Array of body radii on segment

ZFUS Array of body camber ordinates on segment

SFUS Array of y and z coordinates used in arbitrary cross section definition

Output:

KFUS Number of body segments

NF, Body segment number
NFU

NRAD, Number of meridian lines in segment
KRAD

KTEST Arbitrary body indicator

NEWPHI Logical variable controlling input of new meridian angles

PHIR Meridian angle (radians)

DELE Incremental meridian angle

XB Array of axial stations on segment

YB, Arrays of y and z coordinates on
ZB segment

YF, Temporary arrays of y and z coordinates
ZF

RAD Body radius

CAM, Body camber ordinate
ZC

PHIN Array of original meridian angles for arbitrary cross section body

MAX Maximum number of body axial stations

SUBROUTINES

CALLED: None

ERROR

RETURNS: The program will call EXIT if KRAD > 60.

PROGRAM NUTORD

PURPOSE: To revise chordwise panel spacing on fin, canard or tail and compute new airfoil ordinates.

METHOD: The program first tests to determine if the component under consideration is a fin (vertical tail), a canard, or a horizontal tail. The program then initializes the appropriate constants, and reads in an array of leading edge radii if the component has a round leading edge.

Each horizontal or vertical tail component is then treated as an additional wing segment, and the procedure follows the steps described under program NEWORD.

USE: CALL OVERLAY (LWB, 1, 6)

Input:

J4 Fin definition parameter

J5 Tail or canard definition parameter

K4 Fin leading edge definition parameter

K5 Tail or canard leading edge definition parameter

NF Number of fins

NC Number of tails and canards

NFINOR Number of ordinates defining fin airfoil

NCANOR Number of ordinates defining tail and canard airfoils

KFINOR Number of ordinates defining fin panel leading and trailing edges

KANOR Number of ordinates defining tail or canard panel leading and trailing edges

XAF, Array of percent chords for airfoil ordinates

XT

XAFK	Array of percent chords for panel leading and trailing edges
TALCR	Array of airfoil camber line ordinates
TALOR	Array of airfoil half-thickness ordinates
RHO	Array of airfoil leading edge radii

Output:

FIN	Fin identification variable (logical)
NT	Number of fins, tails or canards
J1	Tail or canard camber identifier
JL	Tail definition integer
KL	Airfoil leading edge definition integer
NWAFOR	Number of ordinates defining airfoil
KWAFOR	Number of ordinates defining fin, tail or canard panel leading and trailing edges
NWAR	Number of intervals in curve
NDA, DA	Number and value of derivative at initial point on curve
ZORD	Array of camber line ordinates
TORD	Array of half-thickness ordinates
DZC, DZCDX	Array of camber line slopes
DZT, DZTDX	Array of half-thickness slopes
A, B	Coefficients of leading edge curve
C, CC	Coefficients of cubic curves in each interval
TZORK	Array of revised camber line ordinates

DZCDXK Array of revised camber line slopes
WAFORK Array of revised half-thickness ordinates
DZTDXK Array of revised half-thickness slopes

SUBROUTINES
CALLED: DERIV

ERROR
RETURNS: None

SUBROUTINE PANEL

PURPOSE: To calculate direction cosines of the normal vector, the centroid, area, and inclination angles of an arbitrary quadrilateral panel.

METHOD: The four corners of the panel are numbered in a clockwise direction. A diagonal vector T_1 connects points 1 and 3, and a diagonal vector T_2 connects points 2 and 4. The normal vector N is obtained by taking the cross product of these diagonal vectors, and the direction cosines determined by calculating the projections of this vector in the reference coordinate system. The plane of the panel is defined to be perpendicular to the normal vector and to pass through a point whose coordinates are the averages of the coordinates of the four input points. The input points are then projected into the plane of the panel, and transformed to the reference coordinate system. A new panel coordinate system ξ, η is introduced with the average point of the panel as origin. The coordinates of the centroid and the panel area are calculated in this new system, and the centroid transformed to the reference system. Two angles are used to define the panel orientation. The incidence δ is the angle between the x axis and the line of intersection with the panel of a plane passing through the x axis and perpendicular to the panel. The inclination θ is the angle between the y axis and the line of intersection of the panel with the yz plane. These two angles are calculated in terms of the direction cosines of the normal vector.

USE: CALL PANEL (IP, IQ, J, K, L, NP, AP)

Input:

IP, IQ Panel identification code

J Panel row number

K Panel column number

L Surface identification code

NP Panel number

XC x coordinate of panel corner point
YC y coordinate of panel corner point
ZC z coordinate of panel corner point

Output:

NX,
NY,
NZ Direction cosines of the normal vector

AVX,
AVY,
AVZ Coordinates of average point

D Distance from corner point to plane of panel

XI,
ETA Coordinates of corner point in panel coordinate system

XIO,
ETAO Coordinates of centroid in panel coordinate system

XPT,
YPT,
ZPT Coordinates of centroid in reference coordinate system

DELTA Panel incidence angle
THET Panel inclination angle
AP Panel area

SUBROUTINES

CALLED: None

ERROR

RETURNS: None

SUBROUTINE PARTIN

PURPOSE: For wing-body combinations, to invert the matrix partitions and store the results on TAPE 10. For isolated wings or bodies, to solve the boundary condition equations and determine the body source strengths or wing vortex strengths.

METHOD: This subroutine is called only if the order of the matrix partition (or the full matrix in the case of isolated wings or bodies) does not exceed 60.

For wing-body combinations, the partitions are read from TAPE 9, inverted, and the inverse matrix written on TAPE 10.

For isolated wings or bodies, the matrix is read from TAPE 9, inverted, and the inverse post-multiplied by the normal velocity array to obtain the body source strengths or wing vortex strengths.

USE: CALL PARTIN

Input:

NWING Number of wing and tail panels
NBODY Number of body panels
NDIM Matrix dimension statement size
A, D Array of matrix elements
NW Array of wing and tail normal velocities
NB Array of body normal velocities

Output:

NPANEL Total number of panels
A, D Array of inverse matrix elements

TIME Elapsed time in seconds
GW Array of wing and tail vortex strengths
GB Array of body source strengths

SUBROUTINES
CALLED: SECOND

ERROR
RETURNS: None

SUBROUTINE PRESS

PURPOSE: To compute the pressure coefficient at a panel control point.

METHOD: The u , v , and w components of velocity are given in terms of the reference coordinate system. They are transformed into a new coordinate system aligned with the free stream velocity vector, and used to determine the pressure coefficient by means of the exact isentropic formula:

$$CP = \frac{2}{\gamma M^2} \left\{ \left[1 + \frac{\gamma-1}{2} M^2 (1 - Q^2) \right]^{3.5} - 1 \right\}$$

$$\text{where } Q^2 = (1 + u')^2 + v^2 + w'^2$$

$$u' = u \cos\alpha + w \sin\alpha$$

$$w' = w \cos\alpha - u \sin\alpha$$

If the Mach number M is zero, the pressure coefficient is determined by the incompressible formula:

$$CP = 1 - Q^2$$

The subroutine also calculates the stagnation pressure coefficient, the critical pressure coefficient, and the vacuum pressure coefficient by the following formulas:

$$CPSTAG = \frac{2}{\gamma M^2} \left\{ \left[1 + \frac{\gamma-1}{2} M^2 \right]^{3.5} - 1 \right\}$$

$$CPCRIT = \frac{2}{\gamma M^2} \left\{ \left[\frac{2}{\gamma+1} + \frac{\gamma-1}{\gamma+1} M^2 \right]^{3.5} - 1 \right\}$$

$$CPVAC = - \frac{2}{\gamma M^2}$$

USE: CALL PRESS (NP, XMACH, ARA, U, V, W, CPP,
CPSTAG, CPCRIT, CPVAC)

Input:

NP Panel number

XMACH Mach number

ARA Angle of attack in radians

U, Velocity components at panel control
V, point
W

Output:

CPP Pressure coefficient at panel control
point

CPSTAG Stagnation pressure coefficient

CPCRIT Critical pressure coefficient

CPVAC Vacuum pressure coefficient

SUBROUTINES

CALLED: None

ERROR

RETURNS: None

SUBROUTINE SCAMP4

PURPOSE: Given a set of n points (x_i, y_i) whose abscissae form a strictly monotone sequence, a first or second derivative at x_1 , and a first or second derivative at x_n , to find the smoothest possible curve passing rigorously through the given points, satisfying the specified boundary conditions, and possessing continuous first and second derivatives. The criterion for smoothness is the minimization of the integral of the square of the second derivative, from x_1 to x_n , over all functions having the stated properties. Accordingly, the curve found is a chain of cubics, i.e., a separate cubic defined on each interval (x_i, x_{i+1}) . The coefficients of each such cubic are explicitly found in the form

$$y = c_0 + c_1 x + c_2 x^2 + c_3 x^3$$

METHOD: The most economical (in time and space) and most accurate method of finding such a chain of cubics is to solve first for the n slopes y_i of the curve. This is done by the composite cubic subroutine COMCU, which solves an n th order linear system, the coefficient matrix of which is tridiagonal. Having found the slopes at each of the n given x_i , one can determine the coefficients of each cubic separately by using CUBIC2, which finds the cubic through two points, being given the slope at each. The coefficients of all the $n-1$ cubics can be obtained by using the subject routine (SCAMP4) which serves as a vehicle for calling COMCU (once) and CUBIC2 ($n-1$ times). SCAMP4 has an option to compute the required boundary conditions (first or second derivatives at the end points) if these are not known by the calling program; in this case, the computation of first derivatives at x_1 and x_n is recommended.

The cubic coefficients found by SCAMP4 are either stored in a 4 by $n-1$ array or are arranged in the composite curve format, i.e., in a single linear array where each segment is specified by a block of seven consecutive words: $x_i, x_{i+1}, 3., c_0, c_1, c_2, c_3$. The calling program should dimension the coefficient array as a doubly subscripted variable in the former case and singly subscripted in the latter case.

USE: CALL SCAMP4 (X, Y, N, NDA, NDB, DA, DB, C, S, M)

Input:

X Array of x values

Y Array of y values

N Number of points

NDA The order (1 or 2) of the derivative to be given at X(1). If derivative is to be computed by SCAMP4, NDA < 0.

NDB The order of the derivative to be given at X(N). Similar to NDA.

DA The value of the derivative at X(1). If derivative is to be computed by SCAMP4, leave blank.

DB The value of the derivative at X(N). Similar to NDA.

Code.

M {
12, if the cubic chain coefficients are to be stored in a doubly dimensioned 4 x (N-1) array.
= 12, if the cubic chain coefficients are to be stored in a singly dimensioned array

Output:

C Array of cubic chain coefficients

S Array of first derivatives

M {
Error return
= 0 - success
≠ 0 - error detected

SUBROUTINES
CALLED: COMCU, CUBIC2, DERIV1, DERIV2

ERROR

RETURNS: M = -1 indicates N < 2. 1 ≤ M ≤ 7 indicates an error return from COMCU. M large indicates error return k on the jth call to CUBIC2 (M = 100 + j + k).

SUBROUTINE SECOND

PURPOSE: To return elapsed CPU time in seconds.

METHOD: Control Data Corporation SCOPE Library subroutine.

USE: CALL SECOND (TIME)

Output:

TIME Elapsed CPU time in seconds

SUBROUTINES
CALLED: None

ERROR
RETURNS: None

RESTRICTIONS: Limited to CDC computers using SCOPE 3.0 operating system and library tape.

PROGRAM SOLVE

PURPOSE: To solve for the strengths of the body sources and wing vortices which satisfy the boundary condition of tangential flow at the panel control points, and to determine the corresponding pressure distribution, forces and moments on the configuration.

METHOD: The program first calculates the array of normal velocities required to satisfy the boundary conditions at the wing and body panel control points. The panel inclination angles θ and δ are obtained from the geometry arrays on TAPE 7, and the angle of attack α from COMMON block PARAM.

If the planar boundary condition and wing thickness options have been selected, the program next computes the normal velocities induced on the body and non-coplanar wing or tail segments by the wing source distribution. These normal velocities are subtracted from those previously calculated to obtain the resultant normal velocities at the control points.

The coefficients of the equations to be solved have previously been stored in row order on TAPE 9. Three different procedures are followed to solve the equations depending on the order of the matrix of coefficients. If the configuration to be analyzed consists of an isolated wing or body, and the order of the matrix does not exceed 60, the equations are solved in subroutine PARTIN by direct inversion of the matrix. If the configuration consists of a wing-body combination, and the order of the wing and body partition does not exceed 60, subroutine PARTIN inverts the diagonal partitions of the matrix and writes the inverse matrices on TAPE 10. An iterative procedure described in subroutine ITRATE is then applied to solve the equations. For any configuration for which the order of the wing or body partition exceeds 60, the diagonal blocks of the matrix are read from TAPE 7, inverted, and written on TAPE 10 by subroutine DIAGIN. Subroutine ITRATE is then called to solve the resulting equations by an iterative procedure.

Once the strengths of the source and vortex distributions have been determined, the program calculates the three components of velocity and pressure coefficient at each panel control point, starting with the body panels. The velocity components corresponding to unit strength source and vortex distribution are obtained from TAPE 8. The first three records on this file contains the velocity components at body control points induced by the body source panels, the wing source panels (if present), and the wing vortex panels. The program multiplies these by the corresponding source and vortex strength, and sums the products to obtain the resultant velocity component arrays at each body control point. The magnitude of the normal velocity at the body control points is also calculated at this point. If the absolute value of the print option is greater than one, the three components of velocity and the normals are written on the output file. The program then calls subroutine PRESS to obtain the pressure coefficients at the body panels, and subroutine FORMOM to integrate the pressures and calculate the force and moment acting on the body.

The velocity components at the wing and tail panel control points are computed next. The remaining three records containing the velocity components at wing and tail control points induced by the body source panels, the wing source panels (if present) and the wing vortex panels are read from TAPE 8. The program multiplies these by the corresponding source and vortex strengths and sums the products to obtain the resultant velocity component arrays at the wing and tail panel control points. If the absolute value of the print option is greater than one, the velocity component arrays are written on the output file. The program then calls subroutine PRESS to obtain the pressure coefficients, and subroutine FORMOM to calculate the force and moment acting on the wing.

If the planar boundary condition option has been selected, two passes through this section are required to obtain the velocity components, pressure and forces on both upper and lower surfaces.

The program writes the values of the stagnation pressure coefficient, the critical pressure coefficient, the vacuum pressure coefficient, and the elapsed time on the output file prior to returning.

USE: CALL OVERLAY (LWB, 3, 0)

Input:

NBODY Number of body panels
NWING Number of wing and tail panels
NWTWK Number of wing and tail panel source distributions
NMAX Maximum order of diagonal block matrices
PRINT Print option parameter (integer)
MACH Mach number
MATIN Matrix inversion parameter
LBC Planar boundary condition option parameter (logical)
THK Wing thickness option parameter (logical)
ALPHA Angle of attack in degrees
CHORD Array of wing and tail panel chords
DZTDX Array of wing and tail panel half-thickness slopes
ARRAY Wing or body panel geometry arrays
DELTA Array of panel incidence angles
THET Array of panel inclination angles
UA, VA, WA Arrays of velocity components induced by unit strength source and vortex distributions

Output:

EM Mach number

NPASS	Number of passes through program
COMPT	Wing or body component indicator (integer)
ALP	Angle of attack in radians
SINAL, COSAL	Trigonometric functions of angle of attack
SINT, COST	Trigonometric functions of inclination angle θ
TANDEL	$\tan \delta$
NW	Array of normal velocities required to satisfy boundary conditions at wing control points
NB	Array of normal velocities required to satisfy boundary conditions at body control points
U, V, W	Arrays of velocity components at control points
NS	Array of normal velocities at control points
GB	Array of body panel source strengths
GW	Array of wing and tail panel vortex Strengths
CP	Array of pressure coefficients at control points
CPSTAG	Stagnation pressure coefficient
CPVAC	Vacuum pressure coefficient
CPCRIT	Critical pressure coefficient
SGN	Wing upper and lower surface sign parameter
TIME	Elapsed time in seconds

SUBROUTINES
CALLED: DIAGIN, PARTIN, ITRATE, PRESS, FORMOM, SECOND

ERROR
RETURNS: None

SUBROUTINE SORPAN

PURPOSE: To calculate the three components of velocity induced at a given control point by a constant source distribution on a quadrilateral panel having longitudinal taper and inclined at an angle δ to the free stream direction.

METHOD: Formulas for the three components of velocity u , v , and w are given in Part I of this report. The subroutine obtains the information necessary to evaluate these formulas through COMMON block BODCOM, and returns the velocity components through the subroutine parameter list.

The first step in the calculation procedure is the adjustment of the z coordinate of each panel corner to ensure that it lies in the plane containing the panel leading edge and its control point. The influence functions F , G , and H are then calculated at the specified control point for each corner point in sequence. The final result is obtained by combining the four values of these functions.

USE: CALL SORPAN (UPM, VPM, WPM)

Input:

EM Mach number

SA $\tan \delta$ (δ is panel inclination angle)

CX Panel chord length

XC, Arrays of corner point coordinates

YC,

ZC

XI, Coordinates of control point

YI,

ZI

XJ, Coordinates of panel control point

ZJ

Output:

BT2,	Mach number parameters
BT A	
SM	Panel side edge slopes
DX, DY, DZ	Coordinates of control point referred to corner point
D	Compressed distance from corner point to control point
DPM	Scaled compressed distance from corner point to control point
XPM, YMX, ZAX, AYM	Transformed control point coordinates
RPM	Compressed distance from side edge to control point
TA	Panel edge slope parameter, $(1. + BT2 \cdot SA^2)$
TAM	Panel edge slope parameter, $(1. + BT2(SA^2 + SM^2))$
E, F, G, H	Corner point influence functions
E14, F14, G14	Combined corner point influence functions
R4PI	Reciprocal of 4π (or 2π if EM > 1)
UPM, VPM, WPM	Velocity components at control point in panel coordinate system
SUBROUTINES CALLED:	None
ERROR RETURNS:	None

SUBROUTINE SORVEL

PURPOSE: To calculate the three components of velocity induced at a given control point by constant and linearly varying source distributions on a swept quadrilateral panel. The subroutine calculates the velocity components induced by one corner of the panel.

METHOD: Formulas for the three components of velocity UC, VC, WC induced by a constant source distribution, and UL, VL, WL induced by a source distribution having a linear chordwise variation are given in Part I of this report. The subroutine obtains the information necessary to evaluate these formulas through COMMON block COMPS, and returns the velocity components through the parameter list. It is assumed that the Gothert Rule compressibility transformation has been applied to the geometrical data prior to calling this subroutine. Both sets of velocity components are expressed in terms of the influence functions F1, G1, G2, and G3 which depend only on the geometrical relationship of the control point to the corner point, the sweep angle, and Mach number.

The subroutine contains three separate branches for evaluating the velocity components, corresponding to the general case, a special case for supersonic leading edges, and a special case if the control point lies in the plane of the panel.

USE: CALL SORVEL (UC, VC, WC, UL, VL, WL)

Input:

DELTAY, y and z coordinates of control point
DELTAZ in reference coordinate system

X, Coordinates of control point with
Y, reference to corner point
Z

B Leading edge slope

BPOS Leading edge slope sign parameter
(logical)

SUB Subsonic Mach number parameter (logical)
COST, Sine and cosine of panel dihedral
SINT angle θ

Output:

SUP Supersonic Mach number parameter
(logical)

SUPLE Supersonic leading edge parameter
(logical)

BNEG Leading edge slope sign parameter
(logical)

BTERM Leading edge slope parameter

D Distance from control point to
corner point

R Distance from control point to
side edge

TZ Distance from control point to
leading edge

C1,
T2,
T3,
AT3 Geometrical parameters

F1,
G1,
G2,
G3 Influence functions

UC,
VC,
WC Velocity components at control point
induced by constant source distribution

UL,
VL,
WL Velocity components at control point
induced by source distribution with
linear chordwise variation

**SUBROUTINES
CALLED:** None

**ERROR
RETURNS:** None

PROGRAM TALPAN

PURPOSE: To revise the spanwise panel spacing on fin, canard, or tail and compute the panel geometry.

METHOD: The program first tests to determine if the component under consideration is a fin (vertical tail), a canard, or a horizontal tail. The program initializes the appropriate constants, then rewinds TAPE 7, reads the wing geometry arrays from that file, and stores them in COMMON block POINT. Each horizontal or vertical tail component is then treated as an additional wing segment, following the steps described under subroutine WNGPAN.

At the completion of the calculation, the combined wing and tail geometry arrays are stored in COMMON block POINT, and the entire sequence of arrays are written as a single record back on TAPE 7. The augmented CHORD and SLOPE arrays are also written on TAPE 7 at this point. The remaining wing and tail geometry parameters are stored in COMMON blocks PARAM and SEG. Finally, if the print option is positive, the fin, canard or tail panel corner point coordinates, control point coordinates, inclination angles, areas, and chords are written on the output file.

USE: CALL OVERLAY (LWB, 1, 7)

Input:

LBC Boundary condition option (logical)

PRINT Print option

K4 Fin definition parameter

K5 Tail or canard definition parameter

NF Number of fins

NK Number of tails or canards

NCPT Number of control points on wing

NWING, Number of panels in wing (initial value)
NINIT

KF	Number of streamwise panel edges on fin
KAN	Number of streamwise panel edges on tail or canard
YK	Array of spanwise locations of fin or tail panel streamwise edges
KFINOR	Number of ordinates defining fin panel leading and trailing edges
KANOR	Number of ordinates defining tail or canard panel leading and trailing edges
TALORG	Array of origin and chord length of each fin, tail or canard airfoil (x, y, z, c)
XAFK	Array of percent chords for panel leading and trailing edges
WAFORK	Array of airfoil half-thickness ordinates
TZORK	Array of airfoil camber ordinates
DZTDXK	Array of airfoil half-thickness slopes
DZCDXK	Array of airfoil camber slopes

Output:

Note:	In the following descriptions, the words tail or tail segment may refer to any fin, canard, or tail component
FIN	Fin identification variable (logical)
NTAL	Number of fins, tails, or canards
NT	Tail segment number
KK	Fin identification integer
KL	Leading edge identification integer
KWAF	Number of panel streamwise edges on tail segments

KWAFOR	Number of ordinates defining panel leading and trailing edges on tail segment
WAFORG	Array of origin and chord length of each tail segment airfoil (x, y, z, c)
NWING	Total number of wing and tail panels
NCPT	Total number of wing and tail control points
NP	Panel number
NC	Control point number
NSEG	Number of wing and tail segments
NROW	Number of rows of panels in segment
NCOL	Number of columns of panels in segment
KOL	Number of columns of panels on wing and tail
BL, BLE	Arrays of segment leading edge slopes
BT, BTE	Arrays of segment trailing edge slopes
TH	Array of segment dihedral angles
SINS	Array of sine of segment dihedral angle
COSS	Array of cosine of segment dihedral angle
NWT	Array of wing and tail indicator parameters
XK	Array of x-coordinates of origins of tail panel streamwise edges
ZK	Array of z-coordinates of origins of tail panel streamwise edges
CK	Array of chord lengths of tail panel streamwise edges

CL	Chord length of tail panel streamwise edge divided by one hundred
L	Tail surface indicator L = 1 indicates upper (inner) surface L = 2 indicates lower (outer) surface
SJ	Tail surface sign parameter
IP, IQ	Panel identification constants
XC, YC	Arrays of tail panel corner point x and y coordinates
ZC	Array of tail panel corner point z coordinates or lower (outer) surface coordinates for the non planar boundary condition option
ZU	Array of upper (inner) surface coordinates for the non planar boundary condition option
CR	Panel root chord
CT	Panel tip chord
RI, RO	Centroid ratios
XLE, XLEW	x coordinate of intersection of panel leading edge with streamwise line through centroid
XTE	x coordinate of intersection of panel trailing edge with streamwise line through centroid
CHORD	Array of panel chord lengths passing through centroids
SPN, SPNW	Array of panel spans
AREA	Array of panel areas

XPT, Array of panel control point coordinates
YPT,
ZPT

THET Array of panel dihedral angles

DZCDX Array of tail camber slopes at panel
edges (planar boundary condition option)

DELTA Array of tail camber slopes at panel
control points (planar boundary
condition option) or panel incidence
angle (non planar boundary condition
option)

DZTDX, Array of tail half-thickness slopes at
SLOPE panel edges (planar boundary condition
option)

SLE Leading edge slope for round leading
edge airfoils

XE Array of x coordinates of panel control
points

XS, Array of point source origins (non planar
YS, boundary condition option)
ZS

**SUBROUTINES
CALLED:** PANEL

**ERROR
RETURNS:** The program calls EXIT if NWING > 600

SUBROUTINE TRANS

PURPOSE: To transform the three components of velocity from the panel coordinate system to the reference coordinate system, to combine the contributions of the left and right wing panels, and to calculate the normal velocity at the control point.

METHOD: The axial and vertical velocity components are transformed by a rotation of the coordinate system about the horizontal axis by the angle δ . The axial velocity components induced by the left and right wing panels are added directly to determine the resultant axial velocity u .

Two additional coordinate rotations about the x axis are required before the v and w components induced by the left and right wing panels can be combined. The first rotation transforms the v and w components from the influencing panel coordinate system to the control point panel coordinate system, and the second transforms the combined normal and tangential velocity at the control point to v and w velocity components in the reference coordinate system.

USE: CALL TRANS (UR, VR, WR, UL, VL, WL, U, V, W, A)

Input:

UR, Three components of velocity at control
VR, point in right wing panel coordinate
WR system

UL, Three components of velocity at control
VL, point in left wing panel coordinate
WL system

Output:

U, Three components of velocity at control
V, point in reference coordinate system
W

A Normal velocity at control point

SUBROUTINES
CALLED: None

ERROR
RETURNS: None

SUBROUTINE TRAP

PURPOSE: To evaluate an integral by the trapezoidal rule.

METHOD: The x and y coordinates of a curve are read and the integral obtained by summing the areas within each interval for $i = 1, NT$

$$SUM = \frac{1}{2} \sum_{i=1}^{NT} (x_i - x_{i-1})(y_i + y_{i-1})$$

USE: CALL TRAP (XT, YT, SUM, NT)

Input:

XT Array of x coordinates (abscissa)

YT Array of y coordinates (ordinates)

NT Number of coordinates

Output:

SUM Integral $\int y dx$ by trapezoidal rule

SUBROUTINES
CALLED: None

ERROR
RETURNS: None

PROGRAM USSAERO

PURPOSE: This program controls the sequence of calculations required to determine the aerodynamic characteristics of wing-body-tail configurations in subsonic or supersonic potential flow.

METHOD: The input card deck is read and listed on the output file. The three primary overlay programs GEOM, VELCMP, and SOLVE are then called in sequence to perform the remaining calculations. The lengths of the principal COMMON blocks are also specified in this program.

USE: OVERLAY (LWB, 0, 0)
LWB is overlay file name.

PROGRAMS
CALLED: OVERLAY (LWB, 1, 0) (GEOM)
OVERLAY (LWB, 2, 0) (VELCMP)
OVERLAY (LWB, 3, 0) (SOLVE)

PROGRAM VELCMP

PURPOSE: To compute the velocity components u , v , and w at panel control points, and form the aero-dynamic influence coefficient matrices.

METHOD: The program reads the Mach number and angle of attack from the input file. If the Mach number is negative, or the same as the previous case, a return is executed. Otherwise, the program proceeds to compute the velocity components.

For wing alone, or wing-body configurations, a preliminary calculation is made to determine if the wing control points require relocation, and to compute the number and size of the wing diagonal blocks for later use in the matrix calculations. For wing-body configurations, the body geometry is first placed in temporary storage on TAPE 10. The program then proceeds to recalculate the chordwise locations of the wing control points for wings having supersonic edges, provided the planar boundary condition option has been selected. (An edge is defined to be supersonic if the component of the Mach number normal to the edge is greater than one.) Considering one wing segment at a time, the program tests to determine if either the leading or trailing edge is supersonic. If all edges are subsonic, the control points retain their original locations at the panel centroids. If the leading edge is subsonic and the trailing edge is supersonic, the control points in a given column of panels are adjusted uniformly between the centroid of the leading edge panel and the trailing edge of the last panel in the column. If both edges are supersonic, the control points are relocated at the panel leading edges, and the trailing edge of the last panel in the column. A wing supersonic trailing edge indicator array is also computed at this point in the program. The revised control points are stored in COMMON block POINT, and the entire wing geometry array written on TAPE 7. The body geometry temporarily stored on TAPE 10 is then rewritten on TAPE 7 following the wing geometry arrays.

The velocity component calculations are subdivided into four steps. For wing-alone or body-alone configurations, only the first step is necessary, otherwise all four steps are included. Each step involves the calculation of the influence coefficients of one partition of the complete aerodynamic matrices. The first partition gives the influence of the body panels at the body control points (or the influence of the wing panels at the wing control points for wing-alone configurations). The second partition gives the influence of the wing panels at the body control points, the third gives the influence of the body panels at the wing control points, and the fourth partition gives the influence of the wing panels at the wing control points for wing-body configurations. The program calculates the partition number, reads the appropriate geometry arrays from TAPE 7, and calls the wing or body panel velocity component program to obtain the influence coefficients.

On completion of the influence coefficient calculations, and if the order of any partition is greater than 60, the program writes the diagonal blocks of the aerodynamic matrix on TAPE 7 (following the geometry arrays) in preparation for the iterative solution. The number and size of the body diagonal blocks is calculated at this time, and stored with the wing diagonal block data and other matrix constants in COMMON block VELCOM.

USE:

CALL OVERLAY (LWB, 2, 0)

Input:

LBC Linear boundary condition option parameter (logical)

PRINT Print option parameter

MACH Mach number (real)

ALPHA Angle of attack

NMAX Maximum order of diagonal block matrices

NBODY	Number of body panels
KFUS	Number of body segments
KRADX	Array of body panel meridian lines in segment
KFORX	Array of body panel axial stations in segment
NWING	Number of wing and tail panels
NCPT	Number of wing and tail control points
NSEG	Number of wing and tail segments
NROW	Number of rows of panels in segment
NCOL	Number of columns of panels in segment
BL	Leading edge sweep of wing segment
BT	Trailing edge sweep of wing segment
ARRAY	Wing or body geometry arrays on TAPE 7
CHORD	Array of wing panel chords
DZTDX	Array of wing thickness slopes
XLE	Array of chordwise locations of wing control points
XPT, YPT, ZPT	Arrays of panel control point coordinates
DELTA	Array of panel incidence angles
D	Array of diagonal block matrix

Output:

MATIN	Matrix inversion indicator
SUB	Subsonic indicator (logical)
SUBLE	Subsonic leading edge indicator (logical)

SUBTE Subsonic trailing edge indicator
(logical)

EM Mach number

BETA Mach number parameter

NPOINT Number of control points

NPANEL Total number of panels

NWBLOK Number of diagonal block matrices in
wing partition

NBBLOK Number of diagonal block matrices in
body partition

NWROW,
NK Number of rows in wing diagonal block
matrix

NBROW Number of rows in body diagonal block
matrix

NC Number of columns of panels in segment

NR Number of rows of panels in segment

BLE Leading edge sweep of wing segment

BTE Trailing edge sweep of wing segment

IT Array of wing supersonic trailing edge
indicators

XPT Array of x coordinates of wing control
points

XCPT Array of chord fractions for control
point location

LOCPT Array of control point location
indicators

NPART Matrix partition number

XBT,
YBT,
ZBT Temporary array of panel control point
coordinates

TIME Elapsed time in seconds

PROGRAMS
CALLED: OVERLAY (LWB, 2, 1) (BODVEL)
 OVERLAY (LWB, 2, 2) (LINVEL)
 OVERLAY (LWB, 2, 3) (WNGVEL)
 SECOND

ERROR
RETURNS: None

SUBROUTINE VORPAN

- PURPOSE:** To calculate the three components of velocity induced at a given control point by constant and linearly varying vortex distributions on a swept quadrilateral panel. In addition, the subroutine calculates the three components of velocity induced by the concentrated vortex lying along the downstream extension of the inboard edge, and the vortex sheet located downstream of the trailing edge between the inboard edge and the intersection of the leading and trailing edges of the panel.
- METHOD:** Formulas for the velocity components UC, VC, WC induced by a constant vortex distribution, UL, VL, WL, and ULT, VLT, WLT induced by the leading and trailing edge corners respectively of a vortex distribution having a linear chordwise variation are given in Part I of this report. The subroutine obtains the information necessary to evaluate these formulas through COMMON block COMPS, and returns the velocity components through the parameter list. It is assumed that the Goherent Rule compressibility transformation has been applied to the geometrical data prior to calling this subroutine.
- The subroutine first performs the coordinate transformations and calculates the geometrical parameters required by the velocity component formulas. It then evaluates the downwash velocity induced by the trailing vortex sheet by numerical integration. Eleven chordwise stations are used in the trapezoidal rule integration.
- Three separate branches are provided for evaluating the velocity coefficients. The first branch is a special case for supersonic leading edges, the second contains the formulas for the general case, and the third contains special formulas used if the control point lies in the plane of the panel. In the latter two branches, the velocity components are expressed in terms of the six influence functions F1, G1, G2, G3, H1, and H2 which depend on the geometrical relationship of the control point to the corner point, the leading edge sweep angle, and the Mach number.

The v and w velocity components induced by the vortex sheet in the wake are expressed in terms of the influence functions F1 and H2, while those induced by the concentrated vortex in the wake are expressed in terms of the parameter C6. The wake vortices induce no axial component of velocity.

USE:

```
CALL VORPAN (UC, VC, WC, UL, VL, WL,ULT,  
VLT, WLT, VE, WE, VA, WA)
```

Input:

DELTAY, y and z coordinates of control points
DELTAZ in reference coordinate system

X, Coordinates of control point with
Y, reference to leading edge corner
Z point

A Difference between leading and trailing
edge slopes

B Leading edge slope

C Panel chord length along inboard edge

BPOS Leading edge slope sign parameter
(logical)

SUB Subsonic Mach number parameter (logical)

LBC Planar boundary condition option
parameter (logical)

COST, Sine and cosine of panel dihedral
SINT angle θ

ML Panel leading or trailing edge indicator

MAX Number of arguments in numerical eval-
uation of downwash integral

Output:

SUP Supersonic Mach number parameter (logical)

SUPLE Supersonic leading edge parameter
(logical)

AB,	Geometrical parameters
AZ,	
CC	
R	Distance from control point to side edge
D	Distance from control point to corner point
E	Distance from control point to intersection of leading and trailing edges of panel
T8	E^2
TZ	Distance from control point to leading edge squared
B1, SB1	Mach number parameters
B2	Geometrical parameters
↓	
B4	
C1	Geometrical parameters
↓	
C6	
T1	Geometrical parameters
↓	
T9	
XI	Array of x coordinates used in evaluation of downwash integral
Q, QX	Array of arguments used in evaluation of downwash integral
WQ	Value of downwash integral at leading edge
WQT	Value of downwash integral at trailing edge
SL, TL	Intermediate values of velocity functions at leading edge

ULS,	Intermediate values of velocity functions
VLS,	at trailing edge
WLS,	
TT,	
TLT	
 F1,	Influence functions
G1,	
G2,	
G3,	
H1,	
H2	
 VS,	Intermediate values of velocity
WS	components
 UC,	Velocity components at control point
VC,	induced by constant vortex
WC	distribution
 UL,	Velocity components at control point
VL,	induced by the leading edge corner of
WL	a vortex distribution with linear
	chordwise variation
 ULT,	Velocity components at control point
VLT,	induced by the trailing edge corner of
WLT	a vortex distribution with linear
	chordwise variation
 VA,	Velocity components at control point
VB,	induced by the trailing vortex sheet
WA,	
WB	
 VE,	Velocity components at control point
VD,	induced by concentrated vortex in
WE,	wake
WD	
 SUBROUTINES	
CALLED:	TRAP
 ERROR	
RETURNS:	None

SUBROUTINE VORVEL

PURPOSE: To calculate the three components of velocity induced at a given control point by constant and linearly varying vortex distributions on a swept quadrilateral panel. The subroutine calculates the velocity components induced by the leading and trailing corners of one edge of the panel.

METHOD: Formulas for the velocity components UC, VC, WC induced by a constant vortex distribution, UL, VL, WL, and ULT, VLT, WLT induced by the leading and trailing edge corners respectively of a vortex distribution having a linear chordwise variation are given in Part I of this report. The subroutine obtains the information necessary to evaluate these formulas through COMMON block COMPS, and returns the velocity components through the parameter list. It is assumed that Gothert Rule compressibility transformation has been applied to the geometrical data prior to calling this subroutine.

The subroutine first performs the coordinate transformations and calculates the geometrical parameters required by the velocity component formulas. It then evaluates the downwash velocity induced by the trailing vortex sheet by numerical integration. Eleven chordwise stations are used in the trapezoidal rule integration.

Three separate branches are provided for evaluating the velocity coefficients. The first branch is a special case for supersonic leading edges, the second contains the formulas for the general case, and the third contains special formulas used if the control point lies in the plane of the panel. In the latter two branches, the velocity components are expressed in terms of the six influence functions F1, G1, G2, G3, H1, and H2 which depend on the geometrical relationship of the control point to the corner point, the leading edge sweep angle, and the Mach number.

USE: CALL VORVEL (UC, VC, WC, UL, VL, WL,
ULT, VLT, WLT)

Input:

DELTAY, y and z coordinates of control points
DELTAZ in reference coordinate system

X, Coordinates of control point with
Y, reference to leading edge corner
Z point

A Difference between leading and trailing
edge slopes

B Leading edge slope

C Panel chord length along inboard edge

BPOS Leading edge slope sign parameter
(logical)

SUB Subsonic Mach number parameter (logical)

LBC Planar boundary condition option
parameter (logical)

COST, Sine and cosine of panel dihedral
SINT angle θ

ML Panel leading or trailing edge indicator

MAX Number of arguments in numerical evalua-
tion of downwash integral

Output:

SUP Supersonic Mach number parameter (logical)

SUPLE Supersonic leading edge parameter
(logical)

AB, Geometrical parameters
AZ,
CC

R Distance from control point to side edge

D Distance from control point to corner
point

E	Distance from control point to intersection of leading and trailing edges of panel
T8	E^2
TZ	Distance from control point to leading edge squared
B1, SB1	Mach number parameters
B2 ↓ B4	Geometrical parameters
C1 ↓ C6	Geometrical parameters
T1 ↓ T9	Geometrical parameters
XI	Array of x coordinates used in evaluation of downwash integral
Q, QX	Array of arguments used in evaluation of downwash integral
WQ	Value of downwash integral at leading edge
WQT	Value of downwash integral at trailing edge
SL, TL	Intermediate values of velocity functions at leading edge
ULS, VLS, WLS, TT, TLT	Intermediate values of velocity functions at trailing edge
F1, G1, G2, G3, H1, H2	Influence functions

VS, WS	Intermediate values of velocity components
UC, VC, WC	Velocity components at control point induced by constant vortex distribution
UL, VL, WL	Velocity components at control point induced by the leading edge corner of a vortex distribution with linear chordwise variation
ULT, VLT, WLT	Velocity components at control point induced by the trailing edge corner of a vortex distribution with linear chordwise variation

**SUBROUTINES
CALLED:** TRAP

**ERROR
RETURNS:** None

PROGRAM WNGPAN

PURPOSE: To revise the spanwise panel spacing on the wing and compute the panel geometry.

METHOD: The program first checks if the spanwise panel spacing is to be revised. If so, an array of revised panel edge locations is read in; otherwise, the panel edges are used as originally defined.

The wing panel geometry is established by considering regions defined by sequential pairs of the originally defined airfoil sections. The leading and trailing edge slopes and dihedral angle of the region are calculated, and the origins and chord lengths of any intermediate panel edges obtained by linear interpolation in the spanwise direction.

The individual panel geometry is then calculated. For the planar boundary condition option, the corner points and control points are calculated in the plane of the wing, while the wing camber and thickness slopes at the panel edges are obtained by a linear interpolation of the slopes determined in the program NEWORD. For the non planar boundary condition, the corner points and control points are calculated on the upper and lower surfaces of the wing, and the panel inclination angles determined by subroutine PANEL. In addition, both options calculate the panel area, chord, span, and leading edge x coordinate.

The same procedure is followed for each of the regions between the remaining airfoil sections. Prior to each step, the leading and trailing edge slopes and dihedral angles of the region are compared with those calculated for the previous region. If all these quantities are the same, the calculation proceeds normally. Otherwise, a new wing segment is defined, and the leading and trailing edge slopes, sine and cosine of the dihedral angle, and a wing indicator parameter for the segment are stored in a special array before continuing the calculations. The program also computes the number of rows and columns of panels in each wing segment, the total number of panels, and the total number of segments on the wing.

The three coordinates of the control points, the panel dihedral angles θ , the panel inclination angles δ , the three coordinates of the panel corner points, the panel areas, and x coordinates of the panel leading edges are stored in the COMMON block POINT, and the entire sequence of arrays written as a single record on TAPE 7. The CHORD and SLOPE arrays are also written on TAPE 7 at this point. The remaining wing geometry parameters are stored in COMMON blocks PARAM, and SEG. Finally, if the print option is positive, the corner point coordinates, control point coordinates, inclination angles, areas, and chords are written in the output file for reference.

USE: CALL OVERLAY (LWB, 1, 3)

Input:

LBC	Boundary condition option (logical)
PRINT	Print option
KL	Leading edge radius parameter
NWAF	Number of wing airfoil sections
KWAF	Number of wing panel streamwise edges
KWAFOR	Number of ordinates defining wing panel leading and trailing edges
WAFORG	Array of origin and chord length of each wing airfoil (x, y, x, c)
XAFK	Array of percent chord locations of panel leading and trailing edges
YK	Array of spanwise locations of wing panel streamwise edges
WAFORK	Array of airfoil half-thickness ordinates
TZORK	Array of airfoil camber ordinates
DZTDXK	Array of airfoil half-thickness slopes
DZCDXK	Array of airfoil camber slopes

Output:

NWING	Total number of wing panels
NCPT	Total number of control points
NP	Panel number
NC	Control point number
NSEG	Number of wing segments
NROW	Number of rows of panels in segment
NCOL	Number of columns of panels in segment
KOL	Number of wing panel streamwise edges
BL, BLE	Leading edge slope of wing segment array
BT, BTE	Trailing edge slope of wing segment array
TH	Dihedral angle of wing segment array
SINS	Sine of segment dihedral angle array
COSS	Cosine of segment dihedral angle array
NWT	Wing indicator parameter array
XK	Array of x-coordinates of origins of wing panel streamwise edges
ZK	Array of z-coordinates of origins of wing panel streamwise edges
CK	Array of chord lengths of wing panel streamwise edges
CL	Chord length of wing panel streamwise edge divided by one hundred
L	Wing surface indicator L = 1 indicates upper surface L = 2 indicates lower surface

SJ	Wing surface sign parameter
IP, IQ	Panel identification constants
XC, YC	Arrays of wing panel corner point x and y coordinates
ZC	Array of wing panel corner point z coordinates or lower surface z coordinates for the non planar boundary condition option
ZU	Array of upper surface z coordinates for the non planar boundary condition option
CR	Panel root chord
CT	Panel tip chord
RI, RO	Centroid ratios
XLE, XLEW	x coordinate of intersection of panel leading edge with streamwise line through centroid
XTE	x coordinate of intersection of panel trailing edge with streamwise line through centroid
CHORD	Array of panel chord lengths passing through centroids
SPN, SPNW	Array of panel spans
AREA	Array of panel areas
XPT, YPT, ZPT	Arrays of panel control point coordinates
THET	Array of panel dihedral angles
DZCDX	Array of wing camber slopes at panel edges (planar boundary condition option)

DELTA	Array of wing camber slopes at panel control point (planar boundary condition option) or panel incidence angle (non planar boundary condition option)
DZTDX, SLOPE	Array of wing half-thickness slopes at panel edges (planar boundary condition option)
SLE	Leading edge slope for round leading edge airfoils
XE	Array of x coordinates of panel control points
XS, YS, ZS	Arrays of point source origins (non planar boundary condition option)

SUBROUTINES

CALLED: PANEL

ERROR

RETURNS: The program calls EXIT if NWING > 600

PROGRAM WNGVEL

PURPOSE: To calculate the three components of velocity induced at specified control points by vortex panels located on wing or tail surfaces.

METHOD: The program first applies the Goertohrt rule compressibility transformation to the tangent of the panel inclination angles, and computes trigonometric functions of the revised angles. If the product $\beta \tan \delta$ is greater than one in supersonic flow, the panel lies outside the Mach cone from its apex, an error message is written and the program terminated.

The three coordinates of the first control point, and the corresponding panel inclination angles θ and δ are read from COMMON block POINT. If the control point is on the body, the inclination angle θ is obtained from COMMON block BTTHET.

The program then computes the influence of each panel at the control point. The panels on the upper surface of each chordwise column are considered first, followed by those on the lower surface. This process is repeated for each column of panels on a wing segment, starting with the inboard panel, and continued until all wing and tail segments have been included.

The coordinates of the four corner points of the influencing panel are obtained from COMMON block POINT in the reference coordinate system. They are indexed according to the panel row and column numbers. They are first used to calculate the leading and trailing edge slopes and the chord lengths of the inboard and outboard edges of the panel in a panel coordinate system lying in the plane of the panel and originating at the inboard leading edge corner. The control point is also transformed to the panel coordinate system, and the velocity components induced at the control point by each of the four corners computed by subroutine VORPAN. The subroutine is called twice for each corner point to obtain the contributions of both left and right wing panels.

The contribution of a wake consisting of two concentrated edge vortices with a constant strength vortex sheet between them is calculated following the last panel in each column. The wake vortices are all oriented in a streamwise direction, and are assumed to lie in a plane parallel to the reference axis and containing the trailing edge of the last panel in the column. The velocity components at the control point induced by the upstream corners of the wake are obtained by four additional calls to VORPAN.

The velocity components induced by the four corners of the panel and the wake are now combined to obtain the resultant velocities at the control point. The velocity components induced by the right and left wing panels are combined and the results transformed back to the reference coordinate system by subroutine TRANS. This subroutine calculates the u, v, and w velocity components and the normal velocity at the control point. A similar procedure is applied to calculate the transformed velocity components induced by the three components of the wake. The wake velocity components are then multiplied by the appropriate strength factors and added to obtain the net contribution of the wake. The wake velocities are then added to the panel velocities to obtain the final values of the velocity components at the control point.

Special rules are applied to obtain the velocity components of the leading and trailing edge panels in each column. These rules are designed to provide a continuous vortex distribution around the nose of the airfoil, and to enforce the Kutta condition at the trailing edge.

The procedure is repeated for each column of panels of each wing segment. When all panel influences have been computed, the u, v, and w components of velocity are written as a single record on TAPE 8, and the normal velocities written in one array on TAPE 9. If the control point is in the same column of panels on the wing as the influencing panel, and the wing has more than 60 panels, the normal velocity at the control point is written on TAPE 10, and its

value set equal to zero in the array written on TAPE 9. This procedure sets up the diagonal blocks of the aerodynamic matrix for later use in the iterative solution procedure. Finally, if the print option is selected, the axial and normal velocity component arrays are written on the output file.

This process is repeated for each control point.

USE:

CALL OVERLAY (LWB, 2, 3)

Input:

Note: The word wing includes any tail, fin, or canard in the following descriptions.

MACH Mach number

PRINT Print option parameter

NPART Matrix partition number

NMAX Maximum order of diagonal block matrices

NWING Number of wing panels

NPOINT Number of control points

NSEG Number of wing segments

NROW Number of rows of panels in segment

NCOL Number of columns of panels in segment

NWT Tail segment identification parameter

XPT, Arrays of control point coordinates

YPT,

ZPT

THET, Array of panel inclination angles
THETI

DELTA, Array of panel incidence angles
DELTI

XC, Arrays of x and y coordinates of wing
YC panel corner points

ZC Array of z coordinates of lower surface
 wing panel corner points

ZU Array of z coordinates of upper surface
 wing panel corner points

XS,
YS,
ZS Arrays of coordinates of point source
 origins

Output:

I Control point index

J,
JJ Wing panel index

L Panel row index

N Panel column index

NSIDE Column upper and lower surface index

NS Wing segment number

BETA Mach number parameter

SUB Subsonic flow parameter (logical)

SGN Supersonic flow sign parameter

CON,
BCON Vortex panel constants

NR Number of rows of panels in segment

NR1 NR + 1

NR2,
NRS 2NR

NC Number of columns of panels in segment

NC1 NC + 1

NT Tail segment identification parameter

NI Number of first column in segment

N2 Number of last column in segment

JL,	Number of first vortex distribution on
J1,	upper surface of column
JS1	
JT	Number of last vortex distribution on
	upper surface of column
J2,	Number of last vortex distribution on
JS2	lower surface of column
I1	Number of last panel on upper surface
	of column
I2	Number of last panel on lower surface
	of column
JK,	Temporary panel indices
JM	
M	Panel leading or trailing edge index
K	Panel side edge index
BD,	Tangent of transformed panel incidence
TANBD,	angle, $\beta \tan \delta$
TAND	
SINBD,	Trigonometric functions of transformed
SIND,	panel incidence angle
COSBD,	
COSD	
SINTI	$\sin \theta(I)$
COSTI	$\cos \theta(I)$
THETA	Inclination angle of panel J
SINT	$\sin \theta(J)$
COST	$\cos \theta(J)$
COSTD	$\cos \theta(J) / (1. + (\beta \tan \delta)^2)^{\frac{1}{2}}$
CONTD	$[(\beta \tan \delta)^2 + \cos^2 \theta(J)]^{\frac{1}{2}}$
COSTD	$1. / (\cos D * \text{CONTD})$
CONTDD	$1. / \text{CONTD}$

XI,	Coordinates of control point I
YI,	
ZI	
DXC,	Differences between panel corner points
DYC,	in reference coordinate system
DZC	
DXL,	Differences between panel corner points
DYL,	in panel coordinate system
DZL	
BL	Panel edge sweep
BLE	Panel leading edge sweep
BTE	Panel trailing edge sweep
AL,	Difference between panel leading and
A	trailing edge sweeps
CL	Panel edge chord
CI	Chord of inboard edge
CO	Chord of outboard edge
DX,	Control point coordinates with reference
DY,	to panel corner point
DZ	
XJ,	Control point coordinates in panel
YJ,	coordinate system
ZJ	
X	Dummy variable
UCIR,	Velocity components induced by inboard
VCIR,	leading edge corner of right wing
WCIR	panels containing constant vortex
	distribution
ULIR,	Velocity components induced by inboard
VLIR,	leading edge corner of right wing
WLIR	panels containing linearly varying
	vortex distribution
RCIR,	Same as UCIR, VCIR, WCIR, for inboard
SCIR,	trailing edge corner of right wing
TCIR	panel

RLIR,	Same as ULIR, VLIR, WLIR for inboard trailing edge corner of right wing panel
SLIR,	
TLIR	
UCIL,	Same as UCIR, VCIR, WCIR for left wing panels
VCIL,	
WCIL	
ULIL,	Same as ULIR, VLIR, WLIR for left wing panels
VLIL,	
WLIL	
RCIL,	Same as RCIR, SCIR, TCIR for left wing panels
SCIL,	
TCIL	
RLIL,	Same as RLIR, SLIR, TLIR for left wing panels
SLIL,	
TLIL	
VEIR,	Velocity components induced by concentrated vortex from leading edge along inboard edge of right wing panel
WEIR	
SEIR,	Same as VEIR, WEIR for vortex from trailing edge
TEIR	
VEIL,	Same as VEIR, WEIR for left wing panel
WEIL	
SEIL,	Same as SEIR, TEIR for left wing panel
TEIL	
VEOR,	Velocity components induced by concentrated vortex from leading edge along outboard edge of right wing panel
WEOR	
SEOR,	Same as VEOR, WEOR for vortex from trailing edge
TEOR	
VEOL,	Same as VEOR, WEOR for left wing panel
WEOL	
SEOL,	Same as SEOR, TEOR for left wing panel
TEOL	
VAIR,	Velocity components induced by vortex sheet from inboard leading edge corner of right wing panel
WAIR	

SAIR, TAIR	Same as VAIR, WAIR for vortex sheet from trailing edge
VAIL, WAIL	Same as VAIR, WAIR for left wing panel
SAIL, TAIL	Same as SAIR, TAIR for left wing panel
VAOR, WAOR	Same as VAIR, WAIR for outboard corner of right wing panel
SAOR, TAOR	Same as SAIR, TAIR for outboard corner of right wing panel
VAOL, WAOL	Same as VAOR, WAOR for left wing panel
SAOL, TAOL	Same as SAOR, TAOR for left wing panel
UAR, VAR, WAR	Velocity components induced by vortex sheet behind right wing panels
UAL, VAL, WAL	Same as above for left wing panels
UIR, VIR, WIR	Velocity components induced by inboard concentrated vortex behind right wing panels
UIL, VIL, WIL	Same as above for left wing panels
UOR, VOR, WOR	Velocity components induced by outboard concentrated vortex behind right wing panels
UOL, VOL, WOL	Same as above for left wing panels
ULR, VLR, WLR	Velocity components induced by linearly varying vortex distribution having zero strength along leading edge on right wing panels

ULL,	Same as above for left wing panels
VLL,	
WLL	
UCR, VCR, WCR	Velocity components induced by linearly varying vortex distribution having zero strength along trailing edge on right wing panels
UCL, VCL, WCL	Same as above for left wing panels
UC, VC, WC	Arrays of velocity components induced by vortex panels at control point I
US, VS, WS	Velocity components induced by point sources at control point I
AC	Array of normal velocities induced by vortex panels at control point I
AS	Normal velocity induced by point sources at control point I
DC	Array of normal velocities induced by vortex panels in diagonal block matrices
SUBROUTINES CALLED:	VORPAN, TRANS
ERROR RETURNS:	Program calls EXIT if $\beta \tan \delta > 1.$ in supersonic flow

APPENDIX II

PROGRAM LISTING

```

OVERLAY(LWB,0,0)
PROGRAM USSAERO(INPUT='401,OUTPUT=1001,TAPE5=INPUT,TAPE6=OUTPUT,TAP
1E7=1001,TAPE8=1001,TAPE9=1001,TAPE10=1001,TAPE11=401)

UNIFIED SUBSONIC-SUPERSONIC AERODYNAMICS PROGRAM
                                                 A 60
                                                 A 70
                                                 A 80
                                                 A 90
                                                 A 100
                                                 A 110
                                                 A 120
                                                 A 130
                                                 A 140
                                                 A 150
                                                 A 160
                                                 A 170
                                                 A 180
                                                 A 190
                                                 A 200
                                                 A 210
                                                 A 220
                                                 A 230
                                                 A 240
                                                 A 250
                                                 A 260
                                                 A 270
                                                 A 280
                                                 A 290
                                                 A 300
                                                 A 310
                                                 A 320
                                                 A 330
                                                 A 340
                                                 A 350
                                                 A 360
                                                 A 370
                                                 A 380
                                                 A 390
                                                 A 400
                                                 A 410
                                                 A 420

C PROGRAM USSAERO COMPUTES THE SUBSONIC AND SUPERSONIC POTENTIAL
C FLOW AERODYNAMIC CHARACTERISTICS OF CANARD-BODY-TAIL
C CONFIGURATIONS. THE BODY IS REPRESENTED BY SOURCE PANELS AND THE
C CANARD, WING, AND TAIL ARE REPRESENTED BY LINEARLY VARYING VORTEX
C PANELS.
C
C THIS PROGRAM WAS PREPARED FOR NASA LANGLEY RESEARCH CENTER UNDER
C CONTRACT NAS1-10408 BY AEROPHYSICS RESEARCH CORPORATION, BELLEVUE,
C WASHINGTON.
C
C THE INVESTIGATION WAS CONDUCTED BY MR. FRANK A. WOODWARD OF
C ANALYTICAL METHODS, INCORPORATED, BELLEVUE, WASHINGTON. AREA CODE
C 206-454-6115.
C
C ANY ERRORS OR PROBLEMS ENCOUNTERED IN USING THE PROGRAM SHOULD BE
C DIRECTED TO MR. CHARLES H. FOX, JR. AT NASA LANGLEY. AREA CODE 703
C -827-3711.
C
C A CARD DECK AND DOCUMENTATION FOR THE PROGRAM ARE AVAILABLE FROM
C COSMIC, UNIVERSITY OF GEORGIA, ATHENS, GEORGIA, 30601.
C
C THIS PROGRAM IS WRITTEN IN CDC FORTRAN IV, VERSION 2.3, TO RUN ON
C CDC 6600 SERIES COMPUTERS WITH THE SCOPE 3.0 OPERATING SYSTEM AND
C LIBRARY TAPE.
C
C COMMON DUM(72)
C COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REF(7)
C COMMON /POINT/ ARRAY(6000)
C COMMON /SCRAT/ BLOCK(7500)
C COMMON /HEAD/ TITLE(16)
C COMMON /SEG/ XS(261)
C COMMON /BTHET/ TB(600)
C COMMON /NEWCCM/ K(81)
C COMMON /MATCCM/ MATIN

```

COMMON /VELCCM/ N(5), EM, L(54)
DIMENSION ICARD(8)
REAL MACH

C
LWB=3LLWB
EM=-1.0
IC=0
WRITE (6,70)
WRITE (6,100)
WRITE (6,80)
C LIST INPUT CARDS
C
10 READ (5,110) ICARD
IF (ENDFILE 5) 30,20
WRITE (6,120) ICARD
IC=IC+1
GO TO 10
CONTINUE
20 WRITE (6,90)
WRITE (6,80)
DO 40 I=1,IC
C INPUT CONFIGURATION GEOMETRY AND COMPUTE PANELS
C
30 BACKSPACE 5
CALL OVERLAY (LWB,1,0)
C INPUT MACH NUMBER AND COMPUTE AERODYNAMIC MATRIX
C
40 CALL OVERLAY (LWB,2,0)
50
C MACH = -1. IS USED TO TERMINATE MACH NUMBER AND ANGLE OF ATTACK
C CASES FOR A GIVEN GEOMETRY
C
60 IF (MACH.LT.0.) GO TO 50
C
C SOLVE RESULTING MATRIX EQUATIONS AND
C COMPUTE PRESSURES, FORCES, AND MOMENTS
C
CALL OVERLAY (LWB,3,0)
GU TO 60
C

```

C   FORMAT (1H1,10X,48HUNIFIED SUBSONIC-SUPersonic AERODYNAMICS PROGRA A 860
      1M,10X,11HVERSION A00//) A 870
      FORMAT (10X,80H000000000111111111122222222333333334444444455 A 880
      155555566666666677777778/10X,80H12345678901234567890123456789 A 890
      2012345678901234567890123456789012345678901234567890//) A 900
      FORMAT (//) A 910
      FORMAT (1H0,25X,19HLIST OF INPUT CARDS//) A 920
      FORMAT (8A10) A 930
      FORMAT (8A10) A 940
      FORMAT (10X,8A10) A 950
      END A 960-

```

OVERLAY (LMB, 1, 0)
PROGRAM GEOM

INPUT CONFIGURATION GEOMETRY AND COMPUTE PANELS

THE INPUT TO THIS PROGRAM CONSISTS OF TWO BASIC PARTS, NAMELY,
 THE NUMERICAL DESCRIPTION OF THE CONFIGURATION GEOMETRY AND A
 SPECIFICATION OF THE SINGULARITY PANELING SCHEME ALONG WITH THE
 DESIRED MACH NUMBER AND ANGLE OF ATTACK COMBINATIONS TO CALCULATE

****DESCRIPTION OF GEOMETRY INPUT CARDS IS MODIFIED VERSION OF THE
 INPUT GEOMETRY SCHEME OF NASA TM X-2074)

THE AIRPLANE HAS TO BE SYMMETRICAL ABOUT THE XZ-PLANE, THEREFORE
 ONLY HALF OF THE AIRPLANE NEED BE DESCRIBED TO THE PROGRAM. THE
 CONVENTION USED IN PRESENTING THE INPUT DATA IS THAT THE HALF OF
 THE AIRPLANE ON THE POSITIVE Y-SIDE OF THE XZ-PLANE IS PRESENTED.
 THE NUMBER OF INPUT CARDS DEPENDS ON THE NUMBER OF COMPONENTS USED
 TO DESCRIBE THE CONFIGURATION, WHETHER A COMPONENT HAS BEEN
 DESCRIBED PREVIOUSLY, AND THE AMOUNT OF DETAIL USED TO DESCRIBE
 EACH COMPONENT. .

CARD 1 - IDENTIFICATION. CARD 1 CONTAINS ANY DESIRED IDENTIFYING
 INFORMATION IN COLUMNS 1-80.

CARD 2 - CONTROL INTEGERS. CARD 2 CONTAINS 24 INTEGERS, EACH
 PUNCHED RIGHT JUSTIFIED IN A 3-COLUMN FIELD. COLUMNS 73-80 MAY BE
 USED IN ANY DESIRED MANNER. CARD 2 CONTAINS THE FOLLOWING

COLUMNS	VARIABLE	VALUE	DESCRIPTION
1-3	J0	0	NO REFERENCE AREA
		1	REFERENCE AREA TO BE READ
4-6	J1	0	NO WING DATA

1			CAMBERED WING DATA TO BE READ UNCAMBERED WING DATA TO BE READ	B 430 B 440 B 450	
-1	7-9	J2	0	NO FUSELAGE DATA DATA FOR ARBITRARILY SHAPED FUSELAGE TO BE READ	B 460 B 470 B 480
			1	DATA FOR CIRCULAR FUSELAGE TO BE READ (WITH J6=0, FUSELAGE WILL BE CAMBERED. WITH J6=-1, FUSELAGE WILL BE SYMMETRICAL WITH XY-PLANE. WITH J6=1, ENTIRE CONFIGURATION WILL BE SYMMETRICAL WITH XY-PLANE)	B 490 B 500 B 510
			-1		B 520
10-12		J3	0	NO POD (NACELLE) DATA POD (NACELLE) DATA TO BE READ	B 530 B 540 B 550
13-15		J4	0	NO FIN (VERTICAL TAIL) DATA FIN (VERTICAL TAIL) DATA TO BE READ	B 560 B 570 B 580
16-18		J5	0	NO CANARD (HORIZONTAL TAIL) DATA CANARD (HORIZONTAL TAIL) DATA TO BE READ	B 590 B 600 B 610
19-21		J6	0	A CAMBERED CIRCULAR OR ARBITRARY FUSELAGE IF J2 IS NONZERO COMPLETE CONFIGURATION IS SYMMETRICAL WITH RESPECT TO XY-PLANE, WHICH IMPLIES AN UNCAMBERED CIRCULAR FUSELAGE IF THERE IS A FUSELAGE. UNCAMBERED CIRCULAR FUSELAGE WITH J2 NONZERO	B 620 B 630 B 640 B 650 B 660 B 670 B 680 B 690 B 700 B 710 B 720 B 730 B 740 B 750 B 760
22-24		NWAF	2-20	NUMBER OF AIRFOIL SECTIONS USED TO DESCRIBE THE WING	B 770 B 780 B 790
25-27		NWAFOR	3-30	NUMBER OF ORDINATES USED TO DEFINE EACH WING AIRFOIL SECTION IF THE VALUE OF NWAFOR IS INPUT WITH A NEGATIVE SIGN, THE PROGRAM WILL EXPECT TO READ	B 800 B 810 B 820 B 830 B 840 B 850

C	28-30	NFLS	1-4	NUMBER OF FUSELAGE SEGMENTS	B 870
C	31-33	NRADX(1)	3-30	NUMBER OF POINTS USED TO REPRESENT HALF-SECTION OF FIRST FUSELAGE SEGMENT. IF FUSELAGE IS CIRCULAR, THE PROGRAM COMPUTES THE INDICATED NUMBER OF Y- AND Z-ORDINATES	B 880
C	34-36	NFORX(1)	2-30	NUMBER OF STATIONS FOR FIRST FUSELAGE SEGMENT	B 890
C	37-39	NRAUX(2)	3-30	SAME AS NRADX(1), BUT FOR SECOND FUSELAGE SEGMENT	B 900
C	40-42	NFORX(2)	2-30	SAME AS NFORX(1), BUT FOR SECOND FUSELAGE SEGMENT	B 910
C	43-45	NRADX(3)	3-30	SAME AS NRADX(1), BUT FOR THIRD FUSELAGE SEGMENT	B 920
C	46-48	NFORX(3)	2-30	SAME AS NFORX(1), BUT FOR THIRD FUSELAGE SEGMENT	B 930
C	49-51	NRAUX(4)	3-30	SAME AS NRADX(1), BUT FOR FOURTH FUSELAGE SEGMENT	B 940
C	52-54	NFORX(4)	2-30	SAME AS NFORX(1), BUT FOR FOURTH FUSELAGE SEGMENT	B 950
C	55-57	NP	0-9	NUMBER OF PODS DESCRIBED	B 960
C	58-60	NPODOR	4-30	NUMBER OF STATIONS AT WHICH POD RADII ARE TO BE SPECIFIED	B 970
C	61-63	NF	0-6	NUMBER OF FINS (VERTICAL TAILS) TO BE DESCRIBED	B 980
C	64-66	NFINOR	3-10	NUMBER OF ORDINATES USED TO DESCRIBE EACH FIN (VERTICAL TAIL) AIRFOIL SECTION	B 990

07-69	NCAN	0-6	NUMBER OF CANARDS (HORIZONTAL TAILS) TO BE DESCRIBED	B1290 B1300 B1310 B1320 B1330 B1340 B1350 B1360 B1370 B1380 B1390 B1400 B1410 B1420 B1430 B1440 B1450 B1460 B1470 B1480 B1490 B1500 B1510 B1520 B1530 B1540 B1550 B1560 B1570 B1580 B1590 B1600 B1610 B1620 B1630 B1640 B1650 B1660 B1670 B1680 B1690 B1700 B1710
10-72	NCANCR	3-10	NUMBER OF ORDINATES USED TO DEFINE EACH CANARD (HORIZONTAL TAIL) AIRFOIL SECTION. IF THE VALUE OF NCANCR IS INPUT WITH A NEGATIVE SIGN, THE PROGRAM WILL EXPECT TO READ LOWER SURFACE ORDINATES ALSO, OTHERWISE THE AIRFOIL IS ASSUMED TO BE SYMMETRICAL.	B1330 B1340 B1350 B1360 B1370 B1380 B1390 B1400 B1410 B1420 B1430 B1440 B1450 B1460 B1470 B1480 B1490 B1500 B1510 B1520 B1530 B1540 B1550 B1560 B1570 B1580 B1590 B1600 B1610 B1620 B1630 B1640 B1650 B1660 B1670 B1680 B1690 B1700 B1710
			CARDS 3,4,... - REMAINING INPUT DATA CARDS. THE REMAINING INPUT DATA CARDS CONTAIN A DETAILED DESCRIPTION OF EACH COMPONENT OF THE AIRPLANE. EACH CARD CONTAINS UP TO 10 VALUES, EACH VALUE PUNCHED IN A 7-COLUMN FIELD WITH A DECIMAL POINT AND MAY BE IDENTIFIED IN COLUMNS 73-80. THE CARDS ARE ARRANGED IN THE FOLLOWING ORDER. REFERENCE AREA, WING DATA CARDS, FUSELAGE DATA CARDS, POD DATA CARDS, FIN (VERTICAL TAIL) DATA CARDS, AND CANARD (HORIZONTAL TAIL) DATA CARDS.	
			REFERENCE AREA CARD. THE REFERENCE AREA VALUE IS PUNCHED IN COLUMNS 1-7 AND MAY BE IDENTIFIED AS REFA IN COLUMNS 73-80	B1540 B1550 B1560 B1570 B1580 B1590 B1600 B1610 B1620 B1630 B1640 B1650 B1660 B1670 B1680 B1690 B1700 B1710
			WING DATA CARDS. THE FIRST WING DATA CARD (CR CARDS) CONTAINS THE LOCATIONS IN PERCENT CHORD AT WHICH THE ORDINATES OF ALL THE WING AIRFOILS ARE TO BE SPECIFIED. THERE WILL BE EXACTLY NWAFOR LOCATIONS IN PERCENT CHORD GIVEN. EACH CARD MAY BE IDENTIFIED IN COLUMNS 73-80 BY THE SYMBOL XAFJ WHERE J DENOTES THE LAST LOCATION IN PERCENT CHORD GIVEN ON THAT CARD.	
			THE NEXT WING DATA CARDS (THERE WILL BE NWAF CARDS) EACH CONTAIN FOUR NUMBERS WHICH GIVE THE ORIGIN AND CHORD LENGTH OF EACH OF THE WING AIRFOILS THAT IS TO BE SPECIFIED. THE CARD REPRESENTING THE MUST INBOARD AIRFOIL IS GIVEN FIRST, FOLLOWED BY THE CARDS FOR SUCCESSIVE AIRFOILS. THESE CARDS CONTAIN THE FOLLOWING COLUMNS	

CONTENTS

C C 1-7 B1720
 C C 8-14 B1730
 C C 15-21 B1740
 C C 22-28 B1750
 C C 73-80 B1760
 C C X-ORDINATE OF AIRFOIL LEADING EDGE B1770
 C C Y-ORDINATE OF AIRFOIL LEADING EDGE B1780
 C C Z-ORDINATE OF AIRFOIL LEADING EDGE B1790
 C C AIRFOIL STREAMWISE CHORD LENGTH B1800
 C C CARD IDENTIFICATION. WAFORGJ WHERE J B1810
 C C DENOTES THE PARTICULAR AIRFOIL, THUS B1820
 C C WAFORGJ DENOTES THE MUST INBOARD AIRFOIL. B1830
 C C
 C C IF A CAMBERED WING HAS BEEN SPECIFIED, THE NEXT SET OF WING DATA B1840
 C C CARDS IS THE MEAN CAMBER LINE CARDS. THERE WILL BE NWAFJR VALUES B1850
 C C OF DELTA Z REFERENCED TO THE Z-ORDINATE OF THE AIRFOIL LEADING B1860
 C C EDGE, EACH VALUE CORRESPONDING TO A SPECIFIED PERCENT CHORD B1870
 C C LOCATION ON THE AIRFOIL. THESE CARDS ARE ARRANGED IN THE ORDER B1880
 C C WHICH BEGINS WITH THE MOST INBOARD AIRFOIL AND PROCEEDS OUTBOARD. B1890
 C C EACH CARD MAY BE IDENTIFIED IN COLUMNS 73-80 AS TZDURDJ WHERE J B1900
 C C DENOTES THE PARTICULAR AIRFOIL. B1910
 C C
 C C NEXT ARE THE WING ORDINATE CARDS. THERE WILL BE NWAFJR VALUES OF B1920
 C C HALF-THICKNESS SPECIFIED FOR EACH AIRFOIL EXPRESSED AS PERCENT B1930
 C C CHORD. THESE CARDS ARE ARRANGED IN THE ORDER WHICH BEGINS WITH THE B1940
 C C MOST INBOARD AIRFOIL AND PROCEEDS OUTBOARD. EACH CARD MAY BE B1950
 C C IDENTIFIED IN COLUMNS 73-80 AS WAFORDJ WHERE J DENOTES THE B1960
 C C PARTICULAR AIRFOIL. B1970
 C C
 C C FUSELAGE DATA CARDS. THE FIRST CARD (OR CARDS) SPECIFIES THE X B1980
 C C VALUES OF THE FUSELAGE STATIONS OF THE FIRST SEGMENT. THERE WILL B1990
 C C BE NFURX(1) VALUES AND THE CARDS MAY BE IDENTIFIED IN COLUMNS B2000
 C C 73-80 BY THE SYMBOL XFUSJ WHERE J DENOTES THE NUMBER OF THE LAST B2010
 C C FUSELAGE STATION GIVEN ON THAT CARD. B2020
 C C
 C C IF THE FUSELAGE IS CIRCULAR, THE NEXT CARD (OR CARDS) GIVES THE B2030
 C C FUSELAGE CROSS SECTIONAL AREAS, AND MAY BE IDENTIFIED IN COLUMNS B2040
 C C 73-80 BY THE SYMBOL FUSARDJ WHERE J DENOTES THE NUMBER OF THE LAST B2050
 C C FUSELAGE STATION GIVEN ON THAT CARD. IF THE FUSELAGE IS OF B2060
 C C ARBITRARY SHAPE, NRDX(1) VALUES OF THE Y-ORDINATES FOR A HALF- B2070
 C C SECTION ARE GIVEN AND IDENTIFIED IN COLUMNS 73-80 AS YJ WHERE J IS B2080
 C C THE STATION NUMBER. FOLLOWING THE Y-ORDINATES ARE THE NRDX(1) B2090
 C C VALUES OF THE CORRESPONDING Z-ORDINATES FOR THE HALF-SECTION B2100
 C C IDENTIFIED IN COLUMNS 73-80 AS ZJ WHERE J IS THE STATION NUMBER. B2110
 C C EACH STATION WILL HAVE A SET OF Y AND Z, AND THE CONVENTION OF B2120
 C C ORDERING THE SEGMENTS FROM BOTTOM TO TOP IS OBSERVED. B2130
 C C B2140

FOR EACH FUSELAGE SEGMENT A NEW SET OF CARDS AS DESCRIBED MUST BE PROVIDED. THE SEGMENT DESCRIPTIONS SHOULD BE GIVEN IN ORDER OF INCREASING VALUES OF X.

POD DATA CARDS. THE FIRST POD (NACELLE) DATA CARD SPECIFIES THE LOCATION OF THE CRIGIN OF THE FIRST POD. THE CARD CONTAINS THE FOLLOWING

COLUMNS	CONTENTS	B2240
1-7	X-ORDINATE OF ORIGIN OF POD	B2250
8-14	Y-ORDINATE OF ORIGIN OF POD	B2260
15-21	Z-ORDINATE OF ORIGIN OF POD	B2270
73-80	CARD IDENTIFICATION, PODORG WHERE J DENOTES THE POD NUMBER	B2280

THE NEXT POD INPUT DATA CARD (OR CARDS) CONTAINS THE X-ORDINATES, REFERENCED TO THE POD ORIGIN, AT WHICH NPODOR VALUES OF THE POD RADII ARE TO BE SPECIFIED. THE FIRST X VALUE MUST BE ZERO AND THE LAST X VALUE IS THE LENGTH OF THE POD. THESE CARDS MAY BE IDENTIFIED IN COLUMNS 73-80 BY THE SYMBOL XPODJ WHERE J DENOTES THE POD NUMBER.

THE NEXT POD INPUT DATA CARDS GIVE THE POD RADII CORRESPONDING TO THE POD STATIONS THAT HAVE BEEN SPECIFIED. THESE CARDS MAY BE IDENTIFIED IN COLUMNS 73-80 AS PODRJ WHERE J DENOTES THE POD NUMBER.

FOR EACH ADDITIONAL POD, NEW PODORG, XPOD, AND PODR CARDS MUST BE PROVIDED. ONLY SINGLE PODS ARE DESCRIBED BUT THE PROGRAM ASSUMES THAT IF THE Y-ORDINATE IS NOT ZERO AN EXACT DUPLICATE IS LOCATED SYMMETRICALLY WITH RESPECT TO THE XZ-PLANE, A Y-ORDINATE OF ZERO IMPLIES A SINGLE POD.

COLUMNS	CONTENTS	B2490
1-7	X-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2500
8-14	Y-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2510

FIN DATA CARDS. EXACTLY THREE DATA INPUT CARDS ARE USED TO DESCRIBE A FIN (VERTICAL TAIL). THE FIRST FIN DATA CARD CONTAINS THE FOLLOWING.

COLUMNS	CONTENTS	B2520
1-7	X-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2530
8-14	Y-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2540

COLUMNS	CONTENTS	B2550
1-7	X-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2560
8-14	Y-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B2570

C 15-21 Z-ORDINATE OF INBOARD AIRFOIL LEADING EDGE B2580
 C 22-28 CHORD LENGTH OF INBOARD AIRFOIL B2590
 C 29-35 X-ORDINATE OF CUTBOARD AIRFOIL LEADING B2600
 C EDGE B2610
 C 36-42 Y-ORDINATE OF CUTBOARD AIRFOIL LEADING B2620
 C EDGE B2630
 C 43-49 Z-ORDINATE OF CUTBOARD AIRFOIL LEADING B2640
 C EDGE B2650
 C 50-56 CHORD LENGTH OF OUTBOARD AIRFOIL B2660
 C
 C 73-80 CARD IDENTIFICATION, FINORG WHERE J B2670
 C DENOTES THE FIN NUMBER. B2680
 C B2690
 C
 C THE SECOND FIN INPUT DATA CARD CONTAINS NFINOR VALUES OF X B2700
 C EXPRESSED IN PERCENT CHORD AT WHICH THE FIN AIRFOIL ORDINATES ARE B2710
 C TO BE SPECIFIED. THE CARD MAY BE IDENTIFIED IN COLUMNS 73-80 AS B2720
 C XFINJ WHERE J DENOTES THE FIN NUMBER. B2730
 C B2740
 C
 C THE THIRD FIN INPUT DATA CARD CONTAINS NFINOR VALUES OF THE FIN B2750
 C AIRFOIL HALF-THICKNESS EXPRESSED IN PERCENT CHORD. SINCE THE FIN B2760
 C AIRFOIL MUST BE SYMMETRICAL, ONLY THE ORDINATES ON THE POSITIVE B2770
 C Y SIDE OF THE FIN CHORD PLANE ARE SPECIFIED. THE CARD B2780
 C IDENTIFICATION FINORDJ MAY BE GIVEN IN COLUMNS 73-80 WHERE J B2790
 C DENOTES THE FIN NUMBER. B2800
 C B2810
 C
 C FOR EACH FIN, NEW FINORG, XFIN, AND FINORD CARDS MUST BE PROVIDED. B2820
 C ONLY SINGLE FINS ARE DESCRIBED, BUT THE PROGRAM ASSUMES THAT IF THE B2830
 C Y-ORDINATE IS NOT ZERO AN EXACT DUPLICATE IS LOCATED SYMMETRICALLY B2840
 C WITH RESPECT TO THE XZ-PLANE. A Y-ORDINATE OF ZERO IMPLIES A B2850
 C SINGLE FIN. B2860
 C B2870
 C B2880
 C
 C CANARD DATA CARDS. IF THE CANARD (OR HORIZONTAL TAIL) AIRFOIL IS B2890
 C SYMMETRICAL, EXACTLY THREE CARDS ARE USED TO DESCRIBE A CANARD, B2900
 C AND THE INPUT IS GIVEN IN THE SAME MANNER AS FOR A FIN. IF, B2910
 C HOWEVER, THE CANARD AIRFOIL IS NOT SYMMETRICAL (INDICATED BY A B2920
 C NEGATIVE VALUE OF NCANOR), A FOURTH CANARD INPUT DATA CARD WILL BE B2930
 C REQUIRED TO GIVE THE LOWER ORDINATES. THE INFORMATION PRESENTED CN B2940
 C THE FIRST CANARD INPUT DATA CARD IS AS FOLLOWS. B2950
 C B2960
 C B2970
 C B2980
 C B2990
 C B3000

C CONTENTS
 C X-ORDINATE OF INBOARD AIRFOIL LEADING EDGE
 C Y-ORDINATE OF INBOARD AIRFOIL LEADING EDGE

15-21	Z-ORDINATE OF INBOARD AIRFOIL LEADING EDGE	B3010
22-28	CHORD LENGTH OF INBOARD AIRFOIL	B3020
29-35	X-ORDINATE OF OUTBOARD AIRFOIL LEADING EDGE	B3030
36-42	Y-ORDINATE OF CUTBOARD AIRFOIL LEADING EDGE	B3040
43-49	Z-ORDINATE OF CUTBOARD AIRFOIL LEADING EDGE	B3050
50-56	CHORD LENGTH OF OUTBOARD AIRFOIL	B3060
73-80	CARD IDENTIFICATION. CANARD WHERE J DENOTES THE CANARD NUMBER.	B3070 B3080 B3090 B3100 B3110

THE SECOND CANARD INPUT DATA CARD CONTAINS NCANOR VALUES OF X
EXPRESSED IN PERCENT CHORD AT WHICH THE CANARD AIRFOIL COORDINATES
ARE TO BE SPECIFIED. THE CARD MAY BE IDENTIFIED IN COLUMNS 73-80
AS XCANJ WHERE J DENOTES THE CANARD NUMBER.

THE THIRD CANARD INPUT DATA CARD CONTAINS NCANOR VALUES OF THE
CANARD AIRFOIL HALF-THICKNESS EXPRESSED IN PERCENT CHORD. THIS
CARD MAY BE IDENTIFIED IN COLUMNS 73-80 AS CANRJJ WHERE J DENOTES
THE CANARD NUMBER. IF THE CANARD AIRFOIL IS NOT SYMMETRICAL, THE
LOWER COORDINATES ARE PRESENTED ON A SECOND CANARD CARD. THE PROGRAM
EXPECTS BOTH UPPER AND LOWER ORDINATES TO BE PUNCHED AS POSITIVE
VALUES IN PERCENT CHORD.

FOR ANOTHER CANARD, NEW CANORG, XCAN, AND CANORD CARDS MUST BE PROVIDED.

CARD 1-1 - IDENTIFICATION. CARD 1-1 CONTAINS ANY DESIRED IDENTIFYING INFORMATION IN COLUMNS 1-80.

CARD 1.2 - BOUNDARY CONDITION AND CONTROL POINT DEFINITION.
 NON-PLANAR BOUNDARY CONDITIONS ARE ALWAYS APPLIED ON A BODY,
 HOWEVER CARD 1.2 PERMITS THE SELECTION OF BOUNDARY CONDITIONS TO
 APPLY ON A WING, FIN (VERTICAL TAIL), OR CANARD (HORIZONTAL TAIL).

C THIS CARD ALSO SELECTS THE OUTPUT PRINT OPTIONS. THIS CARD
C CONTAINS THE FOLLOWING

COLUMNS	VARIABLE	VALUE	DESCRIPTION
1-3	LINBC	0	CCNTRL POINTS ON SURFACE OF WING, FIN (VERTICAL TAIL), AND CANARD (HORIZONTAL TAIL). THIS IS REFERRED TO AS THE NCN-PLANAR BOUNDARY CONDITION OPTION. B3470
		1	CONTROL POINTS IN PLANE OF WING, FIN (VERTICAL TAIL), AND CANARD (HORIZONTAL TAIL). THIS IS REFERRED TO AS THE PLANAR BCUNDARY CONDITION OPTION. B3480
4-6	THICK	0	DO NOT CALCULATE WING THICKNESS MATRIX B3490
		1	CALCULATE WING THICKNESS MATRIX IF LINBC=1 B3500
7-9	PRINT	0	PRINT OUT THE PRESSURES AND THE FORCES AND MOMENTS B3510
		1	PRINT OUT OPTION 0 AND THE SPANWISE LOADS ON THE WING, FINS, AND CANARDUS B3520
		2	PRINT OUT OPTION 1 AND THE VELOCITY COMPONENTS AND SOURCE AND VORTEX STRENGTHS B3530
		3	PRINT OUT OPTION 2 AND THE STEPS IN THE ITERATIVE SOLUTION B3540
		4	PRINT OUT OPTION 3 AND THE AXIAL AND NCRMAL VELOCITY MATRICES B3550
			A NEGATIVE VALUE OF PRINT ADDS THE PANEL GEOMETRY PRINT OUT TO THE OUTPUT INDICATED FOR OPTIONS 1, 2, 3, AND 4 B3560
			LINBC, THICK, AND PRINT ARE PUNCHED AS RIGHT JUSTIFIED INTEGERS THICK IS NOT USED IF LINBC = 0 B3570
			CARU-2.1 - REVISED CONFIGURATION PANELING DESCRIPTION CONTROL B3580

INTGERS. THE CCNTENTS OF CARD 2.1 ARE PUNCHED AS RIGT JUSTIFIED
INTEGERS AS FOLLOWS.

COLUMNS	VARIABLE	VALUE	DESCRIPTION	
1-3	K0	0	NC REFERENCE LENGTHS	B3870
		1	REFERENCE LENGTH DATA TO BE READ	B3880
4-6	K1	0	NO WING DATA	B3900
		1	WING DATA TO BE READ, WING HAS A SHARP LEADING EDGE.	B3910
		3	WING DATA TO BE READ, WING HAS A ROUND LEADING EDGE.	B3920
7-9	K2	0	NO BODY DATA	B3930
		1	BODY DATA FOLLOWS	B3940
10-12	K3		NOT USED	B3950
13-15	K4	0	NO FIN (VERTICAL TAIL) DATA	B3960
		1	FIN (VERTICAL TAIL) DATA TO BE READ, FIN HAS A SHARP LEADING EDGE.	B3970
		3	FIN (VERTICAL TAIL) DATA TO BE READ, FIN HAS A ROUND LEADING EDGE.	B3980
16-18	K5	0	NC CANARD (HORIZONTAL TAIL) DATA	B3990
		1	CANARD (HORIZONTAL TAIL) DATA TO BE READ, CANARD HAS A SHARP LEADING EDGE.	B4000
		3	CANARD (HORIZONTAL TAIL) DATA TO BE READ, CANARD HAS A ROUND LEADING EDGE.	B4010
19-21	K6		NOT USED	B4020
22-24	KWAF	0, 2-20	NUMBER OF WING SECTIONS USED TO DEFINE THE INBOARD AND OUTBOARD PANEL EDGES. IF KWAF=0, THE PANEL EDGES ARE DEFINED BY NWAF IN THE GEOMETRY INPUT.	B4230

C	25-27	KWAFOR	0,3-30	NUMBER OF ORDINATES USED TO DEFINE THE LEADING AND TRAILING EDGES OF THE WING PANELS. IF KWAFOR=0, THE PANEL EDGES ARE DEFINED BY NWAFOR IN THE GEOMETRY INPUT.	B4300 B4310 B4320 B4330 B4340 B4350
C	28-30	KFUS	0,3-20	THE NUMBER OF FUSELAGE SEGMENTS. THE PROGRAM SETS KFUS=NFUS.	B4360 B4370 B4380
C	31-33	KRADX(1)	0,3-20	NUMBER OF MERIDIAN LINES USED TO DEFINE PANEL EDGES ON FIRST BODY SEGMENT. IF KRADX(1)=0, THE PANEL EDGES ARE DEFINED BY NRADX(1) IN THE GEOMETRY INPUT. NEGATIVE VALUES OF KRADX(1) INDICATE THAT REVISED MERIDIAN ANGLES FOLLOW.	B4390 B4400 B4410 B4420 B4430 B4440 B4450 B4460 B4470 B4480 B4490 B4500 B4510 B4520 B4530 B4540 B4550 B4560 B4570 B4580 B4590 B4600
C	34-36	KFORX(1)	0,2-30	FOR AN ARBITRARILY SHAPED FUSELAGE (BODY) (J2=1) THERE ARE THREE OPTIONS FOR DEFINING THE PANEL EDGES. IF KRADX(1)=0, THE MERIDIAN LINES ARE DEFINED BY NRADX(1) IN THE GEOMETRY INPUT. IF KRADX(1) IS POSITIVE, THE MERIDIAN LINES ARE CALCULATED AT KRADX(1) EQUALLY SPACED PHIKS. IF KRADX(1) IS NEGATIVE, THE MERIDIAN LINES ARE CALCULATED AT SPECIFIED VALUES OF PHIK.	B4610 B4620 B4630 B4640 B4650 B4660 B4670 B4680 B4690 B4700 B4710 B4720
C	37-39	KRADX(2)	0,3-20	SAME AS KRADX(1), BUT FOR SECOND BODY SEGMENT	
C	40-42	KFORX(2)	0,2-30	SAME AS KFORX(1), BUT FOR SECOND	

		BODY SEGMENT	B4730 B4740	
43-45	KRADX(3)	0,3-20	SAME AS KRADX(1), BUT FOR THIRD BODY SEGMENT B4750 B4760	
46-48	KFORX(3)	0,2-30	SAME AS KFORX(1), BUT FOR THIRD BODY SEGMENT B4770 B4780	
49-51	KRADX(4)	0,3-20	SAME AS KRADX(1), BUT FOR FOURTH BODY SEGMENT B4790 B4800	
52-54	KFORX(4)	0,2-30	SAME AS KFORX(1), BUT FOR FOURTH BODY SEGMENT B4810 B4820 B4830 B4840 B4850	
THIS PROGRAM IS RESTRICTED TO 600 BODY SINGULARITY PANELS. FOR THIS PROGRAM THERE IS AN ADDITIONAL RESTRICTION THAT THE TOTAL NUMBER OF SINGULARITY PANELS IN THE AXIAL DIRECTION ON THE BODY (FUSELAGE) CANNOT EXCEED 30 B4860 IT IS IMPORTANT TO UNDERSTAND THAT THE ARBITRARY BODY (FUSELAGE) CAPABILITY OF THIS PROGRAM IS LIMITED TO THESE SHAPES FOR WHICH K IS A SINGLE-VALUED FUNCTION OF PHI FOR EACH CRUSS SECTION.				
CARD 2.2 - ADDITIONAL REVISED CONFIGURATION PANELING DESCRIPTION CONTROL INTEGERS. THE CONTENTS OF CARD 2.2 ARE PUNCHED AS RIGHT JUSTIFIED INTEGERS AS FOLLOWS.				
COLUMNS	VARIABLE	VALUE	DESCRIPTION	
1-3	KF(1)	0,2-20	NUMBER OF FIN SECTIONS USED TO DEFINE THE INBOARD AND CUTBOARD PANEL EDGES ON THE FIRST FIN. IF KF(1)=0, THE ROOT AND TIP CHORDS DEFINE THE PANEL EDGES.	B4960 B4970 B4980 B4990 B5000 B5010 B5020 B5030 B5040 B5050 B5060 B5070 B5080 B5090 B5100 B5110 B5120 B5130 B5140 B5150
4-6	KFINOR(1)	0,3-30	NUMBER OF ORDINATES USED TO DEFINE THE LEADING AND TRAILING EDGES OF THE FIN PANELS ON THE FIRST FIN. IF KFINOR(1)=0, THE PANEL EDGES ARE DEFINED BY NFINOR.	
7-9	KF(2)	0,2-20	SAME AS FCR KF(1), BUT FOR	

C	10-12	KFINOR(2)	0,3-30	SAME AS FOR KFINOR(1), BUT FOR SECOND FIN.	B5160 B5170 B5180 B5190
C	13-15	KF(3)	0,2-20	SAME AS FOR KF(1), BUT FOR THIRD FIN.	B5200 B5210 B5220
C	16-18	KFINOR(3)	0,3-30	SAME AS FOR KFINOR(1), BUT FOR THIRD FIN.	B5230 B5240 B5250
C	19-21	KF(4)	0,2-20	SAME AS FOR KF(1), BUT FOR FOURTH FIN.	B5260 B5270 B5280
C	22-24	KFINOR(4)	0,3-30	SAME AS FOR KFINOR(1), BUT FOR FOURTH FIN.	B5290 B5300 B5310
C	25-27	KF(5)	0,2-20	SAME AS FOR KF(1), BUT FOR FIFTH FIN.	B5320 B5330 B5340
C	28-30	KFINOR(5)	0,3-30	SAME AS FOR KFINOR(1), BUT FOR FIFTH FIN.	B5350 B5360 B5370
C	31-33	KF(6)	0,2-20	SAME AS FOR KF(1), BUT FOR SIXTH FIN.	B5380 B5390 B5400
C	34-36	KFINOR(6)	0,3-30	SAME AS FOR KFINOR(1), BUT FOR SIXTH FIN.	B5410 B5420 B5430
C	37-39	KCAN(1)	0,2-20	NUMBER OF CANARD SECTIONS USED TO DEFINE THE INBOARD AND OUTBOARD PANEL EDGES ON THE FIRST CANARD. IF KCAN(1)=0, THE ROOT AND TIP CHORDS DEFINE THE PANEL EDGES. IF KCAN(1) NEGATIVE, NO VORTEX SHEET CARRIES THROUGH THE BODY, AND CONCENTRATED VORTICES ARE SHED FROM THE INBOARD EDGE OF THE CANARD OR TAIL SURFACE.	B5440 B5450 B5460 B5470 B5480 B5490 B5500 B5510 B5520 B5530 B5540 B5550 B5560 B5570 B5580
C	40-42	KCANOR(1)	0,3-30	NUMBER OF ORDINATES USED TO DEFINE THE LEADING AND TRAILING	

			EDGES OF THE FIRST CANARD. IF KCANOR(1)=0, THE PANEL EDGES ARE DEFINED BY NCANUR.	85590 B5600 B5610 B5620 B5630 B5640 B5650 B5660 B5670
43-45	KCAN(2)	0,2-20	SAME AS FOR KCAN(1), BUT FOR SECOND CANARD.	B5680
46-48	KCANOR(2)	0,3-30	SAME AS FOR KCANOR(1), BUT FOR SECOND CANARD.	B5690 B5700
49-51	KCAN(3)	0,2-20	SAME AS FOR KCAN(1), BUT FOR THIRD CANARD.	B5710
52-54	KCANOR(3)	0,3-30	SAME AS FOR KCANOR(1), BUT FOR THIRD CANARD.	B5720 B5730
55-57	KCAN(4)	0,2-20	SAME AS FOR KCAN(1), BUT FOR FOURTH CANARD.	B5740 B5750 B5760
58-60	KCANOR(4)	0,3-30	SAME AS FOR KCANOR(1), BUT FOR FOURTH CANARD.	B5770 B5780 B5790
61-63	KCAN(5)	0,2-20	SAME AS FOR KCAN(1), BUT FOR FIFTH CANARD.	B5800 B5810 B5820
64-66	KCANOR(5)	0,3-30	SAME AS FOR KCANOR(1), BUT FOR FIFTH CANARD.	B5830 B5840 B5850
67-69	KCAN(6)	0,2-20	SAME AS FOR KCAN(1), BUT FOR SIXTH CANARD.	B5860 B5870 B5880
70-72	KCANOR(6)	0,3-30	SAME AS FOR KCANOR(1), BUT FOR SIXTH CANARD.	B5890 B5900 B5910 B5920
			THIS PROGRAM IS RESTRICTED TO A TOTAL OF 600 SINGULARITY PANELS ON THE WING-FIN-CANARD COMBINATION. FOR THIS PROGRAM THERE IS AN ADDITIONAL RESTRICTION THAT THE TOTAL NUMBER OF SINGULARITY PANELS IN THE SPANWISE DIRECTION ON THE WING-F-IN-CANARD COMBINATION CANNOT EXCEED 20.	B5930 B5940 B5950 B5960 B5970 B5980 B5990 B6000 B6010
			CARDS 3,4,••• - REMAINING INPUT DATA CARDS. THE REMAINING INPUT DATA CARDS CONTAIN A DETAILED DESCRIPTION OF THE SINGULARITY	

PANELING OF EACH COMPONENT OF THE AIRPLANE. EACH CARD CONTAINS UP TO 10 VALUES, EACH VALUE PUNCHED IN A 7-COLUMN FIELD WITH A DECIMAL POINT AND MAY BE IDENTIFIED IN COLUMNS 75-80. THE CARDS ARE ARRANGED IN THE FOLLOWING ORDER. REFERENCE LENGTHS, WING DATA CARDS, FIN (VERTICAL TAIL) DATA CARDS, CANARD (HORIZONTAL TAIL) DATA CARDS, FUSELAGE (BODY) DATA CARDS, AND FINALLY MACH NUMBER AND ANGLE OF ATTACK CASE CARDS. NOTE THAT THE PRESENT PROGRAM WILL NOT HANDLE A POD AND THEREFORE THERE ARE NO POD PANEL INPUTS, HOWEVER, IF THE GEOMETRY INPUT CONTAINS A PCD DESCRIPTION IT WILL BE READ AND IGNORED.	B6020 B6030 B6040 B6050 B6060 B6070 B6080 B6090 B6100 B6110
REFERENCE LENGTHS CARD. THIS CARD MAY BE IDENTIFIED AS REFL IN COLUMNS 73-80 AND CONTAINS THE FOLLOWING	B6120 B6130 B6140 B6150 B6160 B6170 B6180
COLUMNS VARIABLE	DESCRIPTION
1-7	REFA
8-14	REFB
15-21	REFC
22-28	REFD
29-35	REFL
36-42	REFX
43-49	REFZ

WING REFERENCE AREA. IF REF_A=0, A
THE REFERENCE AREA IS DEFINED BY
THE VALUE OF KEFA IN THE
GEOMETRY INPUT.

WING SEMISPAN. IF REF_B=0, A
VALUE OF 1.0 IS USED FOR THE
REFERENCE SEMISPAN.

WING REFERENCE CHORD. IF REF_C=0,
A VALUE OF 1.0 IS USED FOR THE
REFERENCE CHORD.

BODY (FUSELAGE) REFERENCE
DIAMETER. IF REF_D=0, A VALUE OF
1.0 IS USED FOR THE REFERENCE
DIAMETER.

BODY (FUSELAGE) REFERENCE LENGTH
IF KEFL=0, A VALUE OF 1.0 IS
USED FOR THE REFERENCE LENGTH.

X COORDINATE OF MOMENT CENTER

Z COORDINATE OF MOMENT CENTER

C THE CANARD LEADING EDGE RADIUS CARD AND IS REQUIRED ONLY WHEN K5=3
C THIS CARD CONTAINS NCAN VALUES OF LEADING EDGE RADIUS EXPRESSED IN
C PERCENT CHORD. ONE VALUE FOR EACH CANARD. IT MAY BE IDENTIFIED IN
C COLUMNS 73-80 AS RHOCAN.

C NEXT IS THE CANARD PANEL LEADING EDGE CARD FOR THE FIRST CANARD.
C THIS CARD CONTAINS KCAN(11) VALUES OF CANARD PANEL LEADING EDGE
C LOCATIONS EXPRESSED IN PERCENT CHORD. THIS CARD MAY BE IDENTIFIED
C IN COLUMNS 73-80 AS XCANKJ WHERE J DENOTES THE CANARD NUMBER.
C REPEAT THIS CARD FOR EACH CANARD.

C THE LAST CANARD DATA CARD GIVES THE CANARD PANEL SIDE EDGE DATA
C FOR THE FIRST CANARD. THIS CARD CONTAINS KCAN(11) VALUES OF THE Y
C ORDINATE OF THE PANEL INBOARD EDGES. THIS CARD MAY BE IDENTIFIED
C IN COLUMNS 73-80 AS YCANKJ WHERE J DENOTES THE CANARD NUMBER.
C THESE VALUES ARE ARRANGED IN THE ORDER THAT BEGINS WITH THE MOST
C INBOARD PANEL EDGE AND PROCEEDS OUTBOARD.
C REPEAT THIS CARD FOR EACH CANARD.

C FUSELAGE (BODY) DATA CARDS. THE FIRST BODY CARD IS THE BODY
C MERIDIAN ANGLE CARD. THIS CARD CONTAINS KRDX(11) VALUES OF BODY
C MERIDIAN ANGLE EXPRESSED IN DEGREES AND MAY BE IDENTIFIED IN
C COLUMNS 73-80 AS PHIKJ WHERE J DENOTES THE BODY SEGMENT NUMBER.
C THE CONVENTION IS OBSERVED THAT PHIK=0 AT THE BOTTOM OF THE BODY
C AND PHIK=180 AT THE TOP OF THE BODY. OMIT UNLESS KRDX(11) IS
C NEGATIVE.
C REPEAT THIS CARD FOR EACH FUSELAGE SEGMENT.

C THE SECOND BODY CARD IS THE BODY AXIAL STATION CARD. THIS CARD
C CONTAINS KFCRAX(11) VALUES OF THE X ORIGINATE OF THE BODY AXIAL
C STATIONS AND MAY BE IDENTIFIED IN COLUMNS 72-80 AS XFUSKJ WHERE J
C DENOTES THE BODY SEGMENT NUMBER. OMIT IF KFCRAX(11)=0.
C REPEAT THIS CARD FOR EACH FUSELAGE SEGMENT.

C MACH NUMBER AND ANGLE OF ATTACK CARD. THIS CARD MAY BE IDENTIFIED
C IN COLUMNS 73-80 AS MALPHA AND CONTAINS THE FOLLOWING

C COLUMN	C VARIABLE	C CONTENTS
C 1-7	C MACH	C THE SUBSONIC MACH NUMBER (INCLUDING THE C VALUE MACH=0.) OR THE SUPERSONIC MACH C NUMBER AT WHICH IT IS DESIRED TO CALCULATE

B7230
B7240
B7250
B7260
B7270
B7280
B7290
B7300

```

REFD=1.0          B7740
REFL=1.0          B7750
REFX=0.           B7760
REFZ=0.           B7770
REWIND 7          B7780
REWIND 8          B7790
REWIND 9          B7800
REWIND 10         B7810
REWIND 10         B7820
REWIND 10         B7830
REWIND 10         B7840
REWIND 10         B7850
REWIND 10         B7860
REWIND 10         B7870
REWIND 10         B7880
REWIND 10         B7890
REWIND 10         B7900
REWIND 10         B7910
REWIND 10         B7920
REWIND 10         B7930
REWIND 10         B7940
REWIND 10         B7950
REWIND 10         B7960
REWIND 10         B7970
REWIND 10         B7980
REWIND 10         B7990
REWIND 10         B8000
REWIND 10         B8010
REWIND 10         B8020
REWIND 10         B8030
REWIND 10         B8040
REWIND 10         B8050
REWIND 10         B8060
REWIND 10         B8070
REWIND 10         B8080
REWIND 10         B8090
REWIND 10         B8100
REWIND 10         B8110
REWIND 10         B8120
REWIND 10         B8130
REWIND 10         B8140
REWIND 10         B8150
REWIND 10         B8160

C   INPUT CONFIGURATION PARAMETERS          B7740
C
C   READ (5,140) TITLE1                      B7750
C   IF (ENDFILE 5) 20,10                     B7760
C   CONTINUE                                     B7770
C   WRITE (6,160) TITLE1                      B7780
C   READ (5,140) ABCD                         B7790
C   DECODE (72,170,ABCD) J0,J1,J2,J3,J4,J5,JO,NWAFJ,WFUS,INRADX( B7800
C   11),NFURX(1),I=1,4),NP,NFUDOR,NF,NFINUR,NCAN,NCANOR
C   GU TU 30                                     B7810
C   CALL EXIT                                     B7820
C
C   INPUT DESCRIPTION AND INITIALIZATION      B7830
C
C   CALL UVERLAY (LWB,1,1)                      B7840
C
C   SET BOUNDARY CONDITION AND WING THICKNESS CPTNS B7850
C
C   READ (5,140) TITLE2                         B7860
C   READ (5,170) LINBC,THICK,PRINT             B7870
C   IF (LINBC.GT.0) LBC=.TRUE.                  B7880
C   IF (LBC.AND.THICK.GT.0) THK=.TRUE.          B7890
C
C   INPUT REVISED CONFIGURATION PANELING      B7900
C   DESCRIPTION CONTROL INTEGERS              B7910
C
C   READ (5,140) AEC(                           B7920
C   DECODE (72,170,ABCD) K0,K1,K2,K3,K4,K5,K6,KWAFJ,KFUS,IKRADX( B7930
C   11),KFURX(1),I=1,4)
C   TAIL=.FALSE.                                B7940
C   IF (K4.GT.0.OR.K5.GT.0) TAIL=.TRUE.        B7950
C   IF (.NOT.TAIL) GC TO 40                   B7960
C   READ (5,140) ABCD                         B7970
C   DECODE (72,170,ABCD) IKF(1),KFUR(1),I=1,6), (KAN(1),KANDR(1),I=1, B7980
C   16)                                         B7990

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C   8-14      ALPHA          THE AERODYNAMIC DATA.
C                                     THE ANGLE OF ATTACK EXPRESSED IN DEGREES
C                                     AT WHICH IT IS DESIRED TO CALCULATE THE
C                                     AERODYNAMIC DATA.
C
C   A SERIES OF MACH NUMBER AND ANGLE OF ATTACK COMBINATIONS FOR THE
C   SAME GEOMETRY MAY BE CALCULATED BY REPEATING THIS CARD WITH THE
C   DESIRED VALUES.
C
C   A VALUE OF MACH=-1. ON THIS CARD SIGNIFIES THE TERMINATION OF THE
C   PRESENT CASE. GEOMETRY CARDS FOR A NEW CASE CAN FOLLOW SUCH A
C   TERMINAL CARD.
C
C   ****
C
COMMON ABC(8),J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS,NRADX(4),NFORX
1(4),NP,NPUDCR,NF,NFINOR,NCAN,NCANUR,DUM(36)
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA,REFB,REFC
1,REFD,REFL,REFX,REFZ
COMMON /HEAD/ TITLE1(8),TITLE2(8)
COMMON /SEG/NSEG,NROW(20),NCOL(20),CUSS(20),SINS(20),BT(20)
COMMON /SCRAT/ BLOCK(7500)
COMMON /NEWCCM/ K1,KWAF,KWAF,KRADX(4),KFURX(4),KRAD,MAX,K4,K5,KF
1(6),KAN(6),KFINOR(6),KANOR(6),KUL,NCPT,LOCPT,XCPT
COMMON /VELCOM/ DUM1(5),EM,PRINT,DUM2(53)
C
C   DIMENSION ABCD(8)
LOGICAL LBC,THK,TAIL
INTEGER THICK,PRINT
LWB=3LLWB
LBC=.FALSE.
THK=.FALSE.
EM=-1.
PRINT=0
NCPT=0
NBODY=0
NWING=0
NTAIL=0
NSEG=0
KUL=0
REFB=1.0
REFC=1.0

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40      READ (9) REFA
        IF (K0.EQ.0) GO TO 50
        READ (5,L5C) REAR,REFB,REFC,REFD,REFL,REFX,REFZ
        IF (REFAR.NE.0.) REFA=REFAR
        IF (REFB.EQ.0.) REF B=1.0
        IF (REFC.EQ.0.) REF C=1.0
        IF (REFD.EQ.0.) REF D=1.0
        IF (REFL.EQ.0.) REFL=1.0
        IF (REFX.EQ.0.) REFX=1.0
        COUNTINUE
50      READ (9) BLCK
        IF (K1.EQ.0) GO TO 60
C       REVISE CHORDWISE PANEL SPACING ON WING AND COMPUTE NEW AIRFOIL
C       ORDINATES
C       CALL OVERLAY (LWB,1,2)
C       REVISE SPANWISE PANEL SPACING ON WING AND COMPUTE NEW PANEL
C       GEOMETRY
C       CALL OVERLAY (LWB,1,3)
C       CONTINUE
60      READ (9) BLCK
        IF (TAIL) GO TO 80
        IF (K2.EQ.0) GC TC 80
        IF (TAIL) GC TC 80
        IF (K2.EQ.0) GC TC 80
        IF (K2.EQ.0) GC TC 80
        IF (KRAUX(1).LE.21) GO TC 70
        WRITE (6,190)
        CALL EXIT
        COUNTINUE
70      REVISE BODY (FUSELAGE) MERIDIAN LINE SPACING
C       CALL OVERLAY (LWB,1,4)
C       REVISE AXIAL PANEL SPACING ON BODY (FUSELAGE) AND COMPUTE NEW
C       PANEL GEOMETRY
C       CALL OVERLAY (LWB,1,5)
C       GO TO 130

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```

80 CONTINUE
READ (19) BLOCK
IF (K4.EQ.0) GO TO 90
C REVISE CHORDWISE PANEL SPACING ON FIN (VERTICAL TAIL) AND COMPUTE
C NEW AIRFIELD ORDINATES
C CALL OVERLAY (LNB,1,6)
C REVISE SPANWISE PANEL SPACING ON FIN (VERTICAL TAIL) AND COMPUTE
C NEW PANEL GEOMETRY
C CALL OVERLAY (LNB,1,7)
C CONTINUE
READ (9) BLOCK
IF (K5.EQ.0) GO TO 100
C REVISE CHORDWISE PANEL SPACING ON CANARD (HORIZONTAL TAIL) AND
C COMPUTE NEW AIRFCIL ORDINATES
C CALL OVERLAY (LNB,1,6)
C REVISE SPANWISE PANEL SPACING ON CANARD (HORIZONTAL TAIL) AND
C COMPUTE NEW PANEL GEOMETRY
C CALL OVERLAY (LNB,1,7)
C CONTINUE
IF (KOL.LE.20) GC TO 120
WRITE (6,180)
CALL EXIT
IF (K2.EQ.0) GC TO 130
REWIND 9
TAIL=.FALSE.-
READ (9) REFA
READ (9) BLOCK
GO TO 60
CONTINUE
IF (KOL.GT.20) GO TO 110
REWIND 9
RETURN

```

B9030
B9040
B9050
B9060
B9070
B9080
B9090
B9100
B9110-

C

140 FORMAT (8A10)
150 FORMAT (10F7.0)
160 FORMAT (1H1,8A10)
170 FORMAT (24I3)
180 FORMAT (1H0,56HERROR - WING AND TAIL HAVE MORE THAN 20 COLUMNS OF P
1ANELS)
190 FORMAT (1H0,46HERROR - BODY HAS MORE THAN 20 COLUMNS OF PANELS)
END

```

C          SUBROUTINE PANEL (IP, IQ, J, K, L, NP, API)          C 10
C          CALCULATE PANEL GEOMETRY (BASED ON THE HYPERSONIC ARBITRARY BODY    C 20
C          PROGRAM OF A. E. GENTRY)                                         C 30
C
C          COMMON /POINT/ XPT(600),YPT(600),ZPT(600),THET(600),XG(   C 40
C 130,20),YC(30,20),ZC(30,20)                                         C 50
C          COMMON /SCRAT/ BLOCK(6900),ZU(30,20)                           C 60
C          DIMENSION XIN(4), YIN(4), ZIN(4), XI(4), ETA(4)           C 70
C          REAL NX,NY,NZ                                              C 80
C
C          REORDER THE PANEL CORNER POINTS TO CORRESPOND TO GENTRY CONVENTION C 90
C
C          EPS=1.0E-06                                                 C 100
C
C          J1=J-1                                                       C 110
C          K1=K-1                                                       C 120
C
C          XIN(1)=XC(J1,K1)                                         C 130
C          XIN(2)=XC(J,K1)                                         C 140
C          XIN(3)=XC(J,K)                                         C 150
C          XIN(4)=XC(J1,K)                                         C 160
C          YIN(1)=YC(J1,K1)                                         C 170
C          YIN(2)=YC(J,K1)                                         C 180
C          YIN(3)=YC(J,K)                                         C 190
C          YIN(4)=YC(J1,K)                                         C 200
C
C          IF (L.EQ.1) GO TO 10                                     C 210
C          ZIN(1)=ZC(J1,K1)                                         C 220
C          ZIN(2)=ZC(J,K1)                                         C 230
C          ZIN(3)=ZC(J,K)                                         C 240
C          ZIN(4)=ZC(J1,K)                                         C 250
C
C          GO TO 20                                              C 260
C
C          ZIN(1)=ZU(J1,K1)                                         C 270
C          ZIN(2)=ZU(J,K1)                                         C 280
C          ZIN(3)=ZU(J,K)                                         C 290
C          ZIN(4)=ZU(J1,K)                                         C 300
C
C          CONTINUE                                              C 310
C
C          FORM DIAGONAL VECTORS                               C 320
C
C          T1X=XIN(3)-XIN(1)                                         C 330
C          T2X=XIN(4)-XIN(2)                                         C 340
C          IF (IP.EQ.1) T2X=-T2X                                         C 350
C
C          T1Y=YIN(3)-YIN(1)                                         C 360
C
C          C 370
C          C 380
C          C 390
C          C 400
C          C 410
C          C 420

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T2Y=YIN(4)-YIN(2) C 430
IF (IP.EQ.1) T2Y=-T2Y
T1Z=ZIN(3)-ZIN(1) C 440
T2Z=ZIN(4)-ZIN(2) C 450
IF (IP.EQ.1) T2Z=-T2Z C 460
C C FORM VECTOR CROSS PRODUCT, N = T2 X T1 C 470
C C
NX=T2Y*T1Z-T1Y*T2Z C 480
NY=T1X*T1Z-T2X*T1Z C 490
NZ=T2X*T1Y-T1X*T2Y C 500
IF (ABS(NX)*LE.EPS) NX=0. C 510
IF (ABS(NY)*LE.EPS) NY=0. C 520
IF (ABS(NZ)*LE.EPS) NZ=0. C 530
VN=SQRT(NX*NX+NY*NY+NZ*NZ) C 540
IF (VN.EQ.0.) GO TO 30 C 550
C C FORM UNIT NORMAL VECTOR C 560
VND=1./VN C 570
NX=NX*VND C 580
NY=NY*VND C 590
NZ=NZ*VND C 600
C C COMPUTE AVERAGE POINT C 610
AVX=0.25*(XIN(1)+XIN(2)+XIN(3)+XIN(4)) C 620
AVY=0.25*(YIN(1)+YIN(2)+YIN(3)+YIN(4)) C 630
AVZ=0.25*(ZIN(1)+ZIN(2)+ZIN(3)+ZIN(4)) C 640
C C COMPUTE PROJECTION DISTANCE C 650
D=NX*(AVX-XIN(1))+NY*(AVY-YIN(1))+NZ*(AVZ-ZIN(1)) C 660
PD=ABS(D) C 670
T=SQRT(T1X*T1X+T1Y*T1Y+T1Z*T1Z) C 680
IF (T.EC.0.0) GO TO 40 C 690
TD=1./T C 700
T1X=T1X*TD C 710
T1Y=T1Y*TD C 720
T1Z=T1Z*TD C 730
C C
30 D=NX*(AVX-XIN(1))+NY*(AVY-YIN(1))+NZ*(AVZ-ZIN(1))
PD=ABS(D) C 740
T=SQRT(T1X*T1X+T1Y*T1Y+T1Z*T1Z) C 750
IF (T.EC.0.0) GO TO 40 C 760
C C
TD=1./T C 770
T1X=T1X*TD C 780
T1Y=T1Y*TD C 790
T1Z=T1Z*TD C 800
C C
40 T2X=NY*T1Z-NZ*T1Y C 810
T2Y=NZ*T1X-NX*T1Z C 820
T2Z=NX*T1Y-NY*T1X C 830
C C

```

40

```

C   COMPUTE COORDINATES OF CORNER POINTS IN REFERENCE COORDINATE
C   SYSTEM                                         C 860
C   C
C   DO 50 N=1,4                                C 870
C     XPA=XIN(N)+NX*D                         C 880
C     YPA=YIN(N)+NY*D                         C 890
C     ZPA=ZIN(N)+NZ*D                         C 900
C
C     D=-D                                     C 910
C
C     XDIF=XPA-AVX                            C 920
C     YDIF=YPA-AVY                            C 930
C     ZDIF=ZPA-AVZ                            C 940
C
C   TRANSFORM CORNER POINT TO ELEMENT COORDINATE SYSTEM (XI,ETA)
C   WITH AVERAGE POINT AS ORIGIN               C 950
C
C   XI(N)=T1X*XDIF+T1Y*YDIF+T1Z*ZDIF      C 960
C   ETA(N)=T2X*XDIF+T2Y*YDIF+T2Z*ZDIF      C 970
C
C   COMPUTE CENTROID                           C 980
C
C   ETACK=ETA(2)-ETA(4)
C   IF (ETACK.NE.0.0) GO TO 60
C   XI0=0.0
C   GO TO 70
C   XI0=(XI(4)*(ETA(1)-ETA(2))+XI(2)*(ETA(4)-ETA(1)))/(3.*ETACK)
C   ETAO=-ETA(1)/3.
C
C   OBTAIN CORNER POINTS IN SYSTEM WITH CENTROID AS ORIGIN
C
C   XI(1)=XI(1)-XI0
C   XI(2)=XI(2)-XI0
C   XI(3)=XI(3)-XI0
C   XI(4)=XI(4)-XI0
C   ETA(1)=ETA(1)-ETAO
C   ETA(2)=ETA(2)-ETAO
C   ETA(3)=ETA(3)-ETAO
C   ETA(4)=ETA(4)-ETAO
C
C   TRANSFORM CENTROID TO REFERENCE COORDINATE SYSTEM
C
C   XPT(NP)=AVX+T1X*X10+T2X*ETAO             C 1240
C   YPT(NP)=AVY+T1Y*X10+T2Y*ETAO             C 1250
C
C   C
C   C

```

```

ZPT(NP)=AVZ+T1Z*X10+T2Z*ETAO
C COMPUTE PANEL INCIDENCE AND INCLINATION ANGLE
C
C   DELTA(NP)=0.
C   THET(NP)=0.
C   RN=SQRT(NY*NY+NZ*NZ)
C   IF (L.EQ.0) GO TO 80
C   SL=-1.0
C   IF (L.EQ.2) SL=1.0
C   IF (NX.NE.0.) DELTA(NP)=ATAN2(SL*NX,RN)
C   SP=FLOAT(1-2*IP)
C   IF (NY.NE.0.) THET(NP)=ATAN2(SP*NY,-SP*NZ)
C   GO TO 90
C   IF (NX.NE.0.) DELTA(NP)=ATAN2(-NX,RN)
C   IF (NY.NE.0.) THET(NP)=ATAN2(-NY,NZ)
C   CONTINUE
C
C   COMPUTE PANEL AREA
C
C   AP=0.5*(XI(3)-XI(1))*ETACK
C   IF (IP.EQ.1) AP=-AP
C   RETURN
C
C   END
C1290
C1300
C1310
C1320
C1330
C1340
C1350
C1360
C1370
C1380
C1390
C1400
C1410
C1420
C1430
C1440
C1450
C1460
C1470
C1480
C1490
C1500
C1510
C1520-

```

```

D 10
D 20
D 30
D 40
D 50
D 60
D 70
D 80
D 90
D 100
D 110
D 120
D 130
D 140
D 150
D 160
D 170
D 180
D 190
D 200
D 210
D 220
D 230
D 240
D 250
D 260
D 270
D 280
D 290
D 300
D 310
D 320
D 330
D 340
D 350
D 360
D 370
D 380
D 390
D 400
D 410
D 420

SUBROUTINE SCAMP4 (X,Y,N,NOA,NDB,DA,DB,C,S,M)
C
C   GIVEN A SET OF N POINTS WHOSE ABSISSAE FORM A STRICTLY MONOTONIC
C   SEQUENCE, AND GIVEN A FIRST OR SECOND DERIVATIVE AT X(1) AND A
C   FIRST OR SECOND DERIVATIVE AT X(N), TO FIND THE SMOOTHEST POSSIBLE
C   CURVE PASSING RIGOROUSLY THROUGH THE GIVEN POINTS, SATISFYING THE
C   SPECIFIED BOUNDARY CONDITIONS, AND POSSESSING CONTINUOUS FIRST AND
C   SECOND DERIVATIVES. THE CRITERION OF SMOOTHNESS IS THE
C   MINIMIZATION OF THE INTEGRAL OF THE SQUARE OF THE SECOND
C   DERIVATIVE, AND THE CUBIC FOUND IS ACCORDINGLY A CHAIN OF CUBICS,
C   I.E., A SEPARATE CUBIC ON EACH INTERVAL (X(I),X(I+1))
C
C   DIMENSION C(4,1), S(1), X(1), Y(1), Z(4)
C
L=1
KK=1
D1=CA
D2=CB
IF (M-12) 20,10,20
KK=2
IF (NCA+1) 30,40,50
D1=DERIV2(X,Y,X)
GO TO 50
D1=DERIV1(X,Y,1)
NA=IABS(NCA)
IF (NCB+1) 60,70,80
D2=DERIV2(X(N-3),Y(N-3),X(N))
GO TO 80
D2=DERIV1(X(N-2),Y(N-2),3)
NB=IABS(NDB)
CALL CCMCU (D1,D2,S,X,Y,L,M,N,NA,NB)
IF (M) 160,90,160
K=N-1
DO 150 J=1,K
CALL CUBIC2 (X(J),Y(J),S(J),Z,M);
IF (M-1) 100,110,100
M=10C+J+N
GO TO 160
GO TO 160
110 DO 130 I=1,4
120 DO 130 I=1,4
130 C(I,J)=Z(I)
GO TO 150
L=7*j
140

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```
C(L-6,1)=X(J)
C(L-5,1)=X(J+1)
C(L-4,1)=3.0
C(L-3,1)=Z(1)
C(L-2,1)=Z(2)
C(L-1,1)=Z(3)
C(L,1)=Z(4)
CONTINUE
      M=0
      RETURN
      END
```

150
160

```
D 430
D 440
D 450
D 460
D 470
D 480
D 490
D 500
D 510
D 520
D 530-
```

SUBROUTINE DERIV (X,Y,N,NDA,DA,FD)
COMPANION TO SUBROUTINE SCAMP4

```
C C FIT A CHAIN OF CUBIC CURVES THROUGH A SET OF N POINTS HAVING  
C C CONTINUOUS FIRST AND SECOND DERIVATIVES AT THE INTERMEDIATE POINTS  
C C AND SPECIFIED FIRST OR SECOND DERIVATIVE AT THE END POINTS  
C C  
COMMON /COEF/ C(4,50),CC(4,50)  
DIMENSION X(1),Y(1),FC(1)  
C FIT CUBIC CHAIN AND GET FIRST DERIVATIVES  
C CALL SCAMP4 (X,Y,N,NDA,-1,DA,0.,C,FD,0)  
RETURN  
END
```

```

FUNCTION DERIV1 (X1,Y1,N)
C COMPANION TO SUBROUTINE SCAMP4
C
C FIND THE FIRST DERIVATIVE OF THE QUADRATIC THROUGH THREE GIVEN
C POINTS AT A SPECIFIED ONE OF THESE POINTS. THIS PROVIDES A GOOD
C APPROXIMATION TO THE SLOPE OF A FUNCTION AT A POINT, PARTICULARLY
C IF THE OTHER TWO POINTS USED ARE NEARBY.
C
DIMENSION X(3), Y(3), X1(3), Y1(3)
EQUIVALENCE (S,K)
DO 10 I=1,3
X(I)=X1(I)
Y(I)=Y1(I)
K=N
10
C FIND COEFFICIENTS OF THE X-SQUARED TERM AND THE X TERM. NO NEED TO
C FIND CONSTANT TERM, AS IT DISAPPEARS UNDER DIFFERENTIATION.
C
E=Y(1)-Y(2)
H=Y(1)-Y(3)
A=X(1)-X(2)
B=X(1)-X(3)
C=A*(X(1)+X(2))
DT=B*(X(1)+X(3))
C3=(B*E-A*H)/(B*C-A*DT)
C2=(E-C3*C)/A
C
C TEST TO SEE WHETHER DERIVATIVE IS WANTED AT ONE OF THE INPUT
C POINTS OR ELSEWHERE
C
K1=IABS(K)
DO 20 I=1,3
IF (K1-I) 20,30,20
CONTINUE
20
GO TO 40
S=X(K1)
30
DERIV1=C2+2.0*C3*S
40
RETURN
END
F 10
F 20
F 30
F 40
F 50
F 60
F 70
F 80
F 90
F 100
F 110
F 120
F 130
F 140
F 150
F 160
F 170
F 180
F 190
F 200
F 210
F 220
F 230
F 240
F 250
F 260
F 270
F 280
F 290
F 300
F 310
F 320
F 330
F 340
F 350
F 360
F 370
F 380
F 390
F 400
F 410-

```

FUNCTION DERIV2 (X,Y,XX)

C COMPANION TO SUBROUTINE SCAMP4

C FIND THE SECOND DERIVATIVE OF THE CUBIC THROUGH FOUR GIVEN POINTS
C AT AN ARBITRARY POINT WHOSE X COORDINATE IS SPECIFIED

```
DIMENSION X(4), Y(4)
DERIV2=0.0
IF (X(4)-X(3)) 10, 70, 10
10   IF (X(4)-X(2)) 20, 70, 20
20   IF (X(4)-X(1)) 30, 70, 30
30   IF (X(3)-X(2)) 40, 70, 40
40   IF (X(3)-X(1)) 50, 70, 50
50   IF (X(2)-X(1)) 60, 70, 60
60   Q41=(Y(4)-Y(1))/(X(4)-X(1))
      Q31=(Y(3)-Y(1))/(X(3)-X(1))
      Q21=(Y(2)-Y(1))/(X(2)-X(1))
      E=(Q31-Q21)/(X(3)-X(2))
      D=((Q41-Q21)/(X(4)-X(2))-E)/(X(4)-X(3))
      C=E-D*(X(3)+X(2)+X(1))
      DERIV2=2.0*(C+3.0*0**XX)
      RETURN
END
```

70

G 10
G 20
G 30
G 40
G 50
G 60
G 70
G 80
G 90
G 100
G 110
G 120
G 130
G 140
G 150
G 160
G 170
G 180
G 190
G 200
G 210
G 220
G 230
G 240
G 250-

```

10      SUBROUTINE CUBIC2 (X,Y,θ,C,J)
20
30      C
40      C COMPANION TO SUBROUTINE SCAMP4
50
60      C
70      C FIT A CUBIC TO TWO POINTS GIVEN THE SLOPE AT EACH POINT
80
90      C
100     C
110     C
120     C
130     C
140     C
150     C
160     C
170     C
180     C
190     C
200     C
210     C
220     C
230     C
240     C

10      X2=X(2)
20      B=X(1)-X2
30      IF (B) 20,10,20
40      J=3
50      GO TO 30
60      CALL OVERFL (J)
70      A=(Y(1)-Y(2))/B
80      E=X(1)+X2
90      C(4)=(D(1)+D(2)-A-A)/B/B
100     C(3)=(A-D(2))/B-C(4)*(E+X2)
110     C(2)=A-E*C(3)-C(4)*(E*X2+X(1)**2)
120     C(1)=Y(2)-X2*(C(2)+X2*(C(3)+X2*C(4)))
130     CALL OVERFL (J)
140     J=3-J
150     RETURN
160
170
180
190
200
210
220
230
240

```

SUBROUTINE COMCU (DA,DB,S,X,Y,L,M,N,NDA,NDB)
C COMPANION TO SUBROUTINE SCAMP4

```

C FIT A COMPOSITE CUBIC THROUGH N POINTS, I. E., A SEPARATE CUBIC
C BETWEEN EACH PAIR OF ADJACENT POINTS, SUCH THAT N-1 CUBICS ARE SO
C DETERMINED THAT EACH MATCHES ITS NEIGHBORS IN FUNCTION VALUE AND
C IN THE FIRST AND SECOND DERIVATIVES.

C COMMON /COEF/ C(50),D(50),E(50),DUM(250)
C DIMENSION S(1), X(1), Y(1)

K=N-1
KUE=0
IF (N-2) 10,20,60
10 N=-1
GO TO 180
20 IF (NDA-1) 50,30,50
30 IF (NDB-1) 50,40,50
40 S(1)=DA
S(2)=DB
50 N=0
GO TO 180
KUE=1
60 N=0
E(1)=0.0
C(N)=0.0
IF (NDA-1) 70,70,80
70 D(1)=1.0
C(1)=0.0
S(1)=DA
GO TO 90
80 D(1)=4.0
C(1)=2.0
S(1)=6.0*(Y(2)-Y(1))/(X(2)-X(1))-DA*(X(2)-X(1))
90 IF (KUE) 120,100,120
100 DO 110 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
110 I=110 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
120 I=120 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
130 I=130 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
140 I=140 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
150 I=150 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
160 I=160 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
170 I=170 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
180 I=180 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
190 I=190 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
200 I=200 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
210 I=210 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
220 I=220 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
230 I=230 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
240 I=240 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
250 I=250 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
260 I=260 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
270 I=270 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
280 I=280 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
290 I=290 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
300 I=300 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
310 I=310 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
320 I=320 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
330 I=330 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
340 I=340 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
350 I=350 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
360 I=360 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
370 I=370 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
380 I=380 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
390 I=390 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
400 I=400 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
410 I=410 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V
420 I=420 I=2,K
U=X(I)-X(I-1)
V=X(I+1)-X(E)
C(I)=U
D(I)=2.0*(U+V)
E(I)=V

```

```

110      S(I)=3.0/(U*V)*(U*U*(Y(I+1)-Y(I))+V*V*(Y(I)-Y(I-1)))
120      IF (NDB=1) 130,130,140
130      E(N)=0.0
          D(N)=1.0
          S(N)=DB
140      GO TO 150
          E(N)=2.0
          D(N)=4.0
          S(N)=6.0*(Y(N)-Y(N-1))/(X(N)-X(N-1))+DB*(X(N)-X(N-1))
150      C(I)=C(I)/D(I)
          S(I)=S(I)/D(I)
          DO 160 I=2,N
          F=D(I)-C(I-1)*E(I)
          C(I)=C(I)/F
          S(I)=(S(I)-S(I-1)*E(I))/F
160      DO 170 J=1,K
          I=N-J
          S(I)=S(I)-S(I+1)*C(I)
170      RETURN
180      END
          I 430
          I 440
          I 450
          I 460
          I 470
          I 480
          I 490
          I 500
          I 510
          I 520
          I 530
          I 540
          I 550
          I 560
          I 570
          I 580
          I 590
          I 600
          I 610
          I 620-

```

OVERLAY(LWB,1,1)
PROGRAM CONFIG

C INPUT AND INITIALIZE CONFIGURATION DESCRIPTION (BASED ON PROGRAM
C START OF NASA TMX-2074)
C
COMMON ABC(8),J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,NFUS,NRADX(4),NFORX
1(4),NP,NPODOR,NF,NFINOR,NCAN,NCANOR,J2TEST,NW,NC,DUM(33)
COMMEN / SCRAT/ BLOCK(7500)
C
DIMENSION ABCD(8), XAF(30), WAFORG(20,4), WAFORD(20,3,30), TZORD(2
10,30), WAFOR(20,30), XFUS(30,4), ZFUS(30,4), FUSARD(30,4), FUSRAD(2
30,4), SFUS(30,30,8), PODORG(9,31), XPOD(9,30), PODORD(9,30),
3(9,30), FINORG(6,2,4), XFIN(6,10), FINORD(6,2,10), FINX2(6,2,10),
4FINX3(6,2,10), FINOR(6,10), FINCR(6,10), CANORG(6,2,4), XCAN(6,10)
5, CANORD(6,2,10), CANOR(6,2,10), CANORX(6,2,10), CANORD(6,10), CAN
6CR(6,10)
C
EQUIVALENCE (BLOCK,XAF), (BLOCK(31),WAFORG), (BLOCK(111),WAFORD),
1(BLOCK(1911),TZORD), (BLOCK(2511),WAFOR), (BLOCK,XFUS), (BLOCK(121
2),ZFUS), (BLOCK(241),FUSARD), (BLOCK(361),FUSRAD), (BLOCK(241),SFU
3S), (BLOCK,PODORG), (BLOCK(28),XPOD), (BLOCK(298),PODORD), (BLOCK(241),SFU
4568), XPOD(1), (BLOCK,FINORG), (BLOCK(49),FINI), (BLOCK(109),FINORD)
5, (BLOCK(229),FINX2), (BLOCK(349),FINX3), (BLOCK(469),FINQR), (BLOCK
6CK(529),FINCR), (BLOCK,GANORG), (BLOCK(49),XCAN), (BLOCK(109),CANO
7RD), (BLOCK(229),CANOR1), (BLOCK(349),CANORX), (BLOCK(469),CANOR),
8 (BLOCK(529),CANCR)
C
INTEGERT PLOT
DATA NAN2/24/
DATA P.I./3.14159265/
C
REWIND 9
C
REFERENCE AREA
C
REFA=1.0
IF (J0.EQ.0) GO TO 10
READ (15,470) ABCD
DECODE (17,480,ABCD) REF A
10 WRITE (9) REF A
C

```

C WING
C
      IF (J1.EQ.0) GO TO 160
      N=IABS(NWAFOR)
      NREC=(N+9)/10
      I1=-9
      I2=0
      DO 20 NN=1,NREC
      READ (5,470) ABCD
      I1=I1+10
      I2=I2+10
      DECODE (70,480,ABCD) (XAF(I1),I=I1,I2)

      CONTINUE
      DO 30 I=1,NWAF
      READ (5,470) ABCD
      DECODE (28,480,ABCD) (WAFORG(I,J),J=1,4)
      CONTINUE

 20   C J1 = -1 INDICATES UNCAMBERED WING DATA
      C
      IF (J1.LT.0) GO TO 60
      DO 50 NN=1,NWAF
      I1=-9
      I2=0
      DO 40 NI=1,NREC
      READ (5,470) ABCD
      I1=I1+10
      I2=I2+10
      DECODE (70,480,ABCD) (TZORD(NN,I),I=I1,I2)

      CONTINUE
      DO 70 K=1,N
      TZORD(I,K)=0.
      L=1
      80   C
      NWAFOR POSITIVE INDICATES SYMMETRICAL ORDINATES
      C NWAFOR NEGATIVE INDICATES UPPER AND LOWER ORDINATES ARE GIVEN
      C
      IF (NWAFOR.LT.0) L=2
      DO 100 NN=1,NWAF
      DO 100 K=1,L

```

```

11=-9          J 860
12=C          J 870
00 90 N1=1,NREC J 880
READ (5,470) ABCD
11=11+10      J 890
12=12+10      J 900
J 910
DECODE (70,480,ABCD) (WAFORD(NN,K,I),I=11,12)
90 CONTINUE    J 920
CONTINUE    J 930
100 DO 110 NN=1,NWAF J 940
DO 110 K=1,N J 950
WAFOR(NN,K)=WAFORD(NN,1,K)
IF (L.EQ.1) GO TO 110 J 960
J 970
WAFOR(NN,K)=(WAFORD(NN,1,K)-WAFORD(NN,2,K))/2.
J 980
TZORD(NN,K)=(WAFORD(NN,1,K)+WAFORD(NN,2,K))/2.+TZORD(NN,K) J 990
J 1000
J 1010
CONTINUE
IF (NWAFOR.LT.0) GO TO 130 J 1020
J 1030
DO 120 NN=1,NWAF J 1040
DO 120 K=1,N J 1050
WAFORD(NN,2,K)=WAFORD(NN,1,K)
J 1060
J 1070
J 1080
J 1090
J 1100
J 1110
J 1120
J 1130
J 1140
J 1150
J 1160
J 1170
J 1180
J 1190
J 1200
J 1210
J 1220
J 1230
J 1240
J 1250
J 1260
J 1270
J 1280
110 CONTINUE
120 NWAFOR=1ABS(NWAFOR)
NW=NWAFOR
J1=1ABS(J1)
C
C CHANGE WING TO ACTUAL UNITS
C
DO 150 I=1,NWAF
E=.01*WAFORG(I,4)
E3=WAFORG(I,3)
DO 140 J=1,NWAFOR
WAFORD(I,1,J)=E*WAFORD(I,1,J)+E3*TZORD(I,J)
WAFORD(I,2,J)=-E*WAFORD(I,2,J)+E3+TZORD(I,J)
WAFORD(I,3,J)=WAFORG(I,1)+E*XAF(J)
140 CONTINUE
150
160 WRITE (9) BLOCK
C
C FUSELAGE (BODY)
C
IF (J2.EQ.0) GO TO 290
J2TEST=3
C

```

```

C J2 = -1 AND J6 = -1 INDICATE CIRCULAR FUSELAGE SYMMETRICAL WITH
C THE XY-PLANE J1290
C IF (J2.EQ.-1.AND.J6.EQ.-1) J2TEST=1 J1300
C J2 = -1 AND J6 = 0 INDICATE CIRCULAR CAMBERED FUSELAGE J1310
C IF (J2.EQ.-1.AND.J6.EQ.0) J2TEST=2 J1320
C J6 = 1 INDICATES COMPLETE CONFIGURATION SYMMETRICAL WITH THE
C XY-PLANE J1330
C J6 = 2 INDICATES CIRCULAR CAMBERED FUSELAGE J1340
C J6 = 3 INDICATES ARBITRARY FUSELAGE J1350
C J6 = 4 INDICATES CIRCULAR FUSELAGE SYMMETRICAL WITH THE
C XY-PLANE J1360
C J6 = 5 INDICATES CIRCULAR FUSELAGE SYMMETRICAL WITH THE
C XY-PLANE J1370
C J6 = 6 INDICATES CIRCULAR FUSELAGE SYMMETRICAL WITH THE
C XY-PLANE J1380
C J6 = 7 INDICATES CIRCULAR FUSELAGE SYMMETRICAL WITH THE
C XY-PLANE J1390
C J6 = 8 INDICATES CIRCULAR FUSELAGE SYMMETRICAL WITH THE
C XY-PLANE J1400
C IF (J6.EQ.1) J2TEST=1 J1410
C J2=1 J1420
C DO 280 NFU=1,NFUS J1430
C NRAD=NRADX(NFU)
C NFUSOR=NFORX(NFU)
C N=NFUSOR
C NREC=(N+9)/10 J1440
C I1=-9 J1450
C I2=0 J1460
C DO 170 N1=1,NREC J1470
C READ (5,470) ABCD
C I1=I1+10 J1480
C I2=I2+10 J1490
C DECODE (70,480,ABCD) (XFUS(I,NFU), I=I1,I2)
C 170 CONTINUE J1500
C J2TEST = 2 INDICATES CIRCULAR CAMBERED FUSELAGE J1510
C J2TEST = 3 INDICATES ARBITRARY FUSELAGE J1520
C IF (J2TEST.NE.2) GO TO 190 J1530
C I1=-9 J1540
C I2=0 J1550
C DO 180 N1=1,NREC J1560
C READ (5,470) ABCD
C I1=I1+10 J1570
C I2=I2+10 J1580
C DECODE (70,480,ABCD) (ZFUS(I,NFU), I=I1,I2)
C 180 CONTINUE J1590
C GO TO 210 J1600
C 190 DO 200 I=1,N J1610
C J2TEST = 3 INDICATES ARBITRARY FUSELAGE J1620
C J2TEST = 4 INDICATES CIRCULAR FUSELAGE J1630
C J2TEST = 5 INDICATES CIRCULAR CAMBERED FUSELAGE J1640
C J2TEST = 6 INDICATES ARBITRARY FUSELAGE J1650
C J2TEST = 7 INDICATES CIRCULAR FUSELAGE J1660
C J2TEST = 8 INDICATES CIRCULAR CAMBERED FUSELAGE J1670
C J2TEST = 9 INDICATES ARBITRARY FUSELAGE J1680
C J2TEST = 10 INDICATES CIRCULAR FUSELAGE J1690
C J2TEST = 11 INDICATES CIRCULAR CAMBERED FUSELAGE J1700
C J2TEST = 12 INDICATES ARBITRARY FUSELAGE J1710
C J2TEST = 13 INDICATES CIRCULAR FUSELAGE J1720

```

```

C   ZFUS(I,NFU)=0.
200  IF (J2TEST.NE.-3) GO TO 250
     NCARD=(NRAD+9)/10
     DO 240 LN=1,N
     DO 230 K=1,2
     KK=K+(NFU-1)*2
     I1=10
     I1=-9
     I2=0
     DO 220 NN=1,NCARD
     IF (NN.EQ.NCARD) II=MOD(NRAD,10)
     IF (II.EQ.0) II=10
     I1=I1+10
     I2=I2+II
     READ (5,470) ABCD
     DECODE (70,480,ABCD) (SFUS(I,LN,KK),I=I1,I2)
220  CONTINUE
230  CONTINUE
240  CONTINUE
     GO TO 280
250  I1=-9
     I2=0
     DO 260 NI=1,NREC
     READ (5,470) ABCD
     I1=I1+10
     I2=I2+10
     DECODE (70,480,ABCD) (FUSARD(I,NFU),I=I1,I2)
260  CONTINUE
     DO 270 I=1,N
     FUSRD(I,NFU)=SQRT (FUSARD(I,NFU)/PI)
270  CONTINUE
     WRITE (9) BLOCK
280
290
C   POD GEOMETRY DUMMY READ STATEMENTS
C
C   IF (J3.EQ.0) GO TO 330
N=NPODOR
NREC=(N+9)/10
DO 320 NN=1,NP
READ (5,470) ABCD
DO 300 NI=1,NREC
READ (5,470) ABCD
J1730 J1700 J1740 J1750 J1760 J1770 J1780 J1790 J1800 J1810 J1820 J1830 J1840 J1850 J1860 J1870 J1880 J1890 J1900 J1910 J1920 J1930 J1940 J1950 J1960 J1970 J1980 J1990 J2000 J2010 J2020 J2030 J2040 J2050 J2060 J2070 J2080 J2090 J2100 J2110 J2120 J2130 J2140

```

```

300  CONTINUE
      DO 310 NN=1,NREC
        READ (5,470) ABCD
      CONTINUE
310  CONTINUE
320  CONTINUE
330  CONTINUE
C   FINS (VERTICAL TAILS)
C
C     IF (J4.EQ.0) GO TO 380
N=NFINOR
      DO 350 NN=1,NF
        READ (5,470) ABCD
        DECODE (56,480,ABCD) ((FINORG(NN,I,J),J=1,4),I=1,2)
      READ (5,470) ABCD
        DECODE (70,480,ABCD) (XFIN(NN,I),I=1,N)
      READ (5,470) ABCD
        DECODE (70,480,ABCD) (FINORD(NN,1,J),J=1,N)
      DO 340 J=1,N
        FINCR(NN,J)=0.
      FINOR(NN,J)=FINORD(NN,1,J)
340  CONTINUE
350
C   CHANGE FINS TO ACTUAL UNITS
C
C     DO 370 LQ=1,NF
      DO 370 I=1,2
        J=3-I
        E=.01*FINORG(LQ,J,4)
        E2=FINORG(LQ,J,2)
      DO 360 K=1,NFINOR
        EE=FINORD(LQ,1,K)*E
        FINORD(LQ,J,K)=E2+EE
        FINX2(LQ,J,K)=E2-EE
        FINX3(LQ,J,K)=FINORD(LQ,J,1)+E*FIN(LQ,K)
360  CONTINUE
370  WRITE (9) BLOCK
380
C   CANARDS (HORIZONTAL TAILS)
C
C     IF (JS.EQ.0) GO TO 460
N=IABS(INCANOR)
      DO 420 NN=1,NCAN

```

```

READ (5,470) ABCD
DECODE (56,480,ABCD) ((CANORG(NN,I,J),J=1,4),I=1,2)
READ (5,470) ABCD
DECODE (70,480,ABCD) (XCAN(NN,I),I=1,N)
READ (5,470) ABCD
DECODE (70,480,ABCD) (CANORD(NN,1,J),J=1,N)

C NCANOR POSITIVE INDICATES SYMMETRICAL ORDINATES
C NCANOR NEGATIVE INDICATES UPPER AND LOWER ORDINATES ARE GIVEN
C IF (NCANOR.LT.0) GO TO 400
DO 390 J=1,N
CANCR(NN,J)=0.
CANOR(NN,J)=CANORD(NN,1,J)
390 CANOR1(NN,1,J)=CANORD(NN,1,J)
GO TO 420
400 READ (5,470) ABCD
DECODE (70,480,ABCD) (CANOR1(NN,1,J),J=1,N)
DO 410 J=1,N
CANOR(NN,J)=(CANORD(NN,1,J)+CANOR1(NN,1,J))/2.
CANCR(NN,J)=(CANORD(NN,1,J)-CANOR1(NN,1,J))/2.
410 CONTINUE
420
C CHANGE CANARD TO ACTUAL UNITS
C DO 450 NN=1,NCAN
DO 440 K=1,2
I=3-K
E=.01*CANORG(NN,I,4)
E3=CANORG(NN,I,3)
DO 430 J=1,N
CANORD(NN,I,J)=E*CANORD(NN,1,J)+E3
CANOR1(NN,I,J)=-E*CANOR1(NN,1,J)+E3
CANORX(NN,I,J)=CANORG(NN,I,I)+E*XCAN(NN,J)
430 CONTINUE
440 CONTINUE
450 WRITE (9) BLOCK
C REWIND 9
RETURN
C C 470 FORMAT (8A10)

```

480 FORMAT (10F7.0)
END

J3010
J3020-

OVERLAY(LWB,1,2)
PROGRAM NEWORD

C REVISE CHORDWISE PANEL SPACING ON WING AND COMPUTE NEW AIRFOIL
C ORDINATES.

```
C
COMMON ABC(8),J0,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,DUM(51)
COMMON /NEWCCM/ K1,KWAF,KWAFOR,KRDX(4),KFORX(4),KRAD,MAX
COMMON /COEF/ C(4,50),CC(4,50)
COMMON /SCRAT/ BLOCK(7500)

C
DIMENSION XAF(30), WAFORG(20,4), WAFORD(20,3,30), TZORD(20,30), TZ
10R(K(20,30), WAFORK(20,30), DZCDX(20,30), DZTDX(20,30), DZCDXK(20,3
20), WAFOR(20,30), DZTDXK(20,30), TORD(30), ZORD(30), DZC(30), DZT(
330), RHO(20), A(20), B(20), R(20), XAT(3C), XAFK(30)
C
EQUIVALENCE (BLOCK,XAF), (BLOCK(31),WAFORG), (BLOCK(111),WAFORD),
1(BLOCK(1911),TZORD), (BLOCK(2511),WAFOR), (BLOCK(3111),TZORK), (BL
2OCK(3711),WAFORK), (BLOCK(4311),DZCDX), (BLOCK(4911),DZCDXK), (BLO
3CK(5511),DZTDXK), (BLOCK(6111),XAFK), (BLOCK(6141),RHO), (BLOCK(61
461),A), (BLOCK(6181),B), (BLOCK(6201),R), (BLOCK(6221),TORD), (BLO
5CK(6251),ZORD), (BLOCK(6281),DZC), (BLOCK(6311),DZT), (BLOCK(6341)
6,XAT), (BLOCK(6901),DZTDX)
C
SLOP1(I,XI,C)=C(2,I)+XI*(2.*C(3,I)+3.*XI*C(4,I))
SLOP2(I,XI,CC)=CC(2,I)+XI*(2.*CC(3,I)+3.*XI*CC(4,I))
VALU1(I,XI,C)=C(1,I)+XI*(C(2,I)+XI*(C(3,I)+XI*C(4,I)))
VALU2(I,XI,CC)=CC(1,I)+XI*(CC(2,I)+XI*(CC(3,I)+XI*CC(4,I)))
C
IF (K1.EQ.3) READ (5,220) (RHO(N),N=1,NWAF)
IF (KWAFOR.EQ.0) GO TO 10
READ (5,220) (XAFK(K),K=1,KWAFOR)
GO TO 30
10
KWAFCR=NWAFOR
DO 20 K=1,NWAFOR
20
XAFK(K)=XAF(K)
30
CONTINUE
NWAF=NWAFOR-1
C
C CALCULATE CAMBER AND THICKNESS SLOPES
C
DO 210 N=1,NWAF
210
K 10
K 20
K 30
K 40
K 50
K 60
K 70
K 80
K 90
K 100
K 110
K 120
K 130
K 140
K 150
K 160
K 170
K 180
K 190
K 200
K 210
K 220
K 230
K 240
K 250
K 260
K 270
K 280
K 290
K 300
K 310
K 320
K 330
K 340
K 350
K 360
K 370
K 380
K 390
K 400
K 410
K 420
```

```

NDA=-1 K 430
DA=0. K 440
DO 40 L=1,NWAFOR K 450
ZORD(L)=TZORD(N,L) K 460
TORD(L)=WAFOR(N,L) K 470
C K 480
C J1 = -1 INDICATES UNCAMBERED WING K 490
C K 500
IF (J1.LT.0) GO TO 60 K 510
CALL DERIV (XAF,ZORD,NWAFOR,NDA,DA,DZC) K 520
DO 50 L=1,NWAR K 530
DO 50 M=1,4 K 540
CC(M,L)=C(M,L) K 550
GO TO 80 K 560
DO 70 L=1,NWAR K 570
DZC(L)=0. K 580
DO 70 M=1,4 K 590
CC(M,L)=0. K 600
NWA=NWAFOR K 610
IF (K1.LT.3) GO TO 100 K 620
C K 630
C CALCULATE INITIAL SLOPE FOR ROUND LEADING EDGE K 640
C K 650
NWA=NWAR K 660
NDA=0 K 670
R(N)=SQRT(2.*RHO(N)) K 680
SAF2=SQRT(XAF(2)) K 690
SAF3=SQRT(XAF(3)) K 700
CON2=TORD(2)/XAF(2)-R(N)/SAF2 K 710
CON3=TORD(3)/XAF(3)-R(N)/SAF3 K 720
DX=XAF(3)-XAF(2) K 730
A(N)=(CON2*XAF(3)-CON3*XAF(2))/DX K 740
B(N)=(CCN3-CON2)/DX K 750
DA=R(N)/(2.*SAF2)+A(N)+2.*B(N)*XAF(2) K 760
DO 90 L=1,NWAR K 770
XAT(L)=XAF(L+1) K 780
TORD(L)=TORD(L+1) K 790
GO TO 120 K 800
DO 110 L=1,NWA K 810
XAT(L)=XAF(L) K 820
C CALL DERIV (XAT,TORD,NWA,NDA,DA,DZT) K 830
DO 130 L=1,NWAFOR K 840
DZCX(N,L)=DZC(L) K 850

```

```

130  DZTDX(N,L)=DZT(L)
      IF (K1.LT.3) GO TO 150
      DZTDX(N,1)=900.
      DO 140 L=2,NWAFOR
      DZTDX(N,L)=DZT(L-1)
      CONTINUE
      IF (KWAFOR.EQ.0) GO TO 210
      C
      C. INTERPLATE FOR REVISED CAMBER AND THICKNESS ORDINATES AND SLOPES
      C
      TZORK(N,1)=TZORD(N,1)
      DZCDXK(N,1)=DZCDX(N,1)
      WAFORK(N,1)=WAFOR(N,1)
      DZTDXK(N,1)=DZTDX(N,1)
      K1=2
      DO 200 J=1,NWAR
      DO 180 K=K1,KWAFOR
      IF (XAFK(K).GT.XAF(J+1)) GO TO 190
      XJ=XAFK(K)
      TZCRK(N,K)=VALU2(J,XJ,CC)
      DZCDXK(N,K)=SLOP2(J,XJ,CC)
      L=j
      XL=XJ
      IF (K1.LT.3) GO TO 170
      IF (J.GT.1) GO TO 160
      SXJ=SQRT(XJ)
      DZTDXK(N,K)=R(N)/(2.*SXJ)+A(N)+2.*B(N)*SXJ
      WAFORK(N,K)=R(N)*SXJ+XJ*(A(N)+B(N)*SXJ)
      GO TO 180
      XL=XJ-XAF(1)
      L=j-1
      170  WAFORK(N,K)=VALU1(L,XL,C)
            DZTDXK(N,K)=SLOP1(L,XL,C)
      CONTINUE
      K1=K
      180  CONTINUE
      190  RETURN
      200  CONTINUE
      210  CONTINUE
      C
      C. FORMAT (10F7.0)
      END
      K 860
      K 870
      K 880
      K 890
      K 900
      K 910
      K 920
      K 930
      K 940
      K 950
      K 960
      K 970
      K 980
      K 990
      K1000
      K1010
      K1020
      K1030
      K1040
      K1050
      K1060
      K1070
      K1080
      K1090
      K1100
      K1110
      K1120
      K1130
      K1140
      K1150
      K1160
      K1170
      K1180
      K1190
      K1200
      K1210
      K1220
      K1230
      K1240
      K1250
      K1260
      K1270-

```

```

OVERLAY(LWB,1,3)
PROGRAM WNGPAN
C REVISE SPANNISE PANEL SPACING ON WING AND COMPUTE NEW PANEL
C GEOMETRY
C
COMMON ABC(8), J0, JL, J2, J3, J4, J5, J6, NWAF, NWAFOR, DUM(51)
COMMON /PARAM/ NBODY, NWING, NTAIL, LBC, THK, MACH, ALPHA, REFA
COMMON /NEWGMM/ KL, KWAF, KWAFUR, KRADX(4), KFURX(4), KRAD, MAX, KK(26), K
10L, NCPT, LDCPT, XCPT
COMMON /SEG/ NSEG, NRROW(20), NCOL(20), COSS(20), SINS(20), BIE(20), NKT(120),
SPN(20), XLEM(20), BLE(20), ZLEM(20), XS(20), YS(20), LS(20)
COMMON /SCRAT/ BLOCK(7500)
COMMON /POINT/ ARRAY(16000)
COMMON /VELCOM/ DUM1(6), PRINT, DUM2(53)
C
DIMENSION XPT(600), YPT(600), ZPT(600), THET(600), DELTA(600), XC(130,20), YC(30,20), ZC(30,20), ZU(30,20), AREA(600), XE(600), XAF(320), WAFLRG(20,4), WAFLRD(20,3,30), TZCRK(20,30), MAFORK(20,30), EZ3CDX(20,30), DZTDX(20,30), DZCDXK(20,30), DZTDXK(20,30), SLOPE(600)4, XAFK(30), XK(20), YK(20), ZK(20), CK(20), CD(20), BL(20), TH(20), BT(20), CHORD(600)
C
EQUIVALENCE (BLCK,XAF), (BLOCK(31),WAFLRG), (BLOCK(111),WAFORCE),
1(BLUCK(2511),DZTDX), (BLOCK(311),TZCRK), (BLOCK(3711),WAFORC), {B
2LOCK(4311),DZCDX}, (BLOCK(4911),DZCDXK), (BLOCK(5511),DLTDXK), (BL
3OCK(6111),XAFK), (BLOCK(6141),XK), (BLOCK(6161),YK), (BLOCK(6181),
4LK), (BLOCK(6201),CK), (BLUCK(6221),BL), (BLOCK(6261),TH), (BLOCK(
56281),BT), (BLOCK(6301),CHURD), (BLOCK(6901),SLOPE,ZU), (ARRAY,XPT
6), (ARRAY(601),YPT), (ARRAY(1201),ZPT), (ARRAY(1801),THET), (ARRAY
7(2401),DELTA), (ARRAY(3001),XC), (ARRAY(3601),YC), (ARRAY(4201),ZC
8), (ARRAY(4801),AREA), (ARRAY(5401),XE)
C
LOGICAL LBC, THK
INTEGER PRINT
C
XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)
C
EPS=1.0E-6
IF (KWAF.EQ.0) GO TO 10
C
READ INTERMEDIATE SPAN STATIONS
C

```



```

      BTE(NSEG)=B,T(N)
      NWT(NSEG)=0
      70      CUNT INUE
      DU 80 K=KC,KWAF
      IF (YK(K).GE.WAFCRG(M,2)) GO TO 90
      CUNT INUE
      80      K0=K
      C      CALCULATE ORIGINS OF INTERMEDIATE CHORDS
      C      DO 200 K=KI,KO
      XK(K)=XIN(WAFORG(NI,1),WAFORG(NI,2),WAFORG(N,2),YK(K))
      ZK(K)=XIN(WAFORG(NI,3),WAFORG(NI,2),WAFORG(N,2),YK(K))
      CK(K)=XIN(WAFORG(NI,4),WAFORG(NI,2),WAFORG(N,2),YK(K))
      CL=CK(K)/100.
      L=1
      SJ=1.0
      100     CUNT INUE
      C      CALCULATE COORDINATES OF PANEL CORNERS
      C      DO 150 J=1,KWAFOR
      XC(J,K)=XK(K)+CL*XAFK(J)
      YC(J,K)=YK(K)
      ZC(J,K)=ZK(K)
      IF (LBC) GO TO 110
      ZCAM=XIN(TLORK(NI,J),WAFORG(NI,2),TLORK(N,M,J),WAFORG(M,2),YK(K))
      ZTHK=XIN(WAFORK(NI,J),WAFORG(NI,2),WAFORK(M,J),WAFORG(M,2),YK(K))
      ZC(J,K)=ZK(K)+CL*(ZCAM+SJ*ZTHK)
      IF (L.EQ.1) ZU(J,K)=ZC(J,K)
      110
      IF (K.EQ.KI) GO TO 150
      K1=K-1
      NJ=NJ+1
      IF (J.EQ.1) GO TO 150
      J1=J-1
      NC=NC+1
      NP=NP+1
      IP=1
      IF (SJ.LT.0.) IP=0
      IQ=0
      C      CALCULATE PANEL INCLINATIONS AND CENTROIDS ON WING SURFACE
      C

```

```

IF (.NOT. LBC) CALL PANEL (IP, IQ, J, K, L, NP, AP)
AREA(NP)=AP
CHORD(NP)=0.
IF (PRINT.GE.0) GO TO 130
IF (.NOT. LBC.AND.L.EQ.1) GO TO 120
WRITE (6,310) NP, XC(J1,K1), YK(K1), ZC(J1,K1), XC(J,K1),
L11), XC(J1,K), YK(K), ZC(J1,K), XC(J,K), YK(K), ZC(J,K)
GO TO 130
WRITE (6,310) NP, XC(J1,K1), YK(K1), ZU(J1,K1), XC(J,K1),
L11), XC(J1,K), YK(K), ZU(J1,K), XC(J,K), YK(K), ZU(J,K)
CONTINUE
C
C CALCULATE PANEL CONTROL POINTS IN PLANE OF WING
C
CR=XC(J,K1)-XC(J1,K1)
CT=XC(J,K)-XC(J1,K)
RI=(1.+CT/(CR+CT))/3.
RO=1.-RI
XLE=RI*XC(J1,K)+RO*XC(J1,K1)
XTE=RI*XC(J,K)+RO*XC(J,K1)
CHORD(NP)=XTE-XLE
SPN=SQRT((YK(K)-YK(K1))*(YK(K)-YK(K1))+(ZK(K)-ZK(K1))*
L11)
SPNW(K1)=SPN
IF (J.EQ.2) XLEW(K1)=XLE
YLE=RI*YK(K)+RO*YK(K1)
ZLE=RI*ZK(K)+RO*ZK(K1)
IF (J.EQ.2) ZLEW(K1)=ZLE
IF (LBC).GC TO 140
IF (L.EQ.1.AND.J.EQ.KWAFOR) ZTU=LPT(NP)
IF (L.EQ.1.OR.J.NE.KWAFOR) GO TO 150
XS(K1)=XPT(NP)
YS(K1)=YPT(NP)
ZS(K1)=(LPT(NP)+ZTU)*.5
XS(K1)=XTE
YS(K1)=YLE
ZTU=RI*ZU(J,K)+RO*ZU(J,K1)
ZTL=RI*ZC(J,K)+RO*ZC(J,K1)
ZS(K1)=(ZTU+ZTL)/2.
GO TO 150
CONTINUE
XPT(NC)=XLE
XE(NC)=XPT(NC)

```

```

      YPT(NC)=YLE,
      ZPT(NC)=ZLE
C   CALCULATE PANEL AREAS, CHORDS, AND INCLINATION ANGLES
      AREA(NP)=.5*SPN*(CR+CT)
      THET(NC)=TH(N)
C   INTERPOLATE FOR WING CAMBER AND THICKNESS AT PANEL TRAILING EDGES
      DZCDX(K1,J)=XIN(DZCDXK(NI,J),WAFORG(NI,2),DZCDXK(M,J),WAFORG(M,2),
L1720
      L1730
      L1740
      L1750
      L1760
      L1770
      L1780
      L1790
      L1800
      L1810
      L1820
      L1830
      L1840
      L1850
      L1860
      L1870
      L1880
      L1890
      L1900
      L1910
      L1920
      L1930
      L1940
      L1950
      L1960
      L1970
      L1980
      L1990
      L2000
      L2010
      L2020
      L2030
      L2040
      L2050
      L2060
      L2070
      L2080
      L2090
      L2100
      L2110
      L2120
      L2130
      L2140

      DZCDX(K1,J)=XIN(DZCDXK(NI,1),WAFORG(NI,2),DZCDXK(M,1),WAFORG(M,2),
L1720
      L1730
      L1740
      L1750
      L1760
      L1770
      L1780
      L1790
      L1800
      L1810
      L1820
      L1830
      L1840
      L1850
      L1860
      L1870
      L1880
      L1890
      L1900
      L1910
      L1920
      L1930
      L1940
      L1950
      L1960
      L1970
      L1980
      L1990
      L2000
      L2010
      L2020
      L2030
      L2040
      L2050
      L2060
      L2070
      L2080
      L2090
      L2100
      L2110
      L2120
      L2130
      L2140

      DZDX(K1,J)=XIN(DZDXK(NI,J),WAFORG(NI,2),DZDXK(M,J),WAFORG(M,2),
L1720
      L1730
      L1740
      L1750
      L1760
      L1770
      L1780
      L1790
      L1800
      L1810
      L1820
      L1830
      L1840
      L1850
      L1860
      L1870
      L1880
      L1890
      L1900
      L1910
      L1920
      L1930
      L1940
      L1950
      L1960
      L1970
      L1980
      L1990
      L2000
      L2010
      L2020
      L2030
      L2040
      L2050
      L2060
      L2070
      L2080
      L2090
      L2100
      L2110
      L2120
      L2130
      L2140

      DZDX(K1,1)=XIN(DZDXK(NI,1),WAFORG(NI,2),DZDXK(M,1),WAFORG(M,2),
L1720
      L1730
      L1740
      L1750
      L1760
      L1770
      L1780
      L1790
      L1800
      L1810
      L1820
      L1830
      L1840
      L1850
      L1860
      L1870
      L1880
      L1890
      L1900
      L1910
      L1920
      L1930
      L1940
      L1950
      L1960
      L1970
      L1980
      L1990
      L2000
      L2010
      L2020
      L2030
      L2040
      L2050
      L2060
      L2070
      L2080
      L2090
      L2100
      L2110
      L2120
      L2130
      L2140

      DZDX(K1,1)=XIN(DZDXK(NI,1),WAFORG(NI,2),DZDXK(M,1),WAFORG(M,2),
L1720
      L1730
      L1740
      L1750
      L1760
      L1770
      L1780
      L1790
      L1800
      L1810
      L1820
      L1830
      L1840
      L1850
      L1860
      L1870
      L1880
      L1890
      L1900
      L1910
      L1920
      L1930
      L1940
      L1950
      L1960
      L1970
      L1980
      L1990
      L2000
      L2010
      L2020
      L2030
      L2040
      L2050
      L2060
      L2070
      L2080
      L2090
      L2100
      L2110
      L2120
      L2130
      L2140

```

```

C          CALCULATE INITIAL SLOPE FOR ROUND LEADING EDGE AIRFOILS
C
170      NP=NP-J1
           SL_E=-DZTDX(K1,2)
           DU 180 I=2,J1
           SL_E=SLE-(DZTDX(K1,I)+DZTDX(K1,I+1))*CHORD(NPJ+1)/CHORD(NPJ+1)
180      DZTDX(K1,1)=SLE
           NJJ=NJ-J1
           SLOPE(NJJ)=DZTDX(K1,1)
           CONTINUE
200
C          COMPUTE NUMBER OF ROWS AND COLUMNS IN EACH WING SEGMENT
C
           NROWINSEG)=J1
           NCOLINSEG)=K0-K1
           NCPT=NC
           IF (NCPT.GT.600) GO TO 260
           NWING=NP
           NI=M
           KI=KO
           GO TO 220
210      KO=KO+1
           NI=NI+1
           BL(N)=0.
           BT(N)=0.
           TH(N)=0.
           CONTINUE
           IF (PRINT.GE.0) GO TO 250
           WRITE(6,320)
           IF (LBC) WRITE(6,330)
           IF (.NOT.LBC) WRITE(6,340)
           DO 230 NP=1,NCPT
           IF (LBC) WRITE(6,350) NP,XPT(NP),YPT(NP),ZPT(NP),THET(NP),DELTAN
           1P),SLOPE(NP)
           IF (.NOT.LBC) WRITE(6,350) NP,XPT(NP),YPT(NP),ZPT(NP),THET(NP)
           1LTA(NP)
           CONTINUE
           WRITE(6,380)
           WRITE(6,360)
           DO 240 NP=1,NWING
           WRITE(6,370) NP,AREA(NP),CHORD(NP)
           CONTINUE
250

```

```

C      STORE WING GEOMETRY ON TAPE 7
C
      WRITE (7) ARRAY,CHORD,SLOPE
      GO TO 270
      WRITE (6,390)
      CALL EXIT
      RETURN
C
      C
      FORMAT (10F7.0)
      FORMAT (1H1,9X,35HWING PANEL CORNER POINT COORDINATES/10X,86H1 AND
     1 3 INDICATE WING PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAIL
     2ING-EDGE POINTS)
      FORMAT (1H0,5X,5HPANEL,4(8X,1HX,8X,1HY,8X,1HZ)/20X,3(1H1,8X),3(1H2
     1,8X),3(1H3,8X),3(1H4,8X)//)
      FORMAT (1H ,4X,13,4X,12F9.5)
      FORMAT (1H1,1X,48HWING PANEL CONTROL POINTS AND INCLINATION ANGLES
     1)
      FORMAT (1H0,5HPOINT,8X,1HX,10X,1HY,10X,1HZ,10X,5HTHETA,6X,6HCAM&ER
     1,5X,9HTHICKNESS/15X,3(2HCP,9X),10X,5HSLCPE,8X,5HSLOPE//)
      FORMAT (1H0,5HPOINT,8X,1HX,10X,1HY,10X,1HZ,10X,5HTHETA,6X,5HDELTA/
     115X,3(2HCP,9X)//)
      FORMAT (1H ,1X,13,4X,6F11.5)
      FORMAT (1H0,5HPANEL,6X,4HAREA,8X,5HCORNU)
      FORMAT (1H ,1X,13,4X,2F11.5)
      FORMAT (1H1,9X,27HWING PANEL AREAS AND CHORUS)
      FORMAT (51H ERROR - NUMBER OF WING CONTROL POINTS EXCEEDS 600)
      END

```

L2580
L2590
L2600
L2610
L2620
L2630
L2640
L2650
L2660
L2670
L2680
L2690
L2700
L2710
L2720
L2730
L2740
L2750
L2760
L2770
L2780
L2790
L2800
L2810
L2820
L2830
L2840
L2850
L2860-

```

OVERLAY{FLWB,1,4)
PROGRAM NEWRAD
C C REVISE BODY (FUSELAGE) MERIDIAN LINE SPACING
C C COMMON ABC(8),J0,J1,J2,J3,J4,J5,J6,NWAF,NWFOR,NFUS,NRADX(4),NFORX
C C 1(4),DUD(6),J2TEST,DUM(35)
COMMON /NEWCOM/ KL,KWAF,KWAFOR,KRADX(4),KFORX(4),KFUS,MAX
COMMON /SCRAT/ BLOCK(7500)
COMMON /POINT/ ARRAY(4800)
C C DIMENSION XFUS(30,4), ZFUS(30,4), FUSRAD(30,4), SFUS
C C 1(30,30,8), ANSIN(30), ANCOS(30), PHIN(30), XB(30), YB(30)
C C 2,30), ZB(30,30), YF(30), ZF(30)
C C EQUIVALENCE (BLOCK,XFUS), (BLOCK(121),ZFUS), (BLOCK(241),FUSARD),
C C 1(BLOCK(361),FUSRAD), (BLOCK(241),SFUS), (ARRAY,YB), (ARRAY(1801),Z
C C 2B), (ARRAY(3601),XB), (ARRAY(3661),ANSIN), (ARRAY(3691),ANCOS), (A
C C 3RAY(3721),PHIN), (ARRAY(3751),PHIK)
C C LOGICAL NEWPHI
C C XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)
C C NEWPHI=.FALSE.
M=1
KFUS=NFUS
KTEST=0
RADD=1./57.2957795
REWIND 10
DO 110 NFU=1,NFUS
NRAD=NRADX(NFU)
KRAD=KRADX(NFU)
C C J2TEST IS SET IN PROGRAM CONFIG
C C J2TEST = 3 AND KRAD = 0 INDICATE AN ARBITRARY FUSELAGE WITH
C C MERIDIAN LINES DEFINED BY NRAD IN THE GEOMETRY INPUT
C C
IF (J2TEST.EQ.3.AND.KRAD.EQ.0) KTEST=1
IF (KRAD.EQ.0.) KRAD=NRAD
IF (KRAD.GT.20) GO TO 130

```

```

IF (KRAD.LT.0) NEWPHI=.TRUE.
KRAD=IABS(KRAD)
KRADX(NFU)=KRAD
NFUSOR=NFORX(NFU)
FANG=FLOAT(2*(KRAD-1))
DELETE=c•2831.853/FANG
C
C READ NEW MERIDIAN ANGLES
C
IF (NEWPHI) READ (5,160) (PHIK(K),K=1,KRAD)
DO 30 K=1,KRAD
E=FLOAT(K-1)
IF (NEWPHI) GO TO 10
PHIR=E*DELE
GO TO 20
PHIR=PHIK(K)*RADD
PHIK(K)=PHIR
C
J2TEST = 3 INDICATES ARBITRARY FUSELAGE
C
IF (J2TEST.EQ.3) GO TO 30
PHIR4=PHIR+4.712389
ANSIN(K)=SIN(PHIR4)
ANCOSE(K)=COS(PHIR4)
CONTINUE
KK=1*(NFU-1)*2
NF=NFU
K2=KK+1
DO 100 N=1,NFUSOR
IF (N.GT.1) M=M+1
IF (M.GT.60) GO TO 120
XB(N)=XFUS(N,NF)
C
J2TEST = 3 INDICATES ARBITRARY FUSELAGE
C
IF (J2TEST.EQ.3) GO TO 50
RAD=FUSRAD(N,NF)
CAN=ZFUS(N,NF)
C COMPUTE SECTION Y AND Z COORDINATES FOR CIRCULAR BODY (FUSELAGE)
C
DO 40 K=1,KRAD
YB(N,K)=RAD*ANCOSE(K)

```

```

40 ZB(N,K)=RAD*ANSIN(K)+CAN M 860
   GO TO 100 M 870
   CONTINUE M 880
C COMPUTE SECTION Y AND Z ORDINATES FOR NONCIRCULAR BODY (FUSELAGE) M 890
C BY LINEAR INTERPOLATION M 900
C M 910
C KI=2 M 920
C PHI(N)=0. M 930
C YB(N,1)=SFUS(1,N,KK) M 940
C ZB(N,1)=SFUS(1,N,K2) M 950
C YF(1)=YB(N,1) M 960
C ZF(1)=ZB(N,1) M 970
C ZC=(SFUS(1,N,K2)+SFUS(NRAD,N,K2))/2. M 980
C DO 90 NN=2,NRAD M 990
C IF IKTEST.EQ.1) GO TO 80 M1000
C YF(NN)=SFUS(NN,N,KK) M1010
C ZF(NN)=SFUS(NN,N,K2)-ZC M1020
C N1=NN-1 M1030
C IF (YF(NN).EQ.0..AND.ZF(NN).EQ.0.) GO TO 80 M1040
C PHI(N)=ATAN2(YF(NN),-ZF(NN)) M1050
C DO 60 K=KI,KRAD M1060
C IF (PHIK(K).GT.PHIN(NN)) GO TO 70 M1070
C YB(N,K)=XIN(YF(N1),PHIN(N1),YF(NN),PHIN(NN),PHIK(K)) M1080
C ZB(N,K)=XIN(ZF(N1),PHIN(N1),ZF(NN),PHIN(NN),PHIK(K))*ZC M1090
C CONTINUE M1100
C KI=K M1110
C GO TO 90 M1120
C 80 YB(N,NN)=SFUS(NN,N,KK) M1130
C ZB(N,NN)=SFUS(NN,N,K2) M1140
C CONTINUE M1150
C 90 CONTINUE M1160
C 100 MAX=M M1170
C WRITE (10) XB,YB,ZB M1180
C 110 CONTINUE M1190
C GO TO 150 M1200
C 120 WRITE (6,180) M1210
C GO TO 140 M1220
C 130 WRITE (6,170) M1230
C CALL EXIT M1240
C RETURN M1250
C M1260
C M1270
C M1280

```

M1290
M1300
M1310
M1320-
M1320-

160 FORMAT \$10F7.0)
170 FORMAT (1H ,39HERROR - BODY HAS MORE THAN 20 MERIDIANS)
180 FORMAT (1H ,44HERROR - BODY HAS MORE THAN 60 AXIAL STATIONS)
END

OVERLAY(LW8,1,5)
PROGRAM BODPAN

C C REVISE AXIAL SPACING ON BODY (FUSELAGE) AND COMPUTE NEW PANEL
GEOMETRY

```
N 10
N 20
N 30
N 40
N 50
N 60
N 70
N 80
N 90
N 100
N 110
N 120
N 130
N 140
N 150
N 160
N 170
N 180
N 190
N 200
N 210
N 220
N 230
N 240
N 250
N 260
N 270
N 280
N 290
N 300
N 310
N 320
N 330
N 340
N 350
N 360
N 370
N 380
N 390
N 400
N 410
N 420

COMMON DUM(17),NFUS,NRADX(4),NFORX(4),DUD(42)
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /NEWCOM/ KL,KWAFF,KRADFOR,KRADX(4),KFUS,MAX
COMMON /SCRAT/ BLOCK(7500)
COMMON /POINT/ ARRAY(6000)
COMMON /BTHET/ THETA(600)
COMMON /VELCOM/ DUM1(6),PRINT,DUM2(53)

DIMENSION XB(30),YB(30,30),ZB(30,30),XJ(60),AREA(600),XPT(600
1),YPT(600),ZPT(600),THET(600),DELTA(600),XC(30,20),YC(30,20)
2,ZC(30,20),XFUS(30,4)

C EQUIVALENCE (BLOCK,XFUS), (BLOCK(121),YB), (BLOCK(1921),ZB), (BLOC
1K(3721),XB), (ARRAY,XPT), (ARRAY(601),YPT), (ARRAY(1201),ZPT),
2RAY(1801),THET), (ARRAY(2401),DETA), (ARRAY(3001),XC), (ARRAY(360
31),YC), (ARRAY(4201),ZC), (ARRAY(4801),AREA)
INTEGER PRINT

C XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)

C REWIND 10
IF (PRINT.GE.0) GO TO 10
WRITE (6,180)
WRITE (6,190)
CONTINUE
10
C CALCULATE COORDINATES OF PANEL CORNERS

C IP=0
C IQ=0
C J=1
C L=0
NP=0
DO 100 NFU=1,NFUS
JMAX=KFUX(NFU)
NFUSOR=NFORX(NFU)
```

```

N 430
N 440
N 450
N 460
N 470
N 480
N 490
N 500
N 510
N 520
N 530
N 540
N 550
N 560
N 570
N 580
N 590
N 600
N 610
N 620
N 630
N 640
N 650
N 660
N 670
N 680
N 690
N 700
N 710
N 720
N 730
N 740
N 750
N 760
N 770
N 780
N 790
N 800
N 810
N 820
N 830
N 840
N 850

C READ IN NEW AXIAL STATIONS FOR BODY (FUSELAGE)
C
C READ (5,170) (XJ(K),K=1,JMAX)
C
 20  JMAX=NFORX(NFU)
      KFORX(NFU)=JMAX
      DO 30 K=1,JMAX
      XJ(K)=XFUSIK,NFU)
      CONTINUE
      DO 50 K=1,KRAD
      XC(J,K)=XB(1)
      YC(J,K)=YB(1,K)
      ZC(J,K)=ZB(1,K)
      DO 90 JJ=2,JMAX
      J1=J
      J=J+1
      DO 80 M=2,NFUSOR
      M1=M-1
      IF (XB(M).LT.XJ(JJ)) GO TO 80
      DO 70 K=1,KRAD
      XC(J,K)=XJ(JJ)
      YC(J,K)=XIN(YB(M1,K),XB(M1),YB(M,K),XB(M),XJ(JJ))
      ZC(J,K)=XIN(ZB(M1,K),XB(M1),ZB(M,K),XB(M),XJ(JJ))
      IF (K.EQ.1) GO TO 70
      K1=K-1
      NP=NP+1
      C CALCULATE PANEL INCLINATION AND CENTROID
      C
      CALL PANEL (IP,IQ,J,K,L,np,AP)
      C
      IF (PRINT.GE.0) GO TO 60
      WRITE (6,200) NP,XC(J1,K1),YC(J1,K1),ZC(J1,K1),YC(J,K1),Z
      IC(J,K1),XC(J1,K1),YC(J1,K1),ZC(J1,K1),YC(J,K1),ZC(J,K1)
      AREA(NP)=AP
      CONTINUE
      GO TO 90
 30
 40
 50

```

```

80    CONTINUE          N 860
90    CONTINUE          N 870
100   CONTINUE          N 880
      NBODY=NP          N 890
      IF (NBODY.GT.600) GO TO 150
      IF (PRINT.GE.0) GO TO 190
      WRITE (6,210)
      WRITE (6,220)
      DO 110 NP=1,NBODY
      WRITE (6,230) NP,XPT(NP),YPT(NP),ZPT(NP)
      CONTINUE
      WRITE (6,240)
      WRITE (6,250)
      DO 120 NP=1,NBODY
      WRITE (6,230) NP,AREA(NP),DELTAINP),THET(NP)
      130   CONTINUE
      DO 140 NP=1,NBODY
      C
      C   STORE BODY GEOMETRY ON TAPE 7
      C
      140   THETA(NP)=THET(NP)
      WRITE (7) ARRAY
      REWIND 10
      GO TO 160
      150   WRITE (6,260)
      CALL EXIT
      RETURN
      C
      C   FORMAT (10F7.0)
      180   FORMAT (1H1,9X,35HBODY PANEL CORNER POINT COORDINATES/10X,86H) AND
      1 3 INDICATE BODY PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAIL
      2ING-EDGE POINTS)
      190   FORMAT (1HO,5X,5HPANEL,4(8X,1HX,8X,1HY,8X,1HZ)/20X,3(1H1,8X),3(1H2
      1,8X),3(1H3,8X),3(1H4,8X)//)
      200   FORMAT (1H '4X,I3,4X,12F9.5')
      210   FORMAT (1H1,1X,36HBODY PANEL CONTROL POINT COORDINATES)
      220   FORMAT (1HO,5HPOINT,6X,1HX,10X,1HY,10X,1HZ/15X,3(2HCP,9X)//)
      230   FORMAT (1H ,1X,I3,4X,3F11.5)
      240   FORMAT (1H1,4X,39HBODY PANEL AREAS AND INCLINATION ANGLES)
      250   FORMAT (1HO,5HPANEL,6X,6HAREA,7X,5HDELTA,6X,5HTHETA//)
      260   FORMAT (43H ERROR - NUMBER OF BODY PANELS EXCEEDS 600)
      END
      N1270
      N1280-

```

```

0 10
0 20
0 30
0 40
0 50
0 60
0 70
0 80
0 90
0 100
0 110
0 120
0 130
0 140
0 150
0 160
0 170
0 180
0 190
0 200
0 210
0 220
0 230
0 240
0 250
0 260
0 270
0 280
0 290
0 300
0 310
0 320
0 330
0 340
0 350
0 360
0 370
0 380
0 390
0 400
0 410
0 420

OVERLAY(ILWB,1,6)
PROGRAM NUTORD
C REVISE CHORDWISE PANEL SPACING ON FIN (VERTICAL TAIL) OR CANARD
C (HORIZONTAL TAIL) AND COMPUTE NEW AIRFOIL ORDINATES
C
COMMON ABC(8),JO,J1,J2,J3,J4,J5,J6,NWAF,NWAFOR,DUNW(11),NF,NFINOR,
INC,NCANOR,DUM(36)
COMMON /NEWCOM/ K1,KWAFF,KRADX(4),KFORX(4),KRAD,MAX,K4,K5,KF
I(6),KAN(6),KFINOR(6),KANR(6),KOL,NCPT,LOCPT,XCPT
COMMON /COEF/ C(4,50),CC(4,50)
COMMON /SCRAT/ BLOCK(7500)
C
DIMENSION TALORD(6,2,4), XT(6,10), TALORD(6,2,10), TALCR(6,10), TA
1LOR(6,10), TORD(30), ZORD(30), DZC(30), DZT(30), XAF(30), TZORK(20
2,30), WAFORK(20,30), DZCDX(20,30), DZTDX(20,30), DZCDXK(20,30), WA
3FOR(20,30), DZTDXK(20,30), RHO(20), A(20), B(20), R(20), XAT(30),
4XAFK(6,30)
C
EQUIVALENCE (BLOCK,TALORG), (BLOCK(49),XT), (BLOCK(109),TALRD), (
1BLOCK(469),TALOR), (BLOCK(529),TALCR), (BLOCK(589),WAFOR), (BLOCK(
23111),TZORK), (BLOCK(3711),WAFORK), (BLOCK(4311),DZCDX),
(BLOCK(4911),DZCDXK), (BLOCK(5511),DZTDXK), (BLOCK(6111),XAFK),
(BLOCK(1189
311),DZCDX), (BLOCK(5511),DZTDX), (BLOCK(6111),XAFK), (BLOCK(1189
41),DZC), (BLOCK(1219),DZT), (BLOCK(1249),XAT), (BLOCK(1279),RHO), (
5BLOCK(1299),R), (BLOCK(1309),A), (BLOCK(1329),B), (BLOCK(1349),TOR
60), (BLOCK(1379),ZORD), (BLOCK(2511),DZTDX)
C
LOGICAL FIN
C
SLOP1(I, XI, CI)=C(2, I)+XI*(2.*C(3, I)+3.*XI*C(4, I))
SLOP2(I, XI, QC)=CC(2, I)+XI*(2.*CC(3, I)+3.*XI*CC(4, I))
VALU1(I, XI, CI)=C(1, I)+XI*(C(2, I)+XI*C(3, I)+XI*C(4, I))
VALU2(I, XI, CC)=CC(1, I)+XI*(CC(2, I)+XI*(CC(3, I)+XI*CC(4, I)))
C
C NOTE THAT SOME WING VARIABLES ARE REDEFINED IN TERMS OF FIN OR
C CANARD VARIABLES. THEREFORE CARE MUST BE EXERCISED IN FOLLOWING
C THE LOGIC THROUGH THE TAIL SUBROUTINES. IN ESSENCE, THE PROGRAM
C TREATS THE FINS AND CANARDS AS ADDITIONAL WING SEGMENTS.
C
FIN=.FALSE.

```

```

0 430
0 440
0 450
0 460
0 470
0 480
0 490
0 500
0 510
0 520
0 530
0 540
0 550
0 560
0 570
0 580
0 590
0 600
0 610
0 620
0 630
0 640
0 650
0 660
0 670
0 680
0 690
0 700
0 710
0 720
0 730
0 740
0 750
0 760
0 770
0 780
0 790
0 800
0 810
0 820
0 830
0 840
0 850

IF (K4.LE.0) GO TO 10
FIN=.TRUE.
NT=NF
NWAFOR=NFINOR
J1=-1
JL=J4
KL=K4
GO TO 20
IF (K5.LE.0) RETURN
NT=NC
NWAFOR=JABS(NCANOR)
J1=-1
C
C NCANOR NEGATIVE INDICATES UPPER AND LOWER ORDINATES GIVEN
C
IF (NCANOR.LT.0) J1=1
JL=J5
KL=K5
CONTINUE
IF (KL.EQ.3) READ (5,240) (RHO(I),I=1,NT)
C
C CALCULATE REVISED ORDINATES FOR EACH TAIL SEGMENT
DO 230 N=1,NT
KWAFOR=0
IF (FIN.AND.KFINOR(N).GT.0) KWAFOR=KFINOR(N)
IF (.NOT.FIN.AND.KANOR(N).GT.0) KWAFOR=KANOR(N)
IF (KWAFOR.EQ.0) GO TO 30
READ (5,240) (XAFK(N,K),K=1,KWAFOR)
GO TO 50
KWAFOR=NWAFOR
DO 40 K=1,NWAFOR
XAFK(N,K)=XT(N,K)
CONTINUE
NWA=NWAFOR-1
C
C CALCULATE CAMBER AND THICKNESS SLOPES
NDA=-1
DA=0.
DO 60 L=1,NWAFOR
XAF(L)=XT(N,L)
ZORD(L)=TALCR(N,L)
C

```

```

60      TORD(L)=TALDR(N,L)
        IF (J1.LT.0) GO TO 80
        CALL DERIV (XAF,ZORD,NWAFOR,NDA,DA,DZC)
        DO 70 L=1,NWAR
        DO 70 M=1,4
        CC(M,L)=C(M,L)
        GO TO 100
        DO 90 L=1,NWAR
        DO 90 M=1,4
        DZC(L)=0.
        DO 90 M=1,4
        CC(M,L)=0.
        DZC(INWAFOR)=0.
        NWA=NWAFOR
        IF (KL.LT.3.OR.RHO(N).EQ.0.) GO TO 120
C      CALCULATE INITIAL SLOPE FOR ROUND LEADING EDGE
C
        NWA=NWAR
        NDA>0
        RINI=SQRT(2.*RHO(N))
        SAF2=SQRT(XAF(2))
        SAF3=SQRT(XAF(3))
        CON2=TORD(2)/XAF(2)-R(N)/SAF2
        CON3=TORD(3)/XAF(3)-R(N)/SAF3
        DX=XAF(3)-XAF(2)
        A(N)=(CON2*XAF(3)-CON3*XAF(2))/DX
        B(N)=(CON3-CON2)/DX
        DA=R(N)/(2.*SAF2)+A(N)+2.*B(N)*XAF(2)
        DO 110 L=1,NWAR
        XAT(L)=XAF(L+1)
        TORD(L)=TORD(L+1)
        GO TO 140
        DO 130 L=1,NWA
        XAT(L)=XAF(L)
        CALL DERIV (XAT,TORD,NWA,NDA,DA,DZT)
        DO 150 L=1,NWAFOR
        DZC0X(N,L)=DZC(L)
        DZTDX(N,L)=DZT(L)
        IF (KL.LT.3.OR.RHO(N).EQ.0.) GO TO 170
        DZTDX(N,1)=900.
        DO 160 L=2,NWAFOR
        DZTDX(N,L)=DZT(L-1)
        CONTINUE
110
120
130
140
150
160
170

```

```

01290 IF (KWAFOR.EQ.0) GO TO 230
C C INTERPOLATE FOR REVISED CAMBER AND THICKNESS ORDINATES AND SLOPES
C
01300 TZORK(N,1)=TALCR(N,1)
01310 DZCDXK(N,1)=DZCDX(N,1)
01320 WAFORK(N,1)=TALOR(N,1)
01330 DZTOXK(N,1)=DZTOX(N,1)
01340 KI=2
01350 DO 220 J=1,NWAR
01360 DO 200 K=KI,KWAFOR
01370 IF ((XAFK(N,K).GT.XAF(J+1)) GO TO 210
01380 XJ=XAFK(N,K)
01390 TZCRK(N,K)=VALU2(J,XJ,CC)
01400 DZCDXK(N,K)=SLOP2(J,XJ,CC)
01410 L=J
01420 XL=XJ
01430 IF (IKL.LT.3.*QR.*RHO(N).EQ.0.) GO TO 190
01440 IF ((J.GT.1).GO TO 180
01450 SXJ=SQRT(XJ)
01460 DZTOXK(N,K)=R(N)/(2.*SXJ)+A(N)*2.*B(N)*XJ
01470 WAFORK(N,K)=R(N)*SXJ+XJ*(A(N)+B(N))*XJ
01480 GO TO 200
01490 XL=XJ-XAF(1)
01500 180 L=J-1
01510 WAFORK(N,K)=VALU1(L,XL,C)
01520 DZTOXK(N,K)=SLOP1(L,XL,C)
01530 CONTINUE
01540 KI=K
01550 CONTINUE
01560 200 CONTINUE
01570 210 CONTINUE
01580 220 CONTINUE
01590 230 RETURN
01600
01610
01620
01630
01640
C
C
240 FORMAT (10F7.0)
END

```

```

C          OVERLAY(LWB,1,7)
C          PROGRAM TALPAN
C          REVISE SPANNWISE PANEL SPACING ON FIN (VERTICAL TAIL) OR CANARD
C          (HORIZONTAL TAIL) AND COMPUTE NEW PANEL GEOMETRY
C          COMMON ABC(8),J0,JL,J2,J3,J4,J5,J6,NWAF,NWAFOR,DUNW(11),NF,NFINOR,
C          LNK,NCANOR,DUM(36)
C          COMMON /PARAM/ NBUDY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
C          COMMON /NEWCCM/ KL,KWAF,KWAFOR,KRADX(4),KFCRX(4),KRAD,MAX,K4,K5,KF
C          1(6),KAN(6),KFINOR(6),KANUR(6),KOL,ACPT,LOCPT,XCPT
C          COMMON /SEG/ NSEG,NROW(20),NCUL(20),COSS(20),SINS(20),BIE(20),NWT(120),
C          SPNW(20),XLEW(20),BLE(20),ZLEM(20),XS(20),YS(20),LS(20)
C          COMMON /SCRAT/ ELUCK(7500)
C          COMMON /POINT/ ARRAY(16000)
C          COMMON /VELCOM/ DUM1(6),PRINT,DUM2(53)
C
C          DIMENSION XPT(600), YPT(600), ZPT(600), THET(600), DELTA(600), XC(
C          130,20), YC(30,20), ZC(30,20), ZU(30,20), AREA(600),XE(600), TALOR
C          2G(6,2,4), XT(6,10), TALORD(6,2,10), TALCR(6,10), TALOR(6,10), WAFO
C          3RG(12,4), TZORK(20,30), WAFORK(20,30), DZCDX(20,30), DZTDX(20,30),
C          4DZCDXK(20,30), DZTDXK(20,30), SLOPE(600), XAFK(6,30), XK(20),
C          50), ZK(20), CK(20), CD(20), ZY(20), BL(20), TH(20), BT(20), CHORD(6600)
C
C          EQUIVALENCE (BLOCK,TALORG), (BLOCK(49),XT), (BLOCK(109),TALORD), (
C          1BLOCK(469),TALOR), (BLOCK(529),TALCR), (BLOCK(589),ZY), (BLOCK(609),
C          2), XK), (BLOCK(629),YK), (BLOCK(649),ZK), (BLOCK(669),CK), (BLOCK(6
C          389),BL), (BLOCK(709),BT), (BLOCK(729),TH), (BLOCK(2511),DTDX), 1B
C          4LUCK(3111),TZORK), (BLOCK(3711),WAFORK), (BLOCK(4311),DZCDX), (BLO
C          5CK(4911),DZCDXK), (BLOCK(5511),ZTDXK), (BLOCK(6111),XAFK), (BLOCK
C          6(6301),CHORD), (BLOCK(6901),SLUE,ZU), (ARRAY,XPT), (ARRAY(601),YP
C          7T), (ARRAY(1201),ZPT), (ARRAY(1801),THET), (ARRAY(2401),DELTAB), (A
C          8RRAY(3001),XC), (ARRAY(3601),YC), (ARRAY(4201),ZC), (ARRAY(4801),A
C          9REA), (ARRAY(5401),XE)
C
C          LOGICAL LBC,THK,FIN
C          INTEGER PRINT
C
C          XIN(X1,Y1,X2,Y2,Y)=X1+(X2-X1)*(Y-Y1)/(Y2-Y1)

```

C NOTE THAT SOME WING VARIABLES ARE REDEFINED IN TERMS OF FIN OR
 C CANARD VARIABLES. THEREFORE CARE MUST BE EXERCISED IN FOLLOWING
 C THE LOGIC THROUGH THE TAIL SUBROUTINES. IN ESSENCE, THE PROGRAM
 C TREATS THE FINS AND CANARDS AS ADDITIONAL WING SEGMENTS.
 C

```

EPS=1.0E-6          P 430
FIN=.FALSE.          P 440
IF (K4.LE.0) GO TO 10 P 450
FIN=.TRUE.
IF (PRINT.LT.0) WRITE (6,270) P 460
NTAL=NF              P 470
P 480
KK=K4                P 490
KL=K4                P 500
K4=0                 P 510
GO TO 20              P 520
P 530
IF (K5.LE.0) RETURN P 540
P 550
KK=0                 P 560
KL=K5                P 570
P 580
NTAL=NK              P 590
P 600
P 610
IF (PRINT.LT.0) WRITE (6,280) P 620
P 630
CONTINUE             P 640
IF (PRINT.LT.0) WRITE (6,290)
REWIND 7              P 650
P 660
P 670
P 680
P 690
P 700
P 710
P 720
P 730
P 740
P 750
P 760
P 770
P 780
P 790
P 800
P 810
P 820
P 830
P 840
P 850

C READ WING GEOMETRY FROM TAPE 7
C
C READ (7) ARRAY,CHORD,SLOPE
REWIND 7              P 690
P 700
KI=1                 P 710
NI=1                 P 720
NC=NCPT              P 730
NJ=NCPT              P 740
NINIT=NWING           P 750
NP=NWING              P 760
NC1=NC+1              P 770
NP1=NP+1              P 780
P 790
P 800

C CALCULATE PANEL GEOMETRY FOR EACH TAIL SEGMENT
DO 200 NT=1,NTAL
IF (FIN) KWAFF=KF(NT)
IF (.NOT.FIN) KWAFF=KAN(NT)
  
```

```

C      KWAF=IABS(KWAF)
C      IF (KWAF.EQ.0) GO TO 30
C
C      READ INTERMEDIATE SPAN STATIONS
C
30    READ (5,200) (YK(K),K=1,KWAF)
      KWAFOR=NWAFOR
      IF (FIN.AND.KFINOR(NT).GT.0) KWAFOR=KFINOR(NT)
      IF (.NOT.FIN.AND.KANUR(NT).GT.0) KWAFOR=KANUR(NT)
      DO 50 N=1,2
      WAFORG(N,1)=TALORG(NT,N,1)
      IF (KK.GT.0) GO TO 40
      WAFORG(N,2)=TALORG(NT,N,2)
      WAFORG(N,3)=TALORG(NT,N,3)
      GO TO 50
      WAFORG(N,2)=TALORG(NT,N,3)
      WAFORG(N,3)=TALORG(NT,N,2)
      WAFORG(N,4)=TALORG(NT,N,4)
      IF (KWAF.NE.0) GO TO 70
      KWAF=2
      DO 60 K=1,2
      YK(K)=WAFORG(K,2)
      CONTINUE
      N=1
      M=2
      DELY=WAFORG(N+1,2)-WAFORG(N,2)
      IF (DELY.EQ.0.) GO TO 200
      DELX=WAFORG(N+1,1)-WAFORG(N,1)
      DELZ=WAFORG(N+1,3)-WAFORG(N,3)
      DELC=WAFORG(N+1,4)-WAFORG(N,4)
      BL(N)=DELX/DELY
      BT(N)=(UELX+DELC)/DELY
      CD(N)=WAFORG(N,4)
      IF (FIN) TH(N)=ATAN2(DELY,DELL)
      IF (.NOT.FIN) TH(N)=ATAN2(DELL,DELY)
      NSEG=NSEG+1
      SIN(NSSEG)=SIN(TH(N))
      COS(NSSEG)=COS(TH(N))
      BLE(NSSEG)=BL(N)
      BTE(NSSEG)=BT(N)
      NW(NSEG)=1
      IF (FIN) NW(NSSEG)=-1
      IF (.NOT.FIN.AND.KAN(NT).LT.0) NW(NSSEG)=-1
      P 860
      P 870
      P 880
      P 890
      P 900
      P 910
      P 920
      P 930
      P 940
      P 950
      P 960
      P 970
      P 980
      P 990
      P1000
      P1010
      P1020
      P1030
      P1040
      P1050
      P1060
      P1070
      P1080
      P1090
      P1100
      P1110
      P1120
      P1130
      P1140
      P1150
      P1160
      P1170
      P1180
      P1190
      P1200
      P1210
      P1220
      P1230
      P1240
      P1250
      P1260
      P1270
      P1280

```

C CALCULATE ORIGINS OF INTERMEDIATE CHORDS

```

C DO 190 K=KI,KNAF
K1=K-1
L=K+KUL
L1=L-1
XK(K)=XIN(WAFORG(NI,1),WAFORG(NI,2),WAFORG(N,1),WAFORG(N,2),YK(K))
ZK(K)=XIN(WAFORG(NI,3),WAFORG(NI,2),WAFORG(N,3),WAFORG(N,2),YK(K))
CK(K)=XIN(WAFORG(NI,4),WAFORG(NI,2),WAFORG(N,4),WAFORG(N,2),YK(K))
CL=CK(K)/100.
LP=1
SJ=1.0
ZY(K)=LK(K)
IF (FIN) ZK(K)=YK(K)
CONTINUE
30
C CALCULATE COORDINATES OF PANEL CORNERS
DO 140 J=1,KWAFOR
XC(J,L)=XK(K)+CL*XAFK(NT,J)
LC(J,L)=ZK(K)
IF (LBC) GC TO 90
ZCAM=TZORK(NT,J)
ZTHK=WAFORK(NT,J)
ZC(J,L)=ZY(K)+CL*(ZCAM+SJ*ZTHK)
IF (LP.EQ.1) ZU(J,L)=ZC(J,L)
IF (FIN) YK(K)=ZY(K)
YC(J,L)=YK(K)
IF (K.EQ.KI) GC TO 140
NJ=NJ+1
IF (J.EQ.1) GO TO 140
J1=J-1
NC=NC+1
NP=NP+1
IP=1
IF (SJ.LT.0.) IP=0
IQ=0
90
C CALCULATE PANEL INCLINATIONS AND CENTRIDS ON TAIL SURFACE
C IF (.NOT.LBC) CALL PANEL (IP,IQ,J,L,LP,NP,AP)
AREA(NP)=AP
P1290
P1300
P1310
P1320
P1330
P1340
P1350
P1360
P1370
P1380
P1390
P1400
P1410
P1420
P1430
P1440
P1450
P1460
P1470
P1480
P1490
P1500
P1510
P1520
P1530
P1540
P1550
P1560
P1570
P1580
P1590
P1600
P1610
P1620
P1630
P1640
P1650
P1660
P1670
P1680
P1690
P1700
P1710

```

```

CHORD(NP)=0.
IF (PRINT.GE.0) GO TO 110
IF (.NUT.LBC.ANL.LP.EQ.1) GO TO 100
WRITE (6,300) NP,XC(J1,L1),YC(K1),ZC(J1,L1),XC(J,L1),YC(K1),ZC(J,L)
11),XC(J1,L),YC(K),ZC(J1,L),XC(J,L),ZC(J,L)
GO TO 110
100 WRITE (6,300) NP,XC(J1,L1),YC(K1),ZU(J1,L1),XC(J,L1),YC(K1),ZU(J,L)
11),XC(J1,L),YC(K),ZU(J1,L),XC(J,L),ZU(J,L)
P1720 P1730 P1740 P1750 P1760 P1770 P1780 P1790 P1800 P1810 P1820 P1830 P1840 P1850 P1860 P1870 P1880 P1890 P1900 P1910 P1920 P1930 P1940 P1950 P1960 P1970 P1980 P1990 P2000 P2010 P2020 P2030 P2040 P2050 P2060 P2070 P2080 P2090 P2100 P2110 P2120 P2130 P2140

C CALCULATE PANEL CENTERCL PCINTS IN PLANE OF TAIL
C
110 CONTINUE
CR=XC(J,L1)-XC(J1,L1)
CT=XC(J,L)-XC(J1,L)
RI=(1.+CT/(CR+CT))/3.
RO=1.-RI
XLE=RI*XC(J1,L)+RO*XC(J1,L1)
XTE=RI*XC(J,L)+RC*XC(J,L1)
CHORD(NP)=XTE-XLE
SPN=SQRT((YK(K)-YK(K1))*(YK(K)-YK(K1))+(ZK(K)-ZK(K1))*(ZK(K)-ZK(K1)))
SPNW(LL)=SPN
IF (J.EQ.2) XLEM(LL)=XLE
YLE=RI*YK(K)+RO*YK(K1)
ZLE=RI*ZK(K)+RO*ZK(K1)
IF (J.EQ.2) ZLEW(K1)=ZLE
IF (LBC) GO TO 120
IF (LP.EQ.1.OR.J.NE.KWAFOR/2) GU TO 140
XS(K1)=XTE
YS(K1)=YLE
ZTU=RI*ZU(J,L)+RC*ZU(J,L1)
ZTL=RI*ZC(J,L)+RC*ZC(J,L1)
ZS(K1)=(ZTU+ZTL)/2.
GO TO 140
120 CONTINUE
XPT(NC)=XLE
XE(NC)=XPT(NC)
YPT(NC)=YLE
ZPT(NC)=ZLE
C CALCULATE PANEL AREAS, CHORDS, AND INCLINATION ANGLES
C
AREA(NP)=.5*SPN*(CR+CT)

```

```

C      THET(NC)=TH(N)
C      CALCULATE CAMBER AND THICKNESS SLOPES
C
KJ=KI+1
IF (K.GT.KJ) GO TO 130
DZCDX(INT,J)=DZCDXK(INT,J)
IF (J.EQ.2) DZCCK(INT,1)=DZCDXK(INT,1)
DZTDX(INT,J)=DZTDXK(INT,J)
DELTAINC)=DZCDX(INT,J1)
SLOPE(NJ)=DZTDX(INT,J)
IF (J.NE.KWAFOR) GO TO 140
NC=NC+1
XPNT(NC)=XTE-EPS
XE(NC)=XPNT(NC)
YPT(NC)=YPT(NC-1)
ZPT(NC)=ZPT(NC-1)
ZTE=ZPT(NC)
DELTACNC)=DZCDXK(INT,J)
THET(NC)=TH(N)
CONTINUE
IF (LBC) GO TO 150
IF (SJ.LT.0.) GO TO 150
SJ=-1.0
LP=2
GO TO 80
150 CONTINUE
IF (K.EQ.KI) GO TO 190
IF (K.GT.KJ) GO TO 190
IF (.NOT.LBC) GO TO 190
IF (KL.EQ.3) GO TO 160
P2150
P2160
P2170
P2180
P2190
P2200
P2210
P2220
P2230
P2240
P2250
P2260
P2270
P2280
P2290
P2300
P2310
P2320
P2330
P2340
P2350
P2360
P2370
P2380
P2390
P2400
P2410
P2420
P2430
P2440
P2450
P2460
P2470
P2480
P2490
P2500
P2510
P2520
P2530
P2540
P2550
P2560
P2570
NPJ=NP-J1
SLE=2.*ZTE/CHORD(NPJ+1)-DZTDX(INT,2)
DO 170 I=2,J1
SLE=SLE-(DZTDX(INT,I)+DZTDX(INT,I+1))*CHORD(NPJ+I)/CHORD(NPJ+1)
170

```

```

P2580 DZTDX(INT,i)=SLE
P2590 NJ=NJ-J1
P2600 SLOPE(NJJ)=DZTDX(INT,1)
P2610 CONTINUE
P2620
P2630 COMPUTE NUMBER OF ROWS AND COLUMNS IN EACH TAIL SEGMENT
P2640
P2650
P2660 NROW(NSEG)=J1
P2670 NCCL(NSEG)=KWAFF-KI
P2680 IF (NCPT>NP) GO TO 240
P2690 NWING=NP
P2700 NTAIL=NWING-NINIT
P2710 KCL=KOL+KWAFF
P2720
P2730 CONTINUE
P2740 IF (PRINT.GE.0) GO TO 230
P2750 IF (.FIN) WRITE (6,310)
P2760 IF (.NOT.FIN) WRITE (6,320)
P2770 IF (LBC) WRITE (6,330)
P2780 IF (.NOT.LBC) WRITE (6,340)
P2790 DO 210 NP=NC1,NCPT
P2800 IF (LBC) WRITE (6,350) NP,XPT(NP),YPT(NP),ZPT(NP),THET(NP),DELTA(N
1P),SLOPE(NP)
P2810 IF (.NOT.LBC) WRITE (6,350) NP,XPT(NP),YPT(NP),ZPT(NP),THET(NP),CE
P2820 ILTA(NP)
P2830
P2840 CONTINUE
P2850 IF (.FIN) WRITE (6,390)
P2860 IF (.NOT.FIN) WRITE (6,380)
P2870 WRITE (6,360)
P2880 DO 220 NP=NP1,NWING
P2890 WRITE (6,370) NP,AREA(NP),CHORD(NP)
P2900 CONTINUE
P2910
P2920
P2930
P2940
P2950
P2960
P2970
P2980
P2990
P3000
C STORE WING AND TAIL GEOMETRY ON TAPE 7
C
C WRITE (7) ARRAY,CHORD,SLOPE
C GO TU 250
C WRITE (6,400)
C CALL EXIT
C RETURN
C
C FORMAT (10F7.0)

```

270 FORMAT (1H1,9X,35H FIN PANEL CORNER POINT COORDINATES/10X,8H 1 AN
 10 3 INDICATE FIN PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAIL
 2ING-EDGE POINTS) P3010
 280 FORMAT (1H1,9X,35HTAIL PANEL CORNER POINT COORDINATES/10X,8H1 AND
 1 3 INDICATE TAIL PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAIL
 2ING-EDGE POINTS) P3020
 290 FORMAT (1H0,5X,5HPANEL,4(8X,1HX,8X,1HY,8X,1HZ)/20X,3(1H1,8X),3(1H2
 1,8X),3(1H3,8X),3(1H4,8X))/) P3030
 300 FORMAT (1H ,4X,13,4X,12F9.5) P3040
 310 FORMAT (1H1,1X,48H FIN PANEL CNTRL PCINTS AND INCLINATION ANGLES
 1) P3050
 320 FORMAT (1H1,1X,48HTAIL PANEL CNTRL PCINTS AND INCLINATION ANGLES
 1) P3060
 330 FORMAT (1H0,5HPJINT,8X,1HX,10X,1HY,10X,1HZ,10X,5HTHETA,6X,6HCAMBER
 1,5X,9HTHICKNESS/15X,3(2HCP,9X),10X,5HSLCPE,6X,5HSLOPE//) P3070
 340 FORMAT (1H0,5HPOINT,8X,1HX,10X,1HY,10X,1HZ,10X,5HTHETA,6X,5HDELTA/
 115X,3(2HCP,9X)//) P3080
 350 FORMAT (1H ,1X,13,4X,6F11.5) P3090
 360 FORMAT (1H0,5HPANEL,6X,4HAREA,8X,5HCHORD) P3100
 370 FORMAT (1H ,1X,13,4X,2F11.5) P3110
 380 FORMAT (1H1,9X,27HTAIL PANEL AREAS AND CHORDS) P3120
 390 FORMAT (1H1,9X,27H FIN PANEL AREAS AND CHORDS) P3130
 400 FORMAT (65H ERROR - NUMBER OF WING AND TAIL PANEL CONTROL POINTS E
 1XCEEDS 600) P3140
 ENQ P3150
 P3160
 P3170
 P3180
 P3190
 P3200
 P3210
 P3220
 P3230
 P3240
 P3250-

OVERLAY(LWB,2,0)
PROGRAM VELCMP

```

C   COMPUTE THE VELOCITY COMPONENTS (U,V,W) AT THE PANEL CONTROL
C   POINTS AND FORM THE AERODYNAMIC INFLUENCE COEFFICIENT MATRICES
C
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,PRINT,NMTHK,NMBLOK,
INROW(20),NBBLOK,NBROW(30)
COMMON /NEWCOM/ K1,KWAFOR,KRADX(4),KFUS,MAX,KOUH(28)
1,LOCPT(20),XCPT(20)
COMMON /SCRAT/ BLOCK(7500)
COMMON /POINT/ ARRAY(6000)
COMMON /SEG/ NSEG,NROW(20),NCOL(20),COSS(20),SINS(20),BT(20),DUM(6
10),BL(20)
COMMON /MATCOM/ MATIN
C
DIMENSION XLE(600), XPT(600), DEL(600), COSTH(600)
DIMENSION XBT(600), YBT(600), ZBT(600), YPT(600)
DIMENSION CHORD(600), DZTDX(600), IT(600), D(60,60), DELTA(600)
DIMENSION DELT(600)
C
EQUIVALENCE (BLOCK,DEL), (BLOCK(601),COSTH)
EQUIVALENCE (BLOCK(3901),XBT), (BLOCK(4501),YBT), (BLOCK(5101),ZBT)
1) EQUIVALENCE (BLOCK(5701),IT), (BLOCK(6301),CHORD), (BLOCK(6901),DZ
ITDX), (ARRAY(2401),DELT), (ARRAY(4801),DELT1)
EQUIVALENCE (ARRAY,XPT), (ARRAY(1801),D), (ARRAY(5401),XLE)
EQUIVALENCE (ARRAY(601),YPT), (ARRAY(1201),ZPT)
C
REAL MACH
LOGICAL LBC,SUB,SUPLE,SUPTE
LWB=3LLW8
MATIN=0
NMAX=60
EPS=1.0E-6
C
C   READ IN MACH NUMBER AND ANGLE OF ATTACK
C
READ (5,240) MACH,ALPHA
IF (MACH.LT.0..OR.MACH.EQ.EM) RETURN
SUB=MACH.LT.1.0

```

```

BETA=SQRT(ABS(MACH*MACH-1.0))
BETAD=1./BETA
REWIND 8
REWIND 9
REWIND 10
NPOINT=NCPT
NPANEL=NBODY+NWING
IF (NPANEL.EQ.0) RETURN
REWIND 7
IF (NWING.EQ.0) GO TO 70
NCPT=NWING

C C COMPUTE SIZES OF WING DIAGONAL BLOCKS
C C
C C COMPUTE CHORDWISE CONTROL POINT LOCATIONS ON WING
C C (PLANAR BOUNDARY CONDITION OPTION ONLY)
C C
IF (.NOT.LBC) GO TO 10
READ (7) CHORD,DZDX
IF (NBODY.EQ.0) GO TO 10
READ (7) ARRAY
WRITE (10) ARRAY
REWIND 10
REWIND 7
READ (7) ARRAY,CHORD,DZDX
REWIND 7
10
I=0
J=0
K=0
NWBLOCK=0
DO 50 N=1,NSEG
NC=NCOL(N)
NR=NROW(N)
NR1=NR+1
NWBLOCK=NWBLOK+NC
BLE=BL(N)*BETAD
SUPLE=.FALSE.
IF (.NOT.SUB.AND.ABS(BLE).LT.1.0) SUPLE=.TRUE.
BTE=BT(N)*BETAD
SUPTE=.FALSE.
IF (.NOT.SUB.AND.ABS(BTE).LT.1.0) SUPTE=.TRUE.
DO 50 M=1,NC
      Q 430
      Q 440
      Q 450
      Q 460
      Q 470
      Q 480
      Q 490
      Q 500
      Q 510
      Q 520
      Q 530
      Q 540
      Q 550
      Q 560
      Q 570
      Q 580
      Q 590
      Q 600
      Q 610
      Q 620
      Q 630
      Q 640
      Q 650
      Q 660
      Q 670
      Q 680
      Q 690
      Q 700
      Q 710
      Q 720
      Q 730
      Q 740
      Q 750
      Q 760
      Q 770
      Q 780
      Q 790
      Q 800
      Q 810
      Q 820
      Q 830
      Q 840
      Q 850

```

```

K=K+1
NK=NR
IF (LBC.AND.SUPT) NK=NR1
IF (.NOT.LBC) NK=2*NR
NWROW(K)=NK
DO 50 L=1,NR1
I=I+1
IT(I)=0
IF (L.LT.NR1) GO TO 30
IF (LBC) XPT(I)=XLE(I)
IF (SUPT) GO TO 20
IT(I)=I
J=J+1
IF (LBC) DEL(J)=DELT(A(I))
IF (LBC) COSTH(J)=COSS(N)
GO TO 50
IF (.NOT.LBC) GO TO 50
J=J+1
XF=-.50
XS=XF
LOCPT(N)=0
IF (.NOT.SUPT) GO TO 40
LOCPT(N)=1
IF (SUPT) XS=EPS
XF=XS*FLOAT(NR1-L)/FLOAT(NR1-1)
XPT(I)=XF*XLE(I+1)*(1.-XF)*XLE(I)
DEL(J)=XF*DELT(A(I+1)+(1.-XF)*DELT(A(I))
COSTH(J)=COSS(N)
XCP(N)=XS
CONTINUE
IF (LBC) NCPT=I
IF (.NOT.LBC) GO TO 60
REWIND 11
WRITE (11) DEL,COSTH
REWIND 11
WRITE (7) ARRAY,CHORD,DZTOX
IF (NBODY.EQ.0) GO TO 6C
READ (10) ARRAY
WRITE (7) ARRAY
REWIND 7
REWIND 10
NPINT=NCPT
CONTINUE

```

```

EM=MACH Q1290
NPART=1 Q1300
CALL SECOND (TIME) Q1310
WRITE (6,260) NPART,TIME Q1320
IF (INWING.NE.0) READ (7) ARRAY,CHORD,DZTDX Q1330
IF (NBODY.EQ.0) GO TO 100 Q1340
READ (7) ARRAY Q1350
DO 80 N=1,NBODY Q1360
XBT(N)=XPT(N) Q1370
YBT(N)=YPT(N) Q1380
ZBT(N)=ZPT(N) Q1390
NPOINT=NBODY Q1400
IF (NPART.EQ.1) WRITE (6,270) Q1410
C Q1420
C COMPUTE VELOCITY COMPONENTS INDUCED BY BODY PANELS Q1430
C CALL OVERLAY (LMB,2,1) Q1440
C GO TO 110 Q1450
100 IF (NPART.EQ.1.OR.NPART.EQ.4) WRITE (6,300) Q1460
C Q1470
C COMPUTE VELOCITY COMPONENTS INDUCED BY WING PANELS Q1480
C Q1490
C IF (LBC) CALL OVERLAY (LMB,2,2) Q1500
C IF (.NOT.LBC) CALL OVERLAY (LMB,2,3) Q1510
C GO TO 110 Q1520
C CONTINUE Q1530
C IF (INWING.EQ.0.AND.NBODY.NE.0) GO TO 160 Q1540
C IF (NBODY.EQ.0.AND.NWING.NE.0) GO TO 160 Q1550
C Q1560
C SET UP INDICES FOR MATRIX PARTITIONS Q1570
C Q1580
C Q1590
C NPART=NPART+1 Q1600
C IF (NPART.GT.4) GO TO 150 Q1610
C CALL SECOND (TIME) Q1620
C WRITE (6,260) NPART,TIME Q1630
C IF (NPART.EQ.2) WRITE (6,280) Q1640
C IF (NPART.EQ.3) WRITE (6,290) Q1650
C REWIND 7 Q1660
C READ (7) ARRAY,CHORD,DZTDX Q1670
C IF (NPART.GT.2) GO TO 130 Q1680
C READ (7) (ARRAY(I),I=1,2400),(DELT(I),I=1,600) Q1690
C IF (NPART.GT.2) GO TO 90 Q1700
C NPOINT=NBODY Q1710

```

```

GO TO 100
NPOINT=NCPT
IF (NPART.EQ.4) GO TO 100
READ (7) ARRAY
DO 140 N=1,NBODY
XBT(N)=XPT(N)
YBT(N)=YPT(N)
ZBT(N)=ZPT(N)
REWIND 7
GO TO 120
READ (7) ARRAY
REWIND 8
REWIND 9
REWIND 10
MATIN=1
C
C          WRITE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX ON TAPE 7
C
IF (NBODY.EQ.0) GO TO 190
NBBLOK=1
NBROW(1)=NBODY
IF (NBODY.LE.NMAX) GO TO 190
NBBLOK=0
DO 180 KF=1,KFUS
NR=KRADX(KF)-1
NC=KFORX(KF)-1
DO 180 NN=1,NC
NBBLOK=NBBLOK+1
NBROW(NBBLOK)=NR
DO 170 M=1, NR
READ (10) (D(M,N),N=1, NR)
WRITE (7) D
IF (NWING.EQ.0) GO TO 220
IF (NWING.LE.NMAX) GO TO 220
DO 210 NW=1,NWBLOK
NR=NWROW(NW)
DO 200 M=1, NR
READ (10) (D(M,N),N=1, NR)
WRITE (7) D
GO TO 230
NWBLCK=1
NWROW(1)=NWING
REWIND 7
200
210
220
230

```

```
REWIND 10
CALL SECOND (TIME)
WRITE (6,250) TIME
RETURN
C
C
240  FORMAT (10F7.0)
250  FORMAT (1H0,6H TIME =F10.5)
260  FORMAT (1H1,11H PARTITION =I3,2X,6H TIME =F10.5)
270  FORMAT (1H ,25H INFLUENCE OF BODY ON BODY)
280  FORMAT (1H ,25H INFLUENCE OF WING ON BODY)
290  FORMAT (1H ,25H INFLUENCE OF BODY ON WING)
300  FORMAT (1H ,25H INFLUENCE OF WING ON WING)
END
Q2150
Q2160
Q2170
Q2180
Q2190
Q2200
Q2210
Q2220
Q2230
Q2240
Q2250
Q2260
Q2270
Q2280-
```

```

      R 10
      R 20
      R 30
      R 40
      R 50
      R 60
      R 70
      R 80
      R 90
      R 100

SUBROUTINE TRAP (XT,YT,SUM,NT)
C   EVALUATE AN INTEGRAL BY THE TRAPEZOIDAL RULE.
C
DIMENSION XT(1), YT(1)
SUM=0.
DO 10 I=2,NT
SUM=SUM+.5*(XT(I)-XT(I-1))*(YT(I)+YT(I-1))
RETURN
END
10

```

OVERLAY(ILWB,2,1)
PROGRAM BODVEL

C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT SPECIFIED
C CONTROL POINTS BY THE BODY PANELS
C INDUCED AT SPECIFIED CONTROL POINTS BY THE BODY PANELS

```
S 10
S 20
S 30
S 40
S 50
S 60
S 70
S 80
S 90
S 100
S 110
S 120
S 130
S 140
S 150
S 160
S 170
S 180
S 190
S 200
S 210
S 220
S 230
S 240
S 250
S 260
S 270
S 280
S 290
S 300
S 310
S 320
S 330
S 340
S 350
S 360
S 370
S 380
S 390
S 400
S 410
S 420

COMMON /PARAM/ NBODY, NWINL, NPANEL, LBC, THK, MACH, ALPHA, REFA
COMMON /VELCCM/ NPOINT, NPART, IMAX, JMAX, NMAX, EX, PRINT, NWTHK
COMMON /NEWCOM/ K1, KWAF, KWAFUR, KRADX(4), KFORX(4), KFUS, MAX
COMMON /SCRAT/ UB(600), VBI(600), WB(600), VI(600), WI(600), AN(600), DN(
160), DUM(240), XBT(600), YBT(600), ZBT(600), IT(600), CD(600)
COMMON /POINT/ XPT(600), YPT(600), ZPT(600), THET(600), DELTA(600), XC(
130, 20), YC(30, 20), ZC(30, 20), DELTI(600)
COMMON /BODCOM/ EM, DA, CX, XCOR(4), YCOR(4), ZCOR(4), XI, YI, ZI, XJ, ZJ
COMMON /BTHET/ THETA(600)

C
REAL MACH
INTEGER PRINT
EM=MACH
JMAX=MAX
IT=0

C
C I IS THE INDEX OF THE CCNTRAL POINT
C J IS THE INDEX OF THE INFLUENCING PANEL
C
DO 90 I=1,NPOINT
ISKIP=IT(I)
IF (LBC.AND..I.EQ.ISKIP.AND..NPART.EQ.3) GO TO 90
II=II+1
SINTI=SIN(THET(II))
COSTI=COS(THET(II))
XPTI=XPT(II)
YPTI=YPT(II)
ZPTI=ZPT(II)
IF (NPART.EQ.1) DI=TAN(DELTAI(1))
IF (LBC.AND..NPART.EQ.3) DI=0.
IF (.NOT.LBC.AND..NPART.EQ.3) DI=TAN(DELTI(1))
DO 10 J=1,NBODY
UB(J)=0.
VI(J)=0.
WI(J)=0.
10
```

```

J=0          S 430
J2=0         S 440
L=0          S 450
DO 50 KF=1,KFUS
NROW=KRADX(KF)-1
NCOL=KFORX(KF)-1
DO 40 NC=1,NCOL
L=L+1
J1=1+J2
J2=J1+NROW-1
DO 30 N=1,NROW
J=J+1
DA=TAN(DELTA(J))
COST=COS(THETA(J))
SINT=SIN(THETA(J))
XW=SINT*COSTI
XX=COST*SINTI
XY=COST*COSTI
XZ=SINT*SINTI
SINTR=XW-XX
SIATL=XW+XX
COSTR=XY+XZ
COSTL=XY-XZ
N1=N+1
XC1=XC(L,N1)
YC1=YC(L,N1)
ZC1=ZC(L,N1)

```

C CALCULATION OF PANEL CORNER POINTS IN PANEL COORDINATE SYSTEM

```

XCOR(1)=0
YCOR(1)=0
ZCOR(1)=0
XCOR(2)=XC(L+1,N+1)-XC1
XCOR(3)=0
XCOR(4)=XCOR(2)
DO 20 K=2,4
L1=L+1
N1=N+1
IF (K.GE.3) N1=N
IF (K.EQ.3) L1=L
DELY=YC(L1,N1)-YC1
DELZ=ZC(L1,N1)-ZC1

```

```

20      YCOR(K)=DELY*COST+DELZ*SINT
      ZCOR(K)=DELZ*COST-DELY*SINT
      CX=XCOR(12)
C      CALCULATION OF CONTROL POINT IN PANEL COORDINATE SYSTEM
C      XI=XPT1-XC1
C      DY=YPT1-YC1
C      DZ=ZPT1-ZC1
C      YI=DY*COST+DZ*SINT
C      ZI=DZ*COST-DY*SINT
      XJ=XBT(J)-XC1
      DYJ=YBT(J)-YC1
      DZJ=ZBT(J)-ZC1
      ZJ=DZJ*COST-DYJ*SINT
C      CALCULATE VELOCITY COMPONENTS INDUCED BY CONSTANT SOURCE
C      DISTRIBUTION PANELS
C      CALL SORPAN (UR,VR,WR)
C      DY=-YPT1-YC1
C      VI=DY*COST+DZ*SINT
C      ZI=DZ*COST-DY*SINT
      CALL SORPAN (UL,VL,WL)
C      CALCULATE VELOCITY COMPONENTS IN ORIGINAL COORDINATE SYSTEM
C      UB(J)=UL+UR+UB(J)
      VI(J)=VR*COSTR-MR*SINTR-VL*COSTL+WL*SINTL+VI(J)
      WI(J)=VR*SINTR+VL*SINTL+WR*COSTR+WL*COSTL+WI(J)
      VB(J)=VI(J)*COSTI-WI(J)*SINTI
      WB(J)=WI(J)*COSTI+VI(J)*SINTI
      AN(J)=WI(J)-UB(J)*DI
      IF (NPART.GT.1) GO TO 30
      IF (NBODY.LE.NMAX) GO TO 30
      IF (II.LT.J1.OR.II.GT.J2) GO TO 30
      JS1=J1
      JS2=J2
      NS=NROW
      CONTINUE
      CONTINUE
      CONTINUE
      JMAX=L

```

30
40
50

```

      IF (NBODY.LE.NMAX.OR.NPART.GT.1) GO TO 70
C
C   STORE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX IN DN ARRAY
C
      DO 60 J=1,NBODY
        IF (J.LT.JS1.OR.J.GT.JS2) GO TO 60
        K=J-JS1+1
        DN(K)=AN(J)
        AN(J)=0.
60    CONTINUE
        WRITE (10) (DN(J), J=1, NS)
        CONTINUE
        IF (IABS(PRINT).LT.4) GO TO 80
        WRITE (6,140) I
        WRITE (6,100) NBODY
        WRITE (6,130) (UB(J), J=1,NBODY)
        WRITE(6,6) (VB(J), J=1,NBODY)
        WRITE(6,6) (WB(J), J=1,NBODY)
        WRITE (6,110) NBODY
        WRITE (6,130) (AN(J), J=1,NBODY)
        IF (NBODY.GT.NMAX.AND.NPART.EQ.1) WRITE (6,120) NS
        IF (NBODY.GT.NMAX.AND.NPART.EQ.1) WRITE (6,130) (DN(J), J=1,NS)
        WRITE (8) (UB(J),VB(J),WB(J), J=1,NBODY)
        WRITE (9) (AN(J), J=1,NBODY)
80    CONTINUE
        RETURN
C
C
      100 FORMAT (2X,10HUB(J),J=1,,13)
      110 FORMAT (2X,10HAN(J),J=1,,13)
      120 FORMAT (2X,10HDN(J),J=1,,13)
      130 FORMAT (1H0,10F10.5)
      140 FORMAT (1H0,22HAERODYNAMIC MATRIX, I=1,3)
END

```

SUBROUTINE SORPAN (UPM,VPM,WPM)

```

C   COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT A SPECIFIED
C   CONTROL POINT BY A CONSTANT SOURCE DISTRIBUTION ON A
C   QUADRILATERAL PANEL HAVING LONGITUDINAL TAPER AND INCLINED AT AN
C   ANGLE DELTA TO THE FREE STREAM DIRECTION
C
C
COMMON /BODCOM/ EM,SA,CX,XC(4),YC(4),ZC(4),XI,YI,ZI,XJ,ZJ
DIMENSION B(4), SX(4), SM(4), DX(4), DY(4), DZ(4), D(4), E(4)
1, G(4), H(4), XPM(4), YMX(4), ZAX(4), AYM(4), RPM2(4)
REAL NUM
      EPS=1.0E-5
      EP2=EPS*EPS
      PI=3.14159265
      BT2=1.-EM*EM
      BTA=SQRT(ABS(BT2))
      BA2=BT2*SA*SA
      TA=1.0+BA2
      IF (TA.LT.0.) GO TO 200
      SM(3)=0.0
      DO 190 I=1,4
      ZC(I)=ZJ-SA*(XJ-XC(I))
      IF (I.LE.2) SM(1)=(YC(2)-YC(1))/CX
      IF (I.GT.2) SM(3)=(YC(4)-YC(3))/CX
      SM(2)=SM(1)
      SM(4)=SM(3)
      SSM=SIGN(1.,SM(1))
      BM2=BT2*SM(1)*SM(1)
      TAM=TA+BM2
      IF (ABS(TAM).LE.EPS) TAM=0.
      SAM=SQRT(ABS(TAM))
      SAMU=1./SAM
      CPM=CX*SAM
      DX(I)=XI-XC(I)
      DY(I)=YI-YC(I)
      DZ(I)=ZI-ZC(I)
      IF (ABS(DX(I)).LE.EPS) DX(I)=0.
      IF (ABS(DY(I)).LE.EPS) DY(I)=0.
      IF (ABS(DZ(I)).LE.EPS) DZ(I)=0.
      RPM2(I)=0.
      10
      20
      30
      40
      50
      60
      70
      80
      90
      100
      110
      120
      130
      140
      150
      160
      170
      180
      190
      200
      210
      220
      230
      240
      250
      260
      270
      280
      290
      300
      310
      320
      330
      340
      350
      360
      370
      380
      390
      400
      410
      420

```

```

DX2=DX(I)*DX(I)
DY2=DY(I)*DY(I)
DZ2=DZ(I)*DZ(I)
DR2=DY2+DZ2
IF (I.EQ.2) R22=DR2
IF (I.EQ.4) R42=DR2
D2=DX2+BT2*DR2
D(I)=0.0
IF (EM.GE.-1..) DXL=DX(L)-BTA*ABS(DL(I))
IF (EM.GE.1..AND.DXL.LT.0..) GO TO 170
IF (U2.GT.0.0) D(I)=SQRT(U2)
XPM(I)=DX(I)+BT2*(SM(I)*DY(I)+SA*DZ(I))
YMX(I)=DY(I)-SM(I)*DX(I)
ZAX(I)=DZ(I)-SA*DX(I)
AYM(I)=SA*DY(I)-SM(I)*DZ(I)
IF (ABS(XPM(I)).LE.EPS) XPM(I)=0.
IF (ABS(YMX(I)).LE.EPS) YMX(I)=0.
IF (ABS(ZAX(I)).LE.EPS) ZAX(I)=0.
IF (ABS(AYM(I)).LE.EPS) AYM(I)=0.
IF (I.LE.2) RPM2(I)=YMX(I)*YMX(I)+ZAX(I)*ZAX(I)+BT2*(AYM(I))*AYM(I)
1)
RPM2(2)=RPM2(1)
IF (I.GT.2) RPM2(3)=YMX(3)*YMX(3)+ZAX(3)*ZAX(3)+BT2*(AYM(3))*AYM(3)
1)
RPM2(4)=RPM2(3)
IF (ABS(RPM2(I)).LE.EP2) RPM2(I)=0.
RPM=SQRT(ABS(RPM2(I)))
IF (RPM.LE.EPS) RPM=0.
DPM=SAM*D(I)
F(I)=0.
DNOM=-DX(I)*YMX(I)-BT2*DZ(I)*AYM(I)
FNUM=D(I)*ZAX(I)
IF (FNUM.EQ.0..AND.DNOM.EQ.0..) GO TO 10
F(I)=ATAN2(FNUM,DNCM)
IF (D(I).EQ.0..) F(I)=F(I)*SIGN(I.,ZAX(I))
10 IF (TAM).LT.90.20
20 IF (EM.GT.1..AND.D(I).EQ.0..) GO TO 70
IF (RPM-EPS).GT.40.30
30 NUM=XPM(I)+DPM
G(I)=ALUG(INUM/(BTA*RPM))*SAMD
GO TO 150
40 SA(I)=SIGN(I.,XPM(I))
IF (EM.LT.1.0) GO TO 50

```

```

IF (I.EQ.1.AND.XPM(1).LT.CPM) GO TO 130
IF (I.EQ.3.AND.XPM(3).LT.CPM) GO TO 140
IF (I.EQ.2) SGN12=SGN(1)*SGN(2)
IF (I.EQ.4) SGN34=SGN(3)*SGN(4)
IF (XPM(I)) 60,70,80
IF (I.EQ.2.AND.SGN12.LT.0.) GO TO 130
IF (I.EQ.4.AND.SGN34.LT.0.) GO TO 140
G(I)=-ALUG(ABS(XPM(I)))*SAMD
GO TO 150
G(I)=0.
GU TO 150
G(I)=ALOG(XPM(I))*SAMD
GO TO 150
G(I)=0.
IF (XPM(I).GT.BTA*RPM) G(I)=D(I)/XPM(I)
GO TO 150
G(I)=0.0
ARG=SIGN(1.,XPM(I))
IF (RPM.NE.0.) ARG=XPM(I)/(BTA*RPM)
IF (ARG.GE.1.) GO TO 150
IF (ARG.LE.-1.) GO TO 110
IF (D(I).GT.0) G(I)=ACCS(ARG)*SAMD
GO TO 150
AM2=SA*SA+SM(I)*SM(I)
TRM1=(SM(I)*DY(I)+SA*DZ(I)+ABS(AYM(I))*SAM)/AM2
IF (DX(I).GT.TRM1) GO TO 120
F(I)=0.
IF (SSM.GT.0.) F(I)=PI*SIGN(1.,ZAX(I))
GO TO 150
IF (SSM*YMX(I).GE.0.) GO TO 150
G(I)=PI*SAMD
GO TO 150
G(I)=500.*SAMD
IF (EM.LT.1.0) G(2)=-G(1)
GO TO 160
G(3)=500.*SAMD
IF (EM.LT.1.0) G(4)=-G(3)
CONTINUE
H(I)=0.
HARG=-BTA*DY(I)
IF (D(I).EQ.0.0.AND.HARG.EQ.0.0) GO TO 180
IF (EM.LT.1.0) H(I)=BTA*.5*ALOG((C(I)+ARG)/(D(I)-HARG))
IF (EM.GT.1.0) H(I)=BTA*ATAN2(D(I),HARG)
T1280

```

```

60 T0 180
F(I)=0.
G(I)=0.
H(I)=0.
AYM(I)=0.
YMX(I)=0.
ZAX(I)=0.
XPM(I)=0.
DPM=0.
RPM=0.
RPM2(2)=RPM2(1)
RPM2(4)=RPM2(3)
E(I)=H(I)+BT2*SM(I)*G(I)
CONTINUE
TAD=1./TA
E14=(E(1)-E(2)-E(3)+E(4))*TAD
F14=(F(1)-F(2)-F(3)+F(4))*TAD
G14=G(1)-G(2)-G(3)+G(4)
R4PI=1.0/(4.*PI)
IF (EM.GT.1.) R4PI=2.*R4PI
UPM=R4PI*(E14/BT2-SA*F14)
VPM=-R4PI*G14
WPM=R4PI*(F14+SA*E14)
RETURN
WRITE (6,210)
CALL EXIT
C
C
200 FORMAT (1HO,35HEODY PANEL SLOPE EXCEEDS MACH ANGLE)
END
T1290
T1300
T1310
T1320
T1330
T1340
T1350
T1360
T1370
T1380
T1390
T1400
T1410
T1420
T1430
T1440
T1450
T1460
T1470
T1480
T1490
T1500
T1510
T1520
T1530
T1540
T1550
T1560
T1570
T1580-

```

**OVERLAY(LW8,2,2)
PROGRAM LINVEL**

```

OVERLAY(LWB,2,2) U 10
PROGRAM LINVEL U 20
C
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT SPECIFIED U 40
C CONTROL POINTS BY SOURCE AND VORTEX DISTRIBUTIONS ON PANELS U 50
C LOCATED IN THE PLANE OF THE WING, FIN (VERTICAL TAIL), OR CANARD U 60
C (HORIZONTAL TAIL) SURFACE U 70
C
C
C COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THIK,MACH,ALPHA,REFA U 80
C /COMPS/ DX,DY,DZ,AL,BL,CL,SUB,BPOS,BCOS,BSIN,ML U 90
C /SEGM/ NSEG,NROW(20),NCOL(20),COSS(20),SINS(20),TT(20),NWT(2 U 100
10)
C
C COMMON /VELCCM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,PRINT,AWTHK U 110
C /POINT/ ARRAY(6000) U 120
C COMMON /SCRAT/ UCOR(30),VCOR(30),WCOR(30),ULOR(30),VLOR(30),WLOR(3 U 130
10),UCOL(30),VCOL(30),WCOL(30),ULOL(30),VLOL(30),WLOL(30),UCIR(30), U 140
2VCIR(30),WCIR(30),ULIR(30),VLIL(30),WLIL(30),UROR(30),RCOR(30),SCOR(30), U 150
3L(30),ULIL(30),VLIL(30),WLIL(30),TCOL(30),SCOL(30),TCOL(30),RLOL(30),SLOL(30),MCI U 160
40),SLOR(30),TLOR(30),RCOL(30),SCIR(30),TCIR(30),RLIR(30),SLIR(30),TLIR(30),RCI U 170
5TLDL(30),RCIR(30),SCIL(30),TCIL(30),RLIL(30),SLIL(30),TLIL(30),AC(600),UC(600) U 180
6L(30),SCIL(30),TCIL(30),SLIL(30),TLIL(30),AC(600),UC(600) U 190
7,VC(600),WC(600),UT(600),VT(600),WT(600),DC(60),DC(600),CHORD(600) U 200
8,DZDX(600) U 210
C
C
C DIMENSION XPT(600), YPT(600), ZPT(600), THET(600), DELTA(600), XC( U 220
130,20), YC(30,20), ZC(30,20), BLE(30), UTOR(30), VTOR(30), WTOR(30 U 230
2), UTOL(30), VTOL(30), WTOL(30), UTIR(30), VTIR(30), WTIR(30), UTI U 240
3L(30), VTIL(30), WTIL(30), ASAVE(30), USAVE(30), VSAVE(30), WSAVE( U 250
430) U 260
C
C EQUIVALENCE (ARRAY,XPT), (ARRAY(601):YPT), (ARRAY(1201):ZPT), (ARR U 270
1AY(1801):THET), (ARRAY(3001):XC), (ARRAY(2401):UTOR), (ARRAY(2431) U 280
2:VTOR), (ARRAY(2461):WTOR), (ARRAY(2491):UTOL), (ARRAY(2521):VTOL) U 290
3, (ARRAY(2551):WTOL), (ARRAY(2581):UTIR), (ARRAY(2611):VTIR), (ARR U 300
4AY(2641):WTIR), (ARRAY(2671):UTIL), (ARRAY(2701):VTIL), (ARRAY(273 U 310
51):WTIL), (ARRAY(3601):YC), (ARRAY(4201):ZC), (ARRAY(4801):DELTA), U 320
6 (ARRAY(2761):USAVE), (ARRAY(2791):VSAVE), (ARRAY(2821):WSAVE), (A U 330
7RAY(2851):ASAVE) U 340
C
C LOGICAL THK,THIK,LBC,SUB,BPOS,BCOS,BSIN,ML,UFLAG U 350
C INTEGER PRINT U 360

```



```

NC1=NC+1
DO 10 L=1,NR1
  USAVE(L)=0.
  VSUME(L)=0.
  WSAVE(L)=0.
  ASAVE(L)=0.
  M1=M2
  IF (N.GT.1.AND.NT.NE.0) M1=M2+1
C
C   IF FLAG IS TRUE, AN ADDITIONAL COLUMN OF VORTEX PANELS
C   EXTENDS FROM THE CENTER LINE TO THE INBOARD EDGE OF THE
C   WING, HORIZONTAL TAIL, OR CANARD
C
C   IF (N.EQ.1.AND.NYC.NE.0) FLAG=.TRUE.
MYC=1
IF (ABS(YC(1,M1)).LE.EPS) MYC=0
IF (N.GT.1.AND.NT.EQ.1.AND.MYC.NE.0) FLAG=.TRUE.
IF (FLAG) THK=.FALSE.
M2=M1+NC
IF (FLAG) M2=M1
C
C   CALCULATE PANEL LEADING EDGE SLOPES
C
C   DO 30 L=1,NR1
  IF (.NOT.FLAG) BLE(L)=(XC(L,M2)-XC(L,M1))/((YC(L,M2)-YC(L,M1))*BET
1A)
  IF (FLAG) BLE(L)=0.
CONTINUE
30
BTE=BLE(NR1)
SUPTE=.FALSE.
IF (.NOT.SUB.AND.ABS(BTE).LT.1.0) SUPTE=.TRUE.
COST=COS(S(N))
IF (FLAG) COST=1.0
SINT=SIN(S(N))
IF (FLAG) SINT=0.
BCOS=BETA*COST
BSIN=BETA*SINT
XW=SINT*COST
XY=COST*SINT
XZ=SINT*SINT
SINTR=XW-XX
SINTL=XW+XX
U 860
U 870
U 880
U 890
U 900
U 910
U 920
U 930
U 940
U 950
U 960
U 970
U 980
U 990
U1000
U1010
U1020
U1030
U1040
U1050
U1060
U1070
U1080
U1090
U1100
U1110
U1120
U1130
U1140
U1150
U1160
U1170
U1180
U1190
U1200
U1210
U1220
U1230
U1240
U1250
U1260
U1270
U1280

```

COSTR=XY+XZ
COSTL=XY-XZ

C C CALCULATE INFLUENCE OF INBOARD CORNERS OF FIRST COLUMN OF PANELS C

DO 80 L=1,NR1
DX=XI-XC(L,M1)
DY=YI-YC(L,M1)
IF (FLAG) DY=YI
DZ=ZI-ZC(L,M1)
AT=AL
BL=BLE(L)
CT=CL
ML=1
IF (L.EQ.NR1) GO TO 40
BL1=BLE(L+1)
AB=BL-BL1
CC=XC(L+1,M1)-XC(L,M1)
CONTINUE
BPOS=BL.GE.0.
AL=AB
BL=ABS(BL)
CL=CC
CALL VORVEL (UCOR(L),VCOR(L),WCOR(L),ULOR(L),VLOR(L),WLOR(L),UTOR(L),
IL),VTOR(L),WTOR(L)
IF (L.EQ.1) GO TO 50
ABA=ABS(AB-AT)
ACL=ABS(CL-CT)
IF (ABA.LE.EPS.AND.ACCL.LE.EPS) GO TO 50
AL=AT
CL=CT
ML=2
CALL VORVEL (X,X,X,X,X,X,UTOR(L),VTOR(L))
AL=AB
CL=CC
ML=1
IF (.NOT.THK) GO TO 60
CALL SORVEL (RCOR(L),SCOR(L),TCOR(L),RLOR(L),SLOR(L),TLOR(L))
DY=-YI-YC(L,M1)
IF (FLAG) DY=-YI
CALL VORVEL (UCOL(L),VCOL(L),WCOL(L),ULOL(L),VLOL(L),WLOL(L),UTOL(L),
IL),VTOL(L),WTOL(L)
IF (L.EQ.1) GO TO 70

40

50

60

```

IF (ABA.LE.EPS.AND.AC1.LE.EPS) GO TO 70
AL=AT
CL=CT
ML=2
U1720
U1730
U1740
U1750
U1760
U1770
U1780
U1790
U1800
U1810
U1820
U1830
U1840
U1850
U1860
U1870
U1880
U1890
U1900
U1910
U1920
U1930
U1940
U1950
U1960
U1970
U1980
U1990
U2000
U2010
U2020
U2030
U2040
U2050
U2060
U2070
U2080
U2090
U2100
U2110
U2120
U2130
U2140

ML=1
IF (.NOT.THK) GO TO 80
CALL VORVEL (X,X,X,X,X,UTOL(L),VTOL(L))
CONTINUE
C
C. CALCULATE INFLUENCE OF CORNERS OF REMAINING COLUMNS OF PANELS
C
IF (.NOT.FLAG) M1=M1+1
DO 280 M=M1,M2
NS=NR
IF (SUPTE) NS=NR1
IF (FLAG) GO TO 90
J1=I+J2
J2=J1+NS-1
DO 150 L=1,NR1
UCIR(L)=UCOR(L)
VCIR(L)=VCDR(L)
WCIR(L)=WCOR(L)
UCIL(L)=UCOL(L)
VCIL(L)=VCOL(L)
WCIL(L)=WCOL(L)
ULIR(L)=ULDR(L)
VLIR(L)=VLOR(L)
MLIR(L)=WLOR(L)
ULIL(L)=ULOL(L)
VLIL(L)=VLOL(L)
WLIL(L)=WLOL(L)
UTIR(L)=UTOR(L)
VTIR(L)=VTOR(L)
WTIR(L)=WTOR(L)
UTIL(L)=UTOL(L)
VTIL(L)=VTOL(L)
WTIL(L)=WTOL(L)
IF (.NOT.THK) GO TO 100
RCIR(L)=RCOR(L)
SCIR(L)=SCOR(L)

```

```

TCIR(L)=TCOR(L)
RCIL(L)=RCOL(L)
SCIL(L)=SCOL(L)
TCIL(L)=TCOL(L)
RLIR(L)=RLOR(L)
SLIR(L)=SLOR(L)
TLIR(L)=TLOR(L)
RLIL(L)=RLOL(L)
SLIL(L)=SLOL(L)
TLIL(L)=TLOC(L)
DX=XI-XC(L,M)
DY=YI-YC(L,M)
DZ=ZI-ZC(L,M)
AT=AL
BL=BLE(L)
CT=CL
IF (L.EQ.NR1) GO TO 110
BL1=BLE(L+1)
AB=BL-BL1
CC=XC(L+1,M)-XC(L,M)
CONTINUE
BPOS=BL.GE.0.
AL=AB
BL=ABS(BL)
CL=CC
CALL VORVEL (UCOR(L),VCOR(L),WCOR(L),ULOR(L),VLQR(L),WLOR(L),UTOR(
L),VTOR(L),WTOR(L))
IF (L.EQ.1) GO TO 120
ABA=ABS(AL-AT)
ACL=ABS(CL-CT)
IF (ABA.LE.EPS .AND. ACL.LE.EPS) GO TO 120
AL=AT
CL=CT
ML=1
CALL VORVEL (X,X,X,X,X,X,UTOR(L),VTOR(L),WTOR(L))
AL=AB
CL=CC
ML=1
IF (.NOT.THK) GO TO 130
CALL SORVEL (RCOR(L),SCOR(L),TCOR(L),RLOR(L),SLOR(L),TLOR(L),
DY=-YI-YC(L,M)
CALL VORVEL (UCOL(L),VCOL(L),WCOL(L),ULOL(L),VLOL(L),WLOL(L),UTOR(
L),VTOL(L),WTOL(L))

```

```

IF (L.EQ.1) GO TO 140
IF (ABA.LE.EPS.AND.AC.LE.EPS) GO TO 140
AL=AT
CL=CT
ML=2
U2580 U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

CALL VORVEL (X,X,X,X,X,UTOL(L),VTOL(L),WTOL(L))
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

ML=1
IF (.NOT.THK) GO TO 150
CALL SORVEL (RCOL(L),SCOL(L),TCOL(L),RCOL(L),SCLOL(L),TCLOL(L))
CONTINUE
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

C COMBINE CORNER INFLUENCES TO OBTAIN PANEL VELOCITY COMPONENTS
C
DO 270 L=1,NRI
IF (.NOT.FLAG.OR.L.GT.1) GO TO 160
JSAVE=J
KSAVE=K
NP SAVE=NP
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

270 CONTINUE
K=K+1
IF (SUPTE.OR.L.LT.NRI) GO TO 170
IF (.NOT.THK) GO TO 270
GO TO 210
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

160 CONTINUE
J=J+1
IF (L.EC.NRI) GO TO 200
NP=NP+1
AMP=1.0/CHORD(NP)
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

170 CONTINUE
J=J+1
IF (L.EC.NRI) GO TO 200
NP=NP+1
AMP=1.0/CHORD(NP)
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

C VELOCITY COMPONENTS INDUCED BY PANEL VORTEX DISTRIBUTIONS
C
ULR=ULIR(L)-UTIR(L+1)-ULOR(L)+UTOR(L+1)
UL=L=ULIL(L)-UTIL(L+1)-ULOL(L)+UTOL(L+1)
VLR=VLIR(L)-VTIR(L+1)-VLOR(L)+VTOR(L+1)
VLL=VLIL(L)-VTIL(L+1)-VLOL(L)+VTOL(L+1)
WLR=WLIR(L)-WTIR(L+1)-WLOR(L)+WTOR(L+1)
WLL=WLIL(L)-WTIL(L+1)-WLOL(L)+WTOL(L+1)
UCL=UCIR(L)-UCIR(L+1)+UCOR(L+1)-ULR
VCL=VCIL(L)-UCOL(L)-UCIL(L+1)+UCOL(L+1)-ULL
VCR=VCIR(L)-VCOR(L)-VCIR(L+1)+VCOR(L+1)-VLR
VCL=VCIL(L)-VCOL(L)-VCIL(L+1)+VCOL(L+1)-VLL
WCR=WCIR(L)-WCOR(L)-WCIR(L+1)+WCOR(L+1)-WLR
U2590 U2600 U2610 U2620 U2630 U2640 U2650 U2660 U2670 U2680 U2690 U2700 U2710 U2720 U2730 U2740 U2750 U2760 U2770 U2780 U2790 U2800 U2810 U2820 U2830 U2840 U2850 U2860 U2870 U2880 U2890 U2900 U2910 U2920 U2930 U2940 U2950 U2960 U2970 U2980 U2990 U3000

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WCL=WCOL(L)-WCIL(L)-WCIL(L+1)+WCOL(L+1)-WLL
IF (.NOT.THK) GO TO 180

C VELOCITY COMPONENTS INDUCED BY PANEL SOURCE DISTRIBUTION S

C RLR=(RLIR(L)-RLIR(L+1))-RLOR(L)+RLOR(L+1)*AMP
RLI=(RLIL(L)-RLIL(L+1))-RLOL(L)+RLOL(L+1)*AMP
SLR=(SLIR(L)-SLIR(L+1))-SLOR(L)+SLOL(L+1)*AMP
SLL=(SLLI(L)-SLLI(L+1))-SLLI(L)+SLLI(L+1)*AMP
TLR=(TLIR(L)-TLIR(L+1))-TLOR(L)+TLOL(L+1)*AMP
TLL=(TLLI(L)-TLLI(L+1))-TLLI(L)+TLLI(L+1)*AMP
IF (L.EQ.1) GO TO 190
180
UCR=RCR*UCR
UCL=RCL+UCL
VCR=SCR+VCR
VCL=SCL+VCL
WCR=TCR+WCR
WCL=TCL+WCL
IF (.NOT.THK) GO TO 220
UTR=RTR-RLR
UTL=RTL-RLL
VTR=STR-SLR
VTL=STL-SLL
WTR=TTR-TLR
WTL=TTL-TLL
GO TO 220

C SPECIAL CASE FOR LEADING EDGE PANELS

C 190 IF (.NOT.THK) GO TO 220
UTR=RCIR(L)-RCOR(L)-RLR
UTL=RCIL(L)-RCOL(L)-RLL
VTR=SCIR(L)-SCOR(L)-SLR
VTL=SCIL(L)-SCOL(L)-SLL
WTR=TCIR(L)-TCOR(L)-TLR
WTL=TCIL(L)-TCOL(L)-TLL
GO TO 220

C SPECIAL CASE FOR TRAILING EDGE PANELS

C 200 UCR=RCR
UCL=RCL
VCR=SCR
U3010
U3020
U3030
U3040
U3050
U3060
U3070
U3080
U3090
U3100
U3110
U3120
U3130
U3140
U3150
U3160
U3170
U3180
U3190
U3200
U3210
U3220
U3230
U3240
U3250
U3260
U3270
U3280
U3290
U3300
U3310
U3320
U3330
U3340
U3350
U3360
U3370
U3380
U3390
U3400
U3410
U3420
U3430

```

VCL=SCL          U3440
WCR=TCR          U3450
WCL=TCL          U3460
IF (.NOT.THK) GO TO 230   U3470
UTR=RLL-RCIR(L)+RCOR(L) U3480
UTL=RLL-RCIL(L)+RCOL(L) U3490
VTR=SLR-SCIR(L)+SCOR(L) U3500
VTL=SLL-SCIR(L)+SCOL(L) U3510
WTR=TLR-TCIR(L)+TCOR(L) U3520
WTL=TLI-TCIL(L)+TCOL(L) U3530
GO TO 230           U3540
RCR=ULL          U3550
RCL=ULL          U3560
SCR=VLR          U3570
SCL=VLL          U3580
TCR=MLR          U3590
TCL=WLL          U3600
IF (.NOT.THK) GO TO 230   U3610
RTR=RLL          U3620
RTL=RLL          U3630
STR=SLR          U3640
STL=SLL          U3650
TTR=TLR          U3660
TTL=TLI          U3670
C
C   COMBINE CONTRIBUTIONS OF LEFT AND RIGHT WING PANELS AND TRANSFORM
C   VELOCITY COMPONENTS BACK TO ORIGINAL COORDINATE SYSTEM
C
230  CONTINUE
IF (.NOT.SUPE.AND.L.EQ.NR1) GO TO 260
UC(J)=(UCL+UCL)*BCON
AC(J)=(VCR*SINTR+VCL*SINTL+WCR*COSTR+WCL*COSTL)*BCON
BC=(VCR*COSTR-WCR*SINTR-VCL*COSTL+WCL*SINTL)*BCON
VC(J)=BC*COSTI-AC(J)*SINTI
WC(J)=AC(J)*COSTI+BC*SINTI
IF (INPART.EQ.2) AC(J)=AC(J)-DI*UC(J)
IF (M.GT.M1) GO TO 250
IF (.NOT.FLAG) GO TO 240
USAVE(L)=UC(J)
VSAVE(L)=VC(J)
WSAVE(L)=WC(J)
ASAVE(L)=AC(J)
GO TO 270

```

```

240 UC(J)=UC(J)+USAVE(L)
    VC(J)=VC(J)+VSUME(L)
    WC(J)=WC(J)+WSAVE(L)
    AC(J)=AC(J)+ASAVE(L)
    IF (NWING.LE.NMAX) GO TO 260
    IF (INPART.EQ.2) GO TO 260
    IF (II.LT.J1.OR.II.GT.J2) GO TO 260
    JS1=J1
    JS2=J2
    NSS=NS
    IF (.NOT.THK) GO TO 270
    UT(K)=(UTR+UTL)*CONT
    AT=(VTR*SINTR+VTL*SINTL+VTR*COSTR+VTL*COSTL)*BCONT
    BT=(VTR*COSTR-VTR*SINTR-VTL*COSTL+VTL*SINTL)*BCONT
    VT(K)=BT*COSTI-AT*SINTI
    WT(K)=AT*COSTI+BT*SINTI
    CONTINUE
    270 CONTINUE
    280 CONTINUE
    IF (.NOT.FLAG) GO TO 290
    FLAG=.FALSE.
    THK=THIK
    J=JSAVE
    K=KSAVE
    NP=NPSAVE
    GO TO 20
    CONTINUE
    NWING=J
    NWTWK=K
    IF (NWING.LE.NMAX.OR.NPART.EQ.2) GO TO 310
    C STORE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX IN DC ARRAY
    C
    DO 300 J=1,NWING
    IF (J.LT.JS1.OR.J.GT.JS2) GO TO 300
    K=J-JS1+1
    DC(K)=AC(J)
    AC(J)=0.
    CONTINUE
    300 WRITE(10) DC(J),J=1,NSS
    CONTINUE
    IF (IABS(PRINT).LT.4) GO TO 330
    IF (6,370) 11
    WRITE(6,380) NWING
    310

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```

      WRITE (6,360) (UC(J),J=1,NWING)
      WRITE (6,390) NWING
      WRITE (6,360) (AC(J),J=1,NWING)
      IF (.NOT. THK) GO TO 320
      WRITE (6,400) NWTHK
      WRITE (6,360) (UT(K),K=1,NWTHK)
      WRITE (6,410) NWTHK
      WRITE (6,360) (WT(K),K=1,NWTHK)
      CONTINUE
      IF (INWING.GT.NMAX.AND.NPART.NE.2) WRITE (6,420) NSS
      IF (INWING.GT.NMAX.AND.NPART.NE.2) WRITE (6,360) (DC(J),J=1,NSS)
      IF (.NOT. THK) GO TO 340
      WRITE (8) (UT(K),VT(K),WT(K),K=1,NWTHK)
      WRITE (8) (UC(J),VC(J),WC(J),J=1,NWING)
      WRITE (9) (AC(J),J=1,NWING)
      CONTINUE
      RETURN
      C
      C
      360 FORMAT (1H0,10F10.5)
      370 FORMAT (1H0,22HAERODYNAMIC MATRIX, I=13)
      380 FORMAT (2X,10HUC(J),J=1,,13)
      390 FORMAT (2X,10HAC(J),J=1,,13)
      400 FORMAT (2X,10HUT(K),K=1,,13)
      410 FORMAT (2X,10HWTK),K=1,,13)
      420 FORMAT (2X,10HDC(J),J=1,,13)
      END

```

```

      V 10
      V 20
      V 30
      V 40
      V 50
      V 60
      V 70
      V 80
      V 90
      V 100
      V 110
      V 120
      V 130
      V 140
      V 150
      V 160
      V 170
      V 180
      V 190
      V 200
      V 210
      V 220
      V 230
      V 240
      V 250
      V 260
      V 270
      V 280
      V 290
      V 300
      V 310
      V 320
      V 330
      V 340
      V 350
      V 360
      V 370
      V 380
      V 390
      V 400
      V 410
      V 420

SUBROUTINE SORVEL (UC,VC,WC,UL,VL,WL)
C
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT A SPECIFIED
C CONTROL POINT BY CONSTANT AND LINEARLY VARYING SOURCE
C DISTRIBUTIONS ON A SWEEP QUADRILATERAL PANEL. SORVEL CALCULATES
C THE VELOCITY INDUCED BY ONE CORNER OF THE PANEL.
C
C UC, VC, WC ARE VELOCITY COMPONENTS INDUCED BY CONSTANT SOURCE
C DISTRIBUTION
C
C UL, VL, WL ARE VELOCITY COMPONENTS INDUCED BY LINEAR CHORDWISE,
C LINEAR SPANWISE SOURCE DISTRIBUTION
C
COMMON /COMPS/ X,DELTAY,DELTAZ,A,B,C,SUB,BPOS,COST,SINT
LOGICAL SUB,SUP,BPOS,BNEG,SUPLE
C
      DATA EPS/1.0E-6/,PI/3.14159265/
      SUP=.NOT.SUB
      SUPLE=.FALSE.
      BNEG=.NOT.BPOS
      IF (ABS(B).LE.EPS) B=0.
      SGN=1.0
      IF (SUP) SGN=-1.0
      BT1=SGN+B*B
      BTERRH=SQRT(ABS(BT1))
      BTERRM=1./BTERRH
      Y=DELTAY*COST+DELTAZ*SINT
      IF (BNEG) Y=-Y
      Z=DELTAZ*COST-DELTAY*SINT
      IF (ABS(Y).LE.EPS) Y=0.
      IF (ABS(Z).LE.EPS) Z=0.
      X2=X*X
      Y2=Y*Y
      Z2=Z*Z
      R2=Y2+Z2
      R=SQRT(R2)
      IF (SUB) GO TO 10
      IF (B.LT.1.0) SUPLE=.TRUE.
      IF (X.LE.0.) GO TO 170
      D=0.
      IF (X2.GT.R2) D=SQRT(X2-R2)
      GO TO 20

```

```

10      D= SQRT(X2+R2)
20      CONTINUE
30      T2=B*X+SGN*Y
40      T3=X-B*Y
50      AT3=ABS(T3)
60      IF (AT3.LE.EPS) AT3=0.
70      UC=-PI*BTERM0
80      V 430
90      V 440
100     V 450
110     V 460
120     V 470
130     V 480
140     V 490
150     V 500
160     V 510
170     V 520
180     V 530
190     V 540
200     V 550
210     V 560
220     V 570
230     V 580
240     V 590
250     V 600
260     V 610
270     V 620
280     V 630
290     V 640
300     V 650
310     V 660
320     V 670
330     V 680
340     V 690
350     V 700
360     V 710
370     V 720
380     V 730
390     V 740
400     V 750
410     V 760
420     V 770
430     V 780
440     V 790
450     V 800
460     V 810
470     V 820
480     V 830
490     V 840
500     V 850
C      SPECIAL CASE FOR SUPER SONIC LEADING EDGE
C
C      IF (D.GT.0.) GO TO 30
C      IF (Y.LE.B*X) GO TO 170
C      IF (T3.LE.0.) GO TO 170
C      IF (X.LE.1B*Y+BTERM*ABS(Z)) GO TO 170
C      SZ=SIGN(1.0,Z)
C      UC=-PI/BTERM
C      VC=-B*UC
C      HC=SZ*PI
C      UL=-PI*(T3*BTERM0-Z*SZ)
C      VL=-B*UL
C      WL=-SZ*BTERM*UL
C      GO TO 160
C      IF (SUP.AND.X2.LE.R2) GO TO 170
C      IF (Z.EQ.0.) GO TO 80
C
C      GENERAL EQUATIONS
C
C      DENOM=B*R2-X*Y
C      F1=ATAN2(Z*D,DENOM)
C      IF (SUB) F1=F1-ATAN2(Z,Y)
C      G1=0.
C      IF (BTERM.EQ.0.) GO TO 60
C      ARG=T2
C      IF (SUB) GO TO 40
C      TZ=T3+B*T1*Z2
C      IF (TZ.GT.0.) ST3=SQRT(TZ)
C      IF (SUPLE) GO TO 50
C      ARG=ARG+D*BTERM
C      IF (SUP) ARG=ARG/ST3
C      IF (ARG.GT.0.) G1=ALOG(ARG)*BTERM0
C      GO TO 70
C      G1=ACOS(ARG/ST3)*BTERM0
C      GO TO 70

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```

60      IF (T2.NE.0.) G1=D/T2
70      G2=ALOG((X+D)/R)
    G3=0.
    IF (SUB) G3=ALOG(R)
    C1=D
    IF (SUB) C1=X+D
    G=B*T1*G1-B*G2
    H=B*G1-G2+G3
    UC=-G1
    VC=H
    WC=F1
    UL=Z*F1-T3*G1-Y*G2
    VL=T3*H+C1-B*Z*F1
    WL=T3*F1+Z*G
    GO TO 160
C      SPECIAL EQUATIONS FOR Z=0
C
80      CONTINUE
    F1=C.
    DENOM=-Y*T3
    IF (DENOM.NE.0.) F1=ATAN2(0.,DENOM)
    IF (SUB.AND.Y.NE.0.) F1=F1-ATAN2(0.,Y)
    IF (SUPLE) GO TO 100
    G1=0.
    IF (BTERM.EQ.0.) GO TO 110
    IF (AT3.GT.0.) GO TO 90
    G1=(100.* ALOG(2.*BT1*ABS(Y)))*BTERM
    IF (SUB.AND.Y.LT.0.) G1=-G1
    GO TO 120
    ARG=T2+D*BTERM
    IF (SUP) ARG=ARG/AT3
    IF (ARG.GT.0.) G1=ALOG(ARG)*BTERM
    GO TO 120
100     G1=ACOS(T2/AT3)*BTERM
    GO TO 120
110     IF (T2.NE.0.) G1=D/T2
    G2=100.
    IF (Y.EQ.0.) GO TO 130
    G2=ALOG((X+D)/ABS(Y))
    GO TO 140
130     IF (X.NE.0.) G2=G2+ALOG(2.*ABS(X))
    IF (X.LT.0.) G2=-G2

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140      C1=0.          V1290
          G3=0.          V1300
          IF (.NOT.SUB) GO TO 150
          C1=X+D          V1310
          IF (Y.NE.0.) G3=ALOG(ABS(Y))
          IF (Y.EQ.0.) G3=-100.
          H=B*G1-G2+G3      V1320
          UC=--G1          V1330
          VC=H             V1340
          MC=F1            V1350
          UL=-T3*G1-Y*G2  V1360
          VL=T3*H+C1       V1370
          WL=T3*F1          V1380
          C
          IF (BPOS) RETURN  V1390
          UC=--UC          V1400
          WC=--WC          V1410
          UL=-UL          V1420
          WL=-WL          V1430
          RETURN           V1440
          UC=0.            V1450
          VC=0.            V1460
          WC=0.            V1470
          UL=0.            V1480
          VL=0.            V1490
          WL=0.            V1500
          RETURN           V1510
          END               V1520
          UC=0.            V1530
          VC=0.            V1540
          WC=0.            V1550
          UL=0.            V1560

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SUBROUTINE VORVEL (UC,VC,WL,UL,VL,ULT,VLT,WLT)

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420

C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT A SPECIFIED
C CONTROL POINT BY CONSTANT AND LINEARLY VARYING VORTEX
C DISTRIBUTIONS ON A SWEEP QUADRILATERAL PANEL. VORVEL CALCULATES
C THE VELOCITY INDUCED BY THE LEADING AND TRAILING CORNERS OF ONE
C EDGE OF THE PANEL.

C UC, VC, WL ARE VELOCITY COMPONENTS INDUCED BY CONSTANT CHORDWISE
C AND SPANWISE VORTEX DISTRIBUTION
C
C UL, VL, WL ARE VELOCITY COMPONENTS INDUCED BY LEADING EDGE OF
C LINEAR CHORDWISE, CONSTANT SPANWISE VORTEX DISTRIBUTION
C
C ULT, VLT, WLT ARE VELOCITY COMPONENTS INDUCED BY TRAILING EDGE OF
C LINEAR CHORDWISE, CONSTANT SPANWISE VORTEX DISTRIBUTION
C
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /COMPS/ X,DELTAY,DELTAZ,A,B,C,SUB,BPOS,COST,SINT,ML
DIMENSION Q(51), XI(51), QX(51)
LOGICAL SUB,SUP,BPOS,SUPLE,LBC

C
DATA EPS/1.0E-6/,PI/3.14159265/
IF (ABS(C).LE.EPS) C=0.
CC=C*C
SUP=.NOT.SUB
SUPLE=.FALSE.
IF (ABS(B).LE.EPS) B=0.
AB=A+B
SGN=1.0
IF (SUP) SGN=-1.0
B1=SGN+B*B
SB1=SQRT(ABS(B1))
Y=DELTAY*COST+DELTAZ*SINT
Z=DELTAZ*COST-DELTAY*SINT
IF (ABS(Y).LE.EPS) Y=0.
IF (ABS(Z).LE.EPS) Z=0.
X2=X*X
Y2=Y*Y
Z2=Z*Z
R2=Y2+Z2
R=SQRT(R2)

```

```

IF (SUB) GO TO 10
IF (ABS(B1).LT.1.0) SUPLE=.TRUE.
IF (X.LT.0.) GO TO 320
D=0.
D2=X2+SGN*R2
IF (D2.GT.0.) D=SQRT(D2)
AZ=A*Z
T1=C-A*Y
IF (ABS(T1).LE.EPS) T1=0.
T2=T1*T1
T3=X-B*Y
AT3=ABS(T3)
IF (AT3.LE.EPS) AT3=0.
T4=AZ*AZ
T5=T2+T4
IF (T5.NE.0.) T5=1./T5
T6=B*C-A*X
T7=T6*T6
T8=T7+SGN*(T2+T4)
T9=T1*T3+A*B*Z2
E=SQRT(ABS(T8))
B2=SGN*(C*Y-A*R2)
B3=B*X+SGN*Y
B4=T5*T6
TZ=T3*T3+B1*Z2
IF (TZ.GT.0.) ST3=SQRT(TZ)
WQ=0.

      C
      C EVALUATION OF DOWNWASH INDUCED BY TRAILING VORTEX SHEET
      C
IF (A.EQ.0..OR..ML.EQ.2) GO TO 80
MAX=11
XI(1)=0.
EL=1.0
IF (SUP.AND.X.LT.C) EL=X/C
DXI=EL/FLOAT(MAX-1)
X0=0.
IF (T1.NE.0.) X0=T3/T1
DO 70 M=1,MAX
Q(M)=0.
IF (M.GT.1) XI(M)=XI(M-1)+DXI
DX=X-XI(M)*C
IF (SUP.AND.DX.LT.0.) GC TO 60
      W 430
      W 440
      W 450
      W 460
      W 470
      W 480
      W 490
      W 500
      W 510
      W 520
      W 530
      W 540
      W 550
      W 560
      W 570
      W 580
      W 590
      W 600
      W 610
      W 620
      W 630
      W 640
      W 650
      W 660
      W 670
      W 680
      W 690
      W 700
      W 710
      W 720
      W 730
      W 740
      W 750
      W 760
      W 770
      W 780
      W 790
      W 800
      W 810
      W 820
      W 830
      W 840
      W 850

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IF (Y.LE.B*X) GO TO 320
IF (X.LT.(B*Y+SB1*ABS(Z))) GO TO 320
SZ=SIGN(1.0,Z)
PZ=PI*SZ
UC=PZ
VC=-B*PZ
WC=-SZ*SB1*PZ
IF (TB.GT.0.) E=0.
SL=PI*T5*(SZ*T9-Z*E)
TL=SZ*E*T5*SL
IF (TB.GT.0.) TL=PI*T5*T5*T8*ABS(Z)
IF (ML.EQ.2) GO TO 90
UL=SL
VL=-((B+T1*B4)*SL-AZ*TL)/2.
WL=AZ*B4*SL-T1*TL+A*WQ
IF (.NOT.LBC.AND.ML.EQ.1) GO TO 310
ULS=SL+PZ
ULT=ULS
TT=SZ*E*T5*ULS
IF (TB.GT.0.) TT=TL
VLT=(A*PZ-(AB+T1*B4)*ULS+AZ*TT)/2.
WLT=AZ*B4*ULS-T1*TT
GO TO 310
IF (SUP.AND.D.EQ.0.) GO TO 320
IF (Z.EQ.0.) GO TO 180
C
C          GENERAL EQUATIONS
C
DENOM=B*R2-X*Y
F1=ATAN2(Z*D,DENOM)
IF (SUB) F1=F1-ATAN2(Z,Y)
G1=0.
IF (TB.EQ.0.) GO TO 130
IF (C.EQ.0.) GO TO 110
ARG=X*T6+B2
IF (TB.LT.0.) GO TO 120
ARG=(ARG+D*E)/(ST3*C)
IF (SUP) ARG=ABS(ARG)
IF (ARG.GT.0.) G1=ALOG(ARG)
GO TO 130
IF (ST3.NE.0.) G1=ALOG(ST3)
GO TO 130
ARG=ARG/(ST3*C)
110
120

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DX2=DX*DX
BX=A*X1(M)
BX2=BX*BX
BX1=SGN+BX2
SBX=SQRT(ABS(BX1))
SDX=0.

DXR=DX2+SGN*R2
IF (DXR.GT.0.) SDX=SQRT(DXR)
IF (SDX.EQ.0.) GO TO 20
ARG=SGN*Y+BX*DX
IF (SBX.EQ.0.) GO TO 40
TZI=(T3-X1(M)*T1)**2+BX1*Z2
IF (TZI.EQ.0.) GO TO 50
STZ=SQRT(TZI)
IF (SUP.AND.BX.LT.1.0) GO TO 30
ARG=(ARG+SBX*SDX)/STZ
IF (SUP) ARG=ABS(ARG)
IF (ARG.GT.0.) Q(M)= ALOG(ARG)*BX/SBX
GO TO 60
IF (T1.LT.BX*T6.AND.T8.LT.0.) GO TO 60
IF (Y.LE.BX*DX) GO TO 60
IF (DX.LT.(BX*Y+SBX*ABS(Z))) GO TO 60
Q(M)=PI*BX/SBX
GO TO 60
ARG=ARG/STZ
IF (ARG.GT.1.0) GO TO 60
IF (ARG.LE.-1.0) GO TO 20
Q(M)=ACOS(ARG)*BX/SBX
GO TO 60
Q(M)=SDX*BX/ARG
GO TO 60
Q(M)=100.
IF (Y.LT.0.) Q(M)=-ALOG(ABS(Y))*BX/SBX
CONTINUE
Q(X(M)=Q(M)*X1(M)
CALL TRAP (XI,QX,WQ,MAX)
CONTINUE
IF (.NOT.SUPLE) GO TO 100
C
C      SPECIAL EQUATIONS FOR SUPERSONIC LEADING EDGE
C
IF (D.GT.0.) GO TO 100

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IF (ABS(ARG)-GT.-1.0) GO TO 130
C1=-ACOS(ARG)
H1=0.
130   IF (LBC.AND.ML.EQ.21 GO TO 150
      IF (SBL.EQ.0.) GO TO 150
      ARH=B3
      IF (SUPLE) GO TO 140
      ARH=(ARH+D*SBL)/ST3
      IF (ARH.GT.0.) H1=ALOG(ARH)
      GO TO 150
      H1=-ACCS(ARH/ST3)
      G2=ALOG((X+D)/R)
      G3=0.
      IF (SUBI) G3=ALOG(R)
      C1=0
      IF (SUBI) C1=X+C1
      C2=C1/R2
      H=SBL*H1-B*(G2-G3)
      IF (SBL.EQ.0.) H2=B*D/B3-G2+G3
      IF (SBL.NE.0.) H2=B*H1/SBL-G2+G3
      UC=F1
      VS=-B*F1+Z*C2
      WS=H-Y*C2
      VC=VS
      HC=WS
      IF (C.EQ.0.) C2=0.
      C3=0.
      C4=0.
      C5=G2/2.
      C6=0.
      IF (C.EQ.0.) GO TO 160
      C3=(X*C2+SGN*G2)/(2.*C)
      C4=((X2-SGN*R2/2.)*G2-1.5*X*D)/(2.*CC)
      C5=(D-X*G2)/C
      CONTINUE
      HQ=HQ-C4
      G=E*G1-T6*G2
      SL=15*(T9*F1+Z*G1)
      TL=-B*D
      IF (C.NE.0.) TL=(B2*G2+T6*D)/C
      TL=-T5*(T5*(G*T9-Z*T8*F1)+TL)
      IF (ML.EQ.2) GO TO 170
      UL=SL
      W1720
      W1730
      W1740
      W1750
      W1760
      W1770
      W1780
      W1790
      W1800
      W1810
      W1820
      W1830
      W1840
      W1850
      W1860
      W1870
      W1880
      W1890
      W1900
      W1910
      W1920
      W1930
      W1940
      W1950
      W1960
      W1970
      W1980
      W1990
      W2000
      W2010
      W2020
      W2030
      W2040
      W2050
      W2060
      W2070
      W2080
      W2090
      W2100
      W2110
      W2120
      W2130
      W2140

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VL=-((B+T1*B4)*SL-AZ*TL)/2.+Z*C3   W2150
ML=AZ*B4*SL-T1*TL-Y*C3+A*WQ   W2160
IF (.NOT.LBC.AND.ML.EQ.1) GO TO 310   W2170
170  ULS=SL+F1   W2180
ULT=ULS   W2190
ULT=TL-T5*G   W2200
WQT=C5-C4-C3/2.   W2210
VL S=(A+F1-(AB+T1*B4)*ULS+AZ*TL)/2.+Z*(C2+C3)   W2220
VLT=VLS   W2230
WLS=AZ*B4*ULS-T1*TL-Y*(C2+C3)+A*WQT   W2240
WL T=MLS   W2250
GO TO 310   W2260
W2270
W2280
W2290
W2300
W2310
W2320
W2330
W2340
W2350
W2360
W2370
W2380
W2390
W2400
W2410
W2420
W2430
W2440
W2450
W2460
W2470
W2480
W2490
W2500
W2510
W2520
W2530
W2540
W2550
W2560
W2570

C SPECIAL EQUATIONS FOR Z=0
C
C CONTINUE
C
180  F1=0.
DENCM=-Y*T3
IF (DENCM.NE.0.) F1=ATAN2(0.,DENOM)
IF (SUB.AND.Y.NE.0.) F1=F1-ATAN2(0.,Y)
G1=0.
IF (T8.EQ.0.) GO TO 220
IF (C.EQ.0.) GO TO 200
IF (T8.LT.0.) GO TO 210
IF (AT3.GT.0.) GO TO 190
IF (Y.EQ.0..OR.T1.LE.0.) GO TO 220
G1=ALOG(T1*ABS(Y))
IF (SUB.AND.Y.LT.0.) G1=-G1
IF (Y.GT.0.) G1=100.+G1
GO TO 220
AR G=(X*T6+SGN*Y*T1+D*E)/(AT3*C)
IF (SUP) ARG=ABS(ARG)
IF (ARG.GT.0.) G1=ALOG(ARG)
GO TO 220
IF (AT3.NE.0.) G1=ALOG(AT3)
GO TO 220
ARG=(X*T6-Y*T1)/(AT3*C)
IF (ABS(ARG).GT.1.0) GO TO 220
G1=-ACOS(ARG)
H1=0.
IF (LBC.AND.ML.EQ.2) GO TO 250
IF (SBL.EQ.0.) GO TO 250
IF (SUPLES GO TO 240

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IF (AT3.GT.0.) GO TO 230
IF (Y.EQ.0.) GO TO 250
H1=ALOG(ABS(Y))
IF (SUB.AND.Y.LT.0.) H1=-H1
IF (Y.GT.0.) H1=100.*H1
GO TO 250
230 CONTINUE
ARH=(B3+D*SB1)/AT3
IF (ARH.GT.0.) H1=ALOG(ARH)
GO TO 250
H1=-ACCS(B3/AT3)
240 G2=100.
IF (Y.NE.0.) GO TO 260
IF (X.NE.0.) G2=G2+ALOG(2.*ABS(X))
IF (X.LT.0.) G2=-G2
GO TO 270
G2=ALOG((X+D)/ABS(Y))
250 G3=0.
C1=D
IF (.NOT.SUB1) GO TO 280
C1=X+D
C2=0.
G3=-100.
IF (Y.NE.0.) G3=ALOG(ABS(Y))
260 C2=0.
IF (Y.NE.0.) C2=C1/Y2
H=SB1*H1-B*(G2-G3)
IF (SB1.EQ.0.) H2=B*D/B3-G2+G3
IF (SB1.NE.0.) H2=B*H1/SB1-G2+G3
UC=F1
VS=-B*F1
WS=H-Y*C2
VC=VS
WC=hS
IF (C.EQ.0.) C2=0.
C4=0.
C5=G2/2.
C6=C.
IF (C.EQ.0.) GO TO 290
C3=(X*C2+SGN*G2)/2.
C4=((X2-SGN*Y2/2.)*G2-1.5*X*D)/(2.*CC)
C5=(D-X*G2)/C
CONTINUE
WQ=WQ-C4
290

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WQ T=C5-C4-G3/2.
IF (T1.NE.0.) GO TO 300
WL=A*WQ
WL S=A*WQT
WL T=WL S
GO TO 330
SL=T3*F1/T1
UL=SL
VL=-(B+T6/T1)*SL/2.
G=E*G1-T6*G2
TL=T3*T5*G
IF (C.EQ.0.) TL=TL-B*D/I1
IF (C.NE.0.) TL=TL+(T6*D/T1+Y*(SGN*G2-C3))/C
WL=TL+A*WQ
IF (.NOT.LBC.AND.ML.EQ.1) GO TO 310
UL S=SL+F1
VL S=(A+F1-(AB+T6/T1)*UL S)/2.
WL S=TL+G/T1-Y*C2+A*WQT
UL T=UL S
VL T=VLS
WL T=WL S
RETURN
310
320
UC=0.
VC=0.
WC=0.
WL=0.
ML T=0.
330
UL =0.
VL =0.
UL T=0.
VL T=0.
IF (C.EQ.0.) GO TO 310
RETURN
END

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```
OVERLAY(LWB,2,3)
PROGRAM NGVEL
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```
C          X 10
X  X 20
X  X 30
X  X 40
X  X 50
X  X 60
X  X 70
X  X 80
X  X 90
X  X 100
X  X 110
X  X 120
X  X 130
X  X 140
X  X 150
X  X 160
X  X 170
X  X 180
X  X 190
X  X 200
X  X 210
X  X 220
X  X 230
X  X 240
X  X 250
X  X 260
X  X 270
X  X 280
X  X 290
X  X 300
X  X 310
X  X 320
X  X 330
X  X 340
X  X 350
X  X 360
X  X 370
X  X 380
X  X 390
X  X 400
X  X 410
X  X 420

C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT SPECIFIED
C CONTROL POINTS BY VORTEX PANELS LOCATED ON WING, FIN (VERTICAL
C TAIL), OR CANARD (HORIZONTAL TAIL) SURFACES.
C
C COMMON /PARAM/ NBODY,NWING,NPANEL,LBC,THK,MACH,ALPHA,REFA
C COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,PRINT,NWTHK
C COMMON /SEG/ NSEG,NROW(20),NCOL(20),CUXS(20),SINS(20),TT(20),NWT(2
C 10),SPN(20),XLEM(20),BLE(20),ZLEM(20),XS(20),YS(20),ZS(20)
C COMMON /COMPS/ XJ,YJ,ZJ,AL,BL,CL,SUB,BPCS,M,NSIDE
C COMMON /POINT/ ARRAY(6000)
C COMMON /SCRAT/ DUMMY(1440),A(30),C(30),CO(30),AC(600),LC(600),VC(
C 1600),WC(600),COSBD(600),SINBD(600),TANBD(600),DC(600),DUM(990),UL(3
C 20),VL(30),WL(30),AN(30),ZU(30,20)
C COMMON /TRAN/ SIND,COSD,TAND,SINT,CCSD,CCNT,CCNT,CCN,COSTI,CCN,
C 1DI
C COMMON /BTBET/ THETI(600)
C
C DIMENSION XPT(600), YPT(600), ZPT(600), THET(600), DELTA(600), XC(
C 130,20), YC(30,20), ZC(30,20), DELTI(600)
C
C EQUIVALENCE (ARRY,XPT), (ARRY(601),YPT), (ARRY(1201),ZPT),
C LAY(1801),THET), (ARRY(2401),DELTA), (ARRY(3001),XC), (ARRY(3601),
C 2),YC), (ARRY(4201),ZC), (ARRY(4801),DELTI)
C
C LOGICAL THK,LBC,SUB,BPCS
C INTEGER PRINT
C REAL MACH
C DATA PI/3.14159265/
C SUB=MACH.LT.1.0
C SGN=-1.0
C IF (SUB) SGN=1.0
C BETA=SQRT(ABS(MACH*MACH-1.0))
C CON=1./{2.*PI}
C IF (SUB) CCN=CCN/2.
C BCON=BETA*CCN
C IF (NPART.NE.2) GO TO 10
C REWIND 7
C READ(7,DUMMY(N),N=1,1800),(THET(N),N=1,600),(DELTA(N),N=1,600)
C
```

```

10      REWIND 7
      CONTINUE
      DO 20 N=1,NWING
      BD=BETA*TAN(DELTA(N))
      TANBD(N)=BD
      ARG=1.+SGN*BD*BD
      IF (ARG.LT.0.) GO TO 320
      COSBD(N)=1./SQRT(ARG)
      SINBD(N)=BD*COSBD(N)
20    C
      C   I IS THE INDEX OF THE CONTROL POINT
      C   J IS THE INDEX OF THE INFLUENCING PANEL
      C
      DO 310 I=1,NPOINT
      IF (NPART.EQ.2) GO TO 30
      SINTI=SIN(THET(I))
      COSTI=COS(THET(I))
      DI=TANBD(I)
      GO TO 40
      SINTI=SIN(THET(I))
      COSTI=COS(THET(I))
      DI=BETA*TAN(DELTA(I))
      X1=XPT(I)
      Y1=YPT(I)
      ZI=ZPT(I)
      J=0
      JJ=0
      J2=0
      N2=0
30    C
      C   COMPUTE INFLUENCE OF EACH WING SEGMENT
      C
      DO 270 NS=1,NSEG
      NR=NRW(N$)
      NC=NCOL(NS)
      NR1=NR+1
      NR2=2*NR
      NC1=NC+1
      NT=NWT(NS)
      NI=N2+1
      IF (NS.GT.1.AND.NI.NE.0) NI=NI+1
      N2=NI+NC-1.
270  C

```

```

C COMPUTE INFLUENCE OF EACH COLUMN OF PANELS
C
C DO 270 N=N1,N2
C   J1=1+J2
C   J2=J1+NR2-1
C   JL=J1
C   JT=J1+NR
C   I1=JT-1
C   I2=I1+NR
C
C COMPUTE VELOCITIES INDUCED BY POINT SOURCE
C
C   DXS=XI-XS(N)
C   DYS=(YI-Y$IN)*BETA
C   DZS=(ZI-Z$IN)*BETA
C   S2=DXS**2+DYS**2+DZS**2
C   IF (S2.GT.0.) S=SQRT(S2)
C   S3=0.
C   IF (S2.GT.0.) S3=1.0/(S*S2)
C   US=CCN*DXS*S3
C   VS=BCUN*DYS*S3*SGN
C   WS=BCUN*DZS*S3*SGN
C   AS=WS*CUSTI-VS*SINTI-LS*DI
C
C COMPUTE INFLUENCE OF UPPER AND LOWER SURFACES
C
C DO 260 NSIDE=1,2
C
C COMPUTE INFLUENCE OF EACH PANEL
C
C DU 260 L=1,NR1
C   J=J+1
C   IF (L.EQ.NR1) GO TO 140
C   JJ=JJ+1
C   SIND=SINBD(JJ)
C   CUSD=COSBD(JJ)
C   TAND=TANBD(JJ)
C   THETA=THEBT(JJ)
C   COST=COST(THETA)
C   SINT=SINT(THETA)
C   CUST=CUST*COSD
C   CCNTD=SQR(T1$GN*TAND*COST*COST)
C   CUSDTD=1.0/(COSD*CCNTD)

```

```

C      CONTDD=1./CONTDD
C      COMPUTE PANEL LEADING AND TRAILING EDGE SLOPES
C
DO 50 M=1,2
M=L+M-1
DXC=XC(M1,N+1)-XC(M1,N)
DYC=YC(M1,N+1)-YC(M1,N)
IF (INSIDE.EQ.1) DZC=ZU(M1,N+1)-ZU(M1,N)
IF (INSIDE.EQ.2) DZC=ZC(M1,N+1)-ZC(M1,N)
DYC=BETA*DYC
DZC=BETA*LZC
DZL=DZC*COSTD-DXC*SIND
DYL=DYC*COSD*CINT+SIGN*CZL*CONTDD
DXL=(DXC*COSTD+DZC*SIND*SGN)*CUSSTD
BL=DXL/DYL
IF (M.EQ.1) BLE=BL
IF (M.EQ.2) BTE=BL
CONTINUE
AL=BLE-BTE
AL)=AL
50
C      COMPUTE PANEL CHGRD LENGTHS
C
DO 130 K=1,2
N1=N+K-1
DXC=XC(L+1,N1)-XC(L,N1)
DYC=YC(L+1,N1)-YC(L,N1)
IF (INSIDE.EQ.1) DZC=ZU(L+1,N1)-ZU(L,N1)
IF (INSIDE.EQ.2) DZC=ZC(L+1,N1)-ZC(L,N1)
CL=(DXC*COSTD+BETA*DZC*SIND*SGN)*COSSTD
IF (K.EQ.1) C(L)=CL
IF (K.EQ.2) C(L)=CL
130
C      COMPUTE INFLUENCE OF PANEL CORNERS
C
DO 130 M=1,2
M=L+M-1
C      COMPUTE CONTROL POINT IN PANEL COORDINATE SYSTEM
C
DX=XI-XC(M1,N1)
DY=YL-YC(M1,N1)
130

```

```

1 IF (INSIDE.EQ.1) ZJ=ZI-ZU(M1,N1) X1720
1 IF (INSIDE.EQ.2) ZJ=ZI-ZC(M1,N1) X1730
1 DY=BETA*DY X1740
1 DZ=BETA*CZ X1750
1 XJ=(DX*CCSTD+DZ*SINC*SGN)*COSDT0 X1760
1 ZJ=DZ*COSTD-DX*SIND X1770
1 YJ=DY*COSD*CONT0+SINT*ZJ*CONT0 X1780
1 ZJ=Z-J-DY*CCSD*SINT X1790
1 IF (M.EQ.1) BL=BLE X1800
1 IF (M.EQ.2) BL=BTE X1810
1 IF (K.EQ.2) GO TO 90 X1820
1 IF (M.EQ.2) GO TO 60 X1830
1 CALL VURPAN (UCIR,VCIR,WCIR,ULIR,VLIR,MLIR,X,X,X,VEIR,WEIR,VAIR,WA X1840
1 IIR)
1 GO TO 70 X1850
1 CALL VURPAN (RCIR,SCIR,TCIR,X,X,X,RLIR,SLIR,TLIR,SEIR,TEIR,SAIR,TA X1860
1 IIR)
1 IIR)
1 DY=-YI-YC(M1,N1) X1880
1 DY=BETA*DY X1890
1 ZJ=DZ*COST0-DX*SIND X1900
1 YJ=DY*COSD*CONT0+SINT*ZJ*CONT0 X1910
1 ZJ=Z-J-DY*CCSD*SINT X1920
1 IF (M.EQ.2) GO TO 80 X1930
1 CALL VURPAN (UCIL,VCIL,WCIL,ULIL,VLIL,MLIL,X,X,X,VEIL,WEIL,VAIL,WA X1940
1 IIL)
1 GU TU 130 X1950
1 CALL VURPAN (RCIL,SCIL,TCIL,X,X,X,RLIL,SLIL,TLIL,SEIL,TEIL,SAIL,TA X1960
1 IIL)
1 GO TO 130 X1970
1 IF (M.EQ.2) GO TO 100 X1980
1 CALL VURPAN (UCGR,VCGR,WCGR,ULGR,VLGR,MLGR,X,X,X,VEOR,WEOR,VAOR,WA X1990
1 IOR)
1 GO TO 110 X2000
1 CALL VURPAN (RCGR,SCGR,TCGR,X,X,X,RLGR,SLGR,TLGR,SEOR,TEOR,SAOR,TA X2010
1 IOR)
1 IOR)
1 DY=-YI-YC(M1,N1) X2020
1 DY=BETA*DY X2030
1 ZJ=DZ*COST0-DX*SIND X2040
1 YJ=DY*COSD*CONT0+SINT*ZJ*CONT0 X2050
1 ZJ=Z-J-DY*COSD*SINT X2060
1 IF (M.EQ.2) GO TO 120 X2070
1 CALL VURPAN (UCCL,VCCL,WCCL,ULOL,VLUL,MLUL,X,X,X,VEOL,WEOL,VAGL,WA X2080
1 IUL)

```

```

      GU TO 130          X2150
      CALL VORPAN (RCOL,SCOL,TCOL,X,X,X,RLOL,SLOL,TOL,SEOL,TEOL,SAOL,JA
      10L)          X2160
      CONTINUE        X2170
      GU TO 170        X2180
      C               X2190
      COMPUTE INFLUENCE OF WAKE- NOTE- PLANAR WAKE ASSUMED
      C               X2200
      140             X2210
      SINT=SINS(INS)   X2220
      COST=COSS(INS)   X2230
      COUNTD=CCSD      X2240
      COSDTU=1./((COSD*COUTD)
      COUTD=1./COUNTD  X2250
      TAND=0.           X2260
      SINDD=0.          X2270
      COSD=1.0          X2280
      BCOS=BETA*COST   X2290
      BSIN=BETA*SINT   X2300
      UXC=XC(NR1,N+1)-XC(NR1,N)
      UYC=YC(NR1,N+1)-YC(NR1,N)
      DZC=ZC(NR1,N+1)-ZC(NR1,N)
      DYL=DYL*CUST*DZC*SINT
      BL=UXC/(BETA*DYL)
      AL=0.             X2310
      CL=1.0            X2320
      M=1               X2330
      DO 160 K=1,2      X2340
      N1=N+K-1          X2350
      XJ=X I-XC(NR1,N1)
      DY=Y I-YC(NR1,N1)
      DZ=Z I-ZC(NR1,N1)
      YJ=DY*BCCS+DZ*BSIN
      LZ=DZ*BCCS-DY*BSIN
      IF (K.EQ.2) GO TO 150
      CALL VORPAN (X,X,X,X,X,X,X,VEIR,WEIR,VAIR,WAIR)
      DY=-YI-YC(NR1,N1)
      YJ=DY*BCCS+DZ*BSIN
      LZ=DZ*BCCS-DY*BSIN
      CALL VORPAN (X,X,X,X,X,X,X,VEIL,VAIL,WAIL)
      GO TO 160          X2480
      CALL VORPAN (X,X,X,X,X,X,X,VEOR,WGOR,VACR,WAOR)
      DY=-YI-YC(NR1,N1)
      YJ=DY*BCCS+DZ*BSIN
      X2490          X2500
      X2510          X2520
      X2530          X2540
      X2550          X2560
      X2570          X2580
      150

```

```

X2580
X2590
X2600
X2610
X2620
X2630
X2640
X2650
X2660
X2670
X2680
X2690
X2700
X2710
X2720
X2730
X2740
X2750
X2760
X2770
X2780
X2790
X2800
X2810
X2820
X2830
X2840
X2850
X2860
X2870
X2880
X2890
X2900
X2910
X2920
X2930
X2940
X2950
X2960
X2970
X2980
X2990
X3000

ZJ=D4*B COS-DY*BSIN
CALL VORPAN (X,X,X,X,X,X,X,X,VEL,VACL,WAOL)
SEIR=0.
SEIL=0.
SEQL=0.
SEQR=0.
SAIR=0.
SAIL=0.
SAUL=0.
SAQR=0.
TAIR=0.
TAIL=0.
TAUL=0.
TAUR=0.
TEIR=0.
TEIL=0.
TEOR=0.
TEUL=0.
CONTINUE
CONTINUE
C   COMBINE CORNER INFLUENCES TO OBTAIN PANEL VELOCITY COMPONENTS
C
UAR=0.
VAR=VAIR-VAGR-SAIR+SAOR
WAR=WAIR-WAUR-TAIR+TAOR
UAL=0.
VAL=VAIL-VAOL-SAIL+SAOL
WAL=WAIL-WAOL-TAIL+TAUL
UIR=0.
VIR=VEIR-SEIR
WIR=WEIR-TEIR
UIL=0.
VIL=VEIL-SEIL
WIL=WEIL-TEIL
UOR=0.
VOR=VEOR-SEOR
WUR=WEUR-TEOR
UOL=0.
VCL=VEL-SEOL
WOL=WEOL-TECL
IF (L.EQ.NR1) GO TO 180
ULR=ULIR-ULOR-RLIR+RLOR

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```

ULL=ULIL-ULOL-RLIL+RLOL X3010
VLR=VLIR-VLOR-SLIR+SLOL X3020
VLL=VLIL-VLOL-SLIL+SLOL X3030
WLR=WLIR-WLOR-TLIR+TLOR X3040
WLL=WLIL-WLOL-TLIL+TLOL X3050
UCR=UCIK-UCCR-RCIR+RCOR-ULR X3060
UCL=UCIL-UCOL-RCIL+RCOL-ULL X3070
VCR=VCIR-VCOR-SCIR+SCOR-VLK X3080
VCL=VCIL-VCOL-SCIL+SCCL-VLL X3090
WCX=WCIX-WCIR-TCIR+TCOR-WLR X3100
WCL=WCIL-WCUL-TCIL+TCCL-WLL X3110
X3120
C   COMBINE CONTRIBUTIONS OF LEFT AND RIGHT WING PANELS AND TRANSFORM X3130
C   VELOCITY COMPONENTS BACK TO ORIGINAL COORDINATE SYSTEM X3140
C
C   CALL TRANS (UCR, VCR, WCX, UCL, VCL, WCL, UC(J), VC(J), WC(J), AC(J)) X3150
C   CALL TRANS (ULR, VLR, WLR, ULL, VLL, WLL, UL(L+1), VL(L+1), WL(L+1), AN(L+1) X3160
C
C   IF (L.EQ.1) GO TO 220 X3170
C   CALL TRANS (UIR, VIR, MIR, UIL, VIL, MIL, UI, VI, MI, AI) X3180
C   CALL TRANS (UDR, VDR, MDR, UOL, VOL, VCL, WCL, UO, VO, MC, AO) X3190
C   CALL TRANS (UAR, VAR, MAR, UAL, VAL, WAL, UA, VA, WA, BA)
C   IF (L.EQ.NR1) GO TO 190 X3200
C   UC(J)=UC(J)+UL(L)
C   VC(J)=VC(J)+VL(L)
C   WC(J)=WC(J)+WL(L)
C   AC(J)=AC(J)+AN(L)
C   GO TO 200 X3210
C   UC(J)=UL(L)
C   VC(J)=VL(L)
C   WC(J)=WL(L)
C   AC(J)=AN(L)
C   CONTINUE X3220
C
C   ADD CONTRIBUTION OF THE WAKE X3230
C
C   DO 210 K=2,L X3240
C   K1=K-1 X3250
C
C   UW=UI*C1(K1)-U0*CO(K1)+UA*A(K1) X3260
C   VV=VI*C1(K1)-VO*CO(K1)+VA*A(K1) X3270
C   WW=WI*C1(K1)-WC*CO(K1)+WA*A(K1) X3280
C   AN=AI*C1(K1)-AC*CO(K1)+BA*A(K1) X3290
C   JK=JL+K-2 X3300
C
C   ADD CONTRIBUTION OF THE WAKE X3310
C
C   DO 210 K=2,L X3320
C   K1=K-1 X3330
C
C   UW=UI*C1(K1)-U0*CO(K1)+UA*A(K1) X3340
C   VV=VI*C1(K1)-VO*CO(K1)+VA*A(K1) X3350
C   WW=WI*C1(K1)-WC*CO(K1)+WA*A(K1) X3360
C   AN=AI*C1(K1)-AC*CO(K1)+BA*A(K1) X3370
C   JK=JL+K-2 X3380
C
C

```

```

IF (INSIDE.EQ.2.AND.K.GT.2) JK=JK+NR
UC(JK)=UC(JK)+UW
VC(JK)=VC(JK)+VW
WC(JK)=WC(JK)+WK
AC(JK)=AC(JK)+AK
IF (L.EW.NR1) GO TO 210
JM=JK+1
IF (INSIDE.EQ.2.AND.K.EQ.2) JM=JM+NR
UC(JM)=UC(JM)+UW
VC(JM)=VC(JM)+VW
WC(JM)=WC(JM)+WK
AC(JM)=AC(JM)+AK
CONTINUE
210
CONTINUE
IF (INSIDE.EQ.1) GO TO 240
IF (L.NE.1) GO TO 230
C
C          SPECIAL CASE FOR LEADING EDGE PANELS
C
UC(JL)=UC(JL)+UC(J)
VC(JL)=VC(JL)+VC(J)
WC(JL)=WC(JL)+WC(J)
AC(JL)=AC(JL)+AC(J)
J=J-1
IF (L.NE.NR1) GO TO 240
J=J-1
IF (NWING.LE.NMAX) GO TO 250
IF (NPART.EQ.2) GC TO 250
IF (I.LT.J1.OR.I.GT.J2) GO TO 250
JS1=J1
JS2=J2
NR3=NR2
CONTINUE
250
CONTINUE
UC(JT)=US
VC(JT)=VS
WC(JT)=WS
AC(JT)=AS
CONTINUE
NWING=J
NWTNK=NWING
IF (NWING.LE.NMAX) GO TO 290
IF (NPART.EQ.2) GO TO 290
X3440
X3450
X3460
X3470
X3480
X3490
X3500
X3510
X3520
X3530
X3540
X3550
X3560
X3570
X3580
X3590
X3600
X3610
X3620
X3630
X3640
X3650
X3660
X3670
X3680
X3690
X3700
X3710
X3720
X3730
X3740
X3750
X3760
X3770
X3780
X3790
X3800
X3810
X3820
X3830
X3840
X3850
X3860

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```

C      STORE DIAGONAL BLOCKS OF AERODYNAMIC MATRIX IN DC ARRAY
C
C      DO 280 J=1,NWING
C      IF ((J.LT.JS1.OR.J.GT.JS2)) GO TO 280
C      M=J-JS1+1
C      DC(M)=AC(J,J)
C      AC(J,J)=0.
C      CONTINUE
C      WRITE (110) (DC(J),J=1,NRS)
C      CONTINUE
C      IF (IABS(PRINT).LT.4) GO TO 300
C      WRITE (6,370) I
C      WRITE (6,330) NWING
C      WRITE (6,360) UC(J),J=1,NWING
C      WRITE (6,6) VC(J),J=1,NWING
C      WRITE (6,6) WC(J),J=1,NWING
C      WRITE (6,340) NWING
C      WRITE (6,360) AC(J),J=1,NWING
C      IF (NWING.GT.NMAX) WRITE (6,350) NR
C      IF (NWING.GT.NMAX) WRITE (6,360) DC(J),J=1,NRS
C      WRITE (8) UC(J),VC(J),WC(J),J=1,NWING
C      WRITE (9) AC(J),J=1,NWING
C      CONTINUE
C      RETURN
C      WRITE (6,380)
C      CALL EXIT
C
C      280 FORMAT (2X,10HUC(J),J=1,13)
C      340 FORMAT (2X,10HAC(J),J=1,13)
C      350 FORMAT (2X,10HDC(J),J=1,13)
C      360 FORMAT (1H0,10F10.5)
C      370 FORMAT (1H0,22HAERODYNAMIC MATRIX, I=13)
C      380 FORMAT (1H0,43HERROR - WING PANEL SLOPE EXCEEDS MACH ANGLE)
C      END

```

```

SUBROUTINE VORPAN (UC, VC, WC, UL, VL, ML, ULT, VLT, MLT, VE, WE, VA, WA)
C
C COMPUTE THE THREE COMPONENTS OF VELOCITY INDUCED AT A SPECIFIED
C CONTROL POINT BY CONSTANT AND LINEARLY VARYING VORTEX
C DISTRIBUTIONS ON A SWEEP QUADRILATERAL PANEL. ALSO COMPUTE THE
C THREE COMPONENTS OF VELOCITY INDUCED BY THE CONCENTRATED VORTEX
C LYING ALONG THE DOWNSTREAM EXTENSION OF THE INBOARD EDGE AS WELL
C AS THE VORTEX SHEET LOCATED DOWNSTREAM OF THE TRAILING EDGE
C BETWEEN THE INBOARD EDGE AND THE INTERSECTION OF THE LEADING AND
C TRAILING EDGES OF THE PANEL.
C
C UC, VC, WC ARE VELOCITY COMPONENTS INDUCED BY CONSTANT CHORDWISE
C AND SPANWISE VORTEX DISTRIBUTION
C
C UL, VL, ML, ARE VELOCITY COMPONENTS INDUCED BY LEADING EDGE OF
C LINEAR CHORDWISE, CONSTANT SPANWISE VORTEX DISTRIBUTION
C
C ULT, VLT, MLT ARE VELOCITY COMPONENTS INDUCED BY TRAILING EDGE OF
C LINEAR CHORDWISE, CONSTANT SPANWISE VORTEX DISTRIBUTION
C
C VE, WE ARE VELOCITY COMPONENTS INDUCED BY CONCENTRATED VORTICES
C IN THE WAKE
C
C VA, WA ARE VELOCITY COMPONENTS INDUCED BY VORTEX SHEET IN THE
C WAKE
C
C COMMON /PARAM/ NBODY, NWING, NTAIL, LBC, THK, MACH, ALPHA, REFA
C COMMON /COMPS/ X, Y, Z, A, B, C, SUB, BPOS, ML, NS
C DIMENSION Q(51), XI(51), XQ(51)
C LOGICAL SUB, SUP, BPOS, SUPLE, LBC
C
C DATA EPS/1.0E-6/, PI/3.14159265/
C IF (ABS(C).LE.EPS) C=0.
C CC=C*C
C SUP=.NOT.SUB
C SUPLE=.FALSE.
C IF (ABS(B).LE.EPS) B=0.
C AB=A+B
C SGN=1.0
C IF ((SUP)) SGN=-1.0
C B1=SGN*B*B
C SB1=SQRT(ABS(B))
C
Y 10
Y 20
Y 30
Y 40
Y 50
Y 60
Y 70
Y 80
Y 90
Y 100
Y 110
Y 120
Y 130
Y 140
Y 150
Y 160
Y 170
Y 180
Y 190
Y 200
Y 210
Y 220
Y 230
Y 240
Y 250
Y 260
Y 270
Y 280
Y 290
Y 300
Y 310
Y 320
Y 330
Y 340
Y 350
Y 360
Y 370
Y 380
Y 390
Y 400
Y 410
Y 420

```

```

IF (ABS(Y).LE.EPS) Y=0.
IF (ABS(Z).LE.EPS) Z=0.
X2=X*X
Y2=Y*Y
Z2=Z*Z
R2=Y2+Z2
R=SQRT(R2)
VA=0.
VE=0.
WA=0.
WE=0.
IF (SUB1 GO TO 10
IF (ABS(B).LT.1.0) SUPLE=.TRUE.
IF (X.LT.0.) GO TO 340
D=0.
D2=X2+SGN*R2
IF (D2.GT.0.) D=SQRT(D2)
AZ=A*Z
T1=C-A*Y
IF (ABS(T1).LE.EPS) T1=0.
T2=T1*T1
T3=X-B*Y
AT3=ABS(T3)
IF (AT3.LE.EPS) AT3=0.
T4=AZ*AZ
T5=T2+T4
IF (T5.NE.0.) T5=1./T5
T6=B*C-A*X
T7=T6*T6
T8=T7+SGN*(T2+T4)
T9=T1*T3+A*B*Z2
E=SQRT(ABS(T8))
B2=SGN*(C*Y-A*R2)
B3=B*X+SGN*Y
B4=T5*T6
T2=T3*T3+B1*Z2
IF (T2.GT.0.) ST3=SQRT(T2)
WQ=0.

C EVALUATION OF DOWNWASH INDUCED BY TRAILING VORTEX SHEET
C
C IF (A.EQ.0..OR..ML.EQ.2) GO TO 80
MAX=11
Y 430
Y 440
Y 450
Y 460
Y 470
Y 480
Y 490
Y 500
Y 510
Y 520
Y 530
Y 540
Y 550
Y 560
Y 570
Y 580
Y 590
Y 600
Y 610
Y 620
Y 630
Y 640
Y 650
Y 660
Y 670
Y 680
Y 690
Y 700
Y 710
Y 720
Y 730
Y 740
Y 750
Y 760
Y 770
Y 780
Y 790
Y 800
Y 810
Y 820
Y 830
Y 840
Y 850

```

```

XI(1)=0.
EL=1.0
IF (SUP.AND.X.LT.C) EL=X/C
DXI=EL/FLOAT(MAX-1)
X0=0.
IF (T1.NE.0.) X0=T3/T1
DO 70 M=1,MAX
    Q(M)=0.
    IF (M.GT.1) XI(M)=XI(M-1)+DXI
    DX=X-XI(M)*C
    IF (SUP.AND.DX.LT.0.) GO TO 60
    DX2=DX*DX
    BX=B-A*XI(M)
    BX2=BX*BX
    BX1=SGN+BX2
    SBX=SQRT(ABS(BX1))
    SDX=0.
    DXR=DX2+SGN*R2
    IF (DXR.GT.0.) SDX=SQRT(DXR)
    IF (SDX.EQ.0.) GO TO 20
    ARG=SGN*Y+BX*DX
    IF (SBX.EQ.0.) GO TO 40
    TZ1=(T3-XI(M)*T1)**2+BX1*TZ2
    IF (TZ1.EQ.0.) GO TO 50
    STZ=SQRT(TZ1)
    IF (SUP.AND.BX.LT.1.0) GO TO 30
    ARG=(ARG+SBX*SDX)/STZ
    IF (SUP) ARG=ABS(ARG)
    IF (ARG.GT.0.) Q(M)= ALOG(ARG)*BX/SBX
    GO TO 60
    IF (T1.LT.BX*T6.AND.T8.LT.0.) GO TO 60
    IF (Y.LE.BX*DX) GO TO 60
    IF (DX.LT.(BX*Y+SBX*ABS(Z))) GO TO 60
    Q(M)=PI*BX/SBX
    GO TO 60
    ARG=ARG/STZ
    IF (ARG.GT.1.0) GO TO 60
    IF (ARG.LE.-1.0) GO TO 20
    Q(M)=ACOS(ARG)*BX/SBX
    GO TO 60
    Q(M)=SDX*BX/ARG
    GO TO 60
    Q(M)=100.
20
30
40
50

```

```

IF (Y.LT.0.) Q(M)=-ALOG(ABS(Y).J.*BX/SBX
CONTINUE
Q(X|M)=Q(M)*X| (M)
Y1300
Y1310
CONTINUE
CALL TRAP (XI,QX,WQ,MAX)
Y1320
CONTINUE
IF (.NOT.SUPLE) GO TO 100
Y1330
Y1340
Y1350
Y1360
Y1370
Y1380
C
C SPECIAL EQUATIONS FOR SUPERSONIC LEADING EDGE
C
IF (D.GT.0.) GO TO 100
Y1390
IF (Y.LE.B*X) GO TO 340
Y1400
IF (X.LT.(B*Y+SBI*ABS(Z))) GO TO 340
Y1410
SZ=SIGN(1.0,Z)
Y1420
PZ=PI*SZ
Y1430
UC=PZ
Y1440
YC=-B*PZ
Y1450
WC=-SZ*SBI*PZ
Y1460
IF (T8.GT.0.) E=0.
Y1470
SL=PI*T5*(SZ*T9-Z*E)
Y1480
TL=SZ*E*T5*SL
Y1490
IF (T8.GT.0.) TL=PI*T5*T5*T8*ABS(Z)
Y1500
IF (ML.EQ.2) GO TO 90
Y1510
UL=SL
Y1520
YL=-((B+T1*B4)*SL-AZ*TL)*0.5
Y1530
WL=AZ*B4*SL-T1*TL+A*WQ
Y1540
IF (.NOT.LBC.AND.ML.EQ.1) GO TO 330
Y1550
ULS=SL+PZ
Y1560
UL=T=ULS
Y1570
TT=SZ*E*T5*ULS
Y1580
IF (T8.GT.0.) TT=TL
Y1590
YL=(A*PL-(AB+T1*B4)*ULS+AZ*TT)*0.5
Y1600
WLT=AZ*B4*ULS-T1*TT
Y1610
GO TO 330
Y1620
IF (SUP.AND.D.EQ.0.) GO TO 340
Y1630
IF (Z.EQ.0.) GO TO 190
Y1640
Y1650
Y1660
Y1670
C
C GENERAL EQUATIONS
C
DENOM=B*R2-X*Y
Y1680
F1=ATAN2(Z*D,DENOM)
Y1690
IF (SUBI) F1=F1-ATAN2(Z,Y)
Y1700
G1=0.
Y1710

```

```

IF (T8.EQ.0.) GO TO 130
IF (C.EQ.0.) GO TO 110
AR G=X*T6+B2
IF (T8.LT.0.) GO TO 120
ARG=(ARG+D*E)/(ST3*C)
IF (SUP) ARG=ABS(ARG)
IF (ARG.GT.0.) GI=ALOG(ARG)
GO TO 130
IF (ST3.NE.0.) GI=ALOG(ST3)
GO TO 130
Y1720
Y1730
Y1740
Y1750
Y1760
Y1770
Y1780
Y1790
Y1800
Y1810
Y1820
Y1830
Y1840
Y1850
Y1860
Y1870
Y1880
Y1890
Y1900
Y1910
Y1920
Y1930
Y1940
Y1950
Y1960
Y1970
Y1980
Y1990
Y2000
Y2010
Y2020
Y2030
Y2040
Y2050
Y2060
Y2070
Y2080
Y2090
Y2100
Y2110
Y2120
Y2130
Y2140

110
120
130
140
150
160
170
180
190
200
210
220
230
240
250
260
270
280
290
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410
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660
670
680
690
700
710
720
730
740
750
760
770
780
790
800
810
820
830
840
850
860
870
880
890
900
910
920
930
940
950
960
970
980
990

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```

C5=(D-X*C2)/C
160 IF (LBG) GO TO 170
C6=.50/R2 Y2160
1F (SUB) C6=C6*C1/D Y2170
C2=C2+C6*C Y2180
VB=-F1*.0.5 Y2190
WB=H2*.5 Y2200
VD=Z*C6 Y2210
WD=-Y*C6 Y2220
VA=VB Y2230
WA=WB Y2240
VE=VD Y2250
ME=MD Y2260
HO=HO-C4 Y2270
1F (ML.EQ.1) GO TO 170 Y2280
VC=VS+C*VDA+AVB Y2290
WC=WS+C*WDA+A*WB Y2300
Y2310
HO=HO-C4 Y2320
G=E*G1-T6*G2 Y2330
SL=T5*(T9*F1+Z*G) Y2340
TL=-B*D Y2350
IF (C.NE.0.) TL=(B2*C2+I6*D)/C Y2360
TL=-15*(T5*(G*T9-Z*T8*F1)+TL) Y2370
IF (ML.EQ.2) GO TO 180 Y2380
UL=SL Y2390
VL=-(LB+T1*B4)*SL-AZ*TL)*0.5+Z*C3 Y2400
WL=AZ*B4*SL-T1*TL-Y*C3+AWB Y2410
IF (NOT(LBC.AND.ML.EQ.1)) GO TO 330 Y2420
ULS=SL+F1 Y2430
ULF=ULS Y2440
TLT=TL-T5*G Y2450
WQT=C5-C4-G3*0.5 Y2460
VLS=(A*F1-(AB+T1*B4)*ULS+AZ*TL-Y*(C2+C3))+WQT Y2470
VLT=VLS Y2480
MLS=AZ*B4*ULS-T1*TL-Y*(C2+C3)+A*WQT Y2490
MLT=MLS Y2500
IF (LBG) GO TO 330 Y2510
VLT=VLS+AVB Y2520
MLT=MLS+AWB Y2530
GO TO 330 Y2540
C SPECIAL EQUATIONS FOR Z=0 Y2550
C CONTINUE " Y2560
C Y2570

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```

F1=0.
DENCM=-Y*T3
IF (DENCM.NE.0.) F1=ATAN2(C.,DENOM)
IF (SUB.AND.Y.NE.0.) F1=F1-ATAN2(0.,Y)
IF (NS.EQ.2) F1=-F1
G1=0.
IF (T8.EQ.0.) GO TO 230
IF (C.EQ.0.) GO TO 210
IF (T8.LT.0.) GO TO 220
IF (AT3.GT.0.) GO TO 200
IF (Y.EQ.0..OR.T1.LE.0.) GO TO 230
G1=ALOG(T1*ABS(Y))
IF (SUB.AND.Y.LT.0.) G1=-G1
IF (Y.GT.0.) G1=100.+G1
GO TO 230
ARG=(X*T6+SGN*Y*T1+D*E)/(AT3*C)
IF (SUP) ARG=ABS(ARG)
IF (ARG.GT.0.) G1=ALOG(ARG)
GO TO 230
IF (AT3.NE.0.) G1=ALOG(AT3)
GO TO 230
ARG=(X*T6-Y*T1)/(AT3*C)
IF (ABS(ARG).GT.1.0) GO TO 230
G1=-ACOS(ARG)
H1=0.
IF (LBC.AND.ML.EQ.2) GC TO 260
IF (SBI.EQ.0.) GO TO 260
IF (SUPLE) GO TO 250
IF (AT3.GT.0.) GO TO 240
IF (Y.EQ.0.) GO TO 260
H1=ALOG(ABS(Y))
IF (SUB.AND.Y.LT.0.) H1=-H1
IF (Y.GT.0.) H1=100.+H1
GO TO 260
CONTINUE
ARH=(B3+D*SB1)/AT3
IF (ARH.GT.0.) H1=ALOG(ARH)
GO TO 260
H1=-ACOS(B3/AT3)
G2=100.
IF (Y.NE.0.) GO TO 270
IF (X.NE.0.) G2=G2+ALOG(2.*ABS(X))
IF (X.LT.0.) G2=-G2

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```

GO TO 280
G2=ALOG((X+D)/ABS(Y))
280
G3=0.
C1=D
IF (.NOT.SUB). GO TO 290
C1=X+D
G3=-100.
Y3070
IF (Y=NE.0.). G3=ALOG(ABS(Y))
Y3080
C2=0.
IF (Y=NE.0.). C2=C1/Y2
Y3090
H=SBI*HL-B*(G2-G3)
Y3100
IF (SBI.EQ.0.) H2=B*D/B3-G2+G3
Y3110
IF (SBI.NE.0.) H2=B*HL/SBI-G2+G3
Y3120
UC=F1
Y3130
Y3140
VS=-B#F1
Y3150
WS=H-Y*C2
Y3160
VC=VS
Y3170
WC=WS
Y3180
IF (C.EQ.0.) C2=0.
Y3190
Y3200
C4=0.
Y3210
C5=G2*0.5
Y3220
IF (C.EQ.0.) GO TO 300
Y3230
C3=(X*C2+SGN#G2)*0.5
Y3240
C4=((X2-SGN#Y2*0.5)*G2-1.5*X*D)/(2.*CC)
Y3250
C5=(D-X*G2)/C
Y3260
IF (LBC) GO TO 310
Y3270
C6=0.
Y3280
IF (Y=NE.0.). C6=.50/Y2
Y3290
IF (SUB.AND.D.NE.0.) C6=C6*C1/D
Y3300
C2=C2+C6*C
Y3310
VB=-F1*0.5
Y3320
WB=H2*0.5
Y3330
WD=-Y*C6
Y3340
VA=VB
Y3350
WA=WB
Y3360
WE=WD
Y3370
IF (HL.EQ.1) GO TO 310
Y3380
VC=VS+A*VB
Y3390
WC=WS+A*WB+C*WD
Y3400
WQ=WQ-C4
Y3410
WQT=C5-C4-G3#0.5
Y3420
IF (TL.NE.0.) GO TO 320
Y3430
WL=A*WQ

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```

ML S=A*WQT          Y3440
WL T=WL S          Y3450
IF (.NOT.LBC) WL T=WL S+A*WB  Y3460
GO TO 350          Y3470
SL=T3*F1/T1        Y3480
UL=SL              Y3490
VL=-(B+T6/T1)*SL*0.5 Y3500
G=E*G1-T6*G2      Y3510
TL=T3*T5*G        Y3520
IF (C.EQ.0.) TL=TL-B*D/T1  Y3530
IF (C.NE.0.) TL=TL+(T6*D/T1+Y*(SGN*G2-C3))/C  Y3540
WL=TL+A*WQT       Y3550
IF (.NOT.LBC.AND.ML.EQ.1) GO TO 330  Y3560
UL S=SL+F1        Y3570
VL S=(A*F1-(AB+T6/T1)*UL S)*0.5 Y3580
WL S=TL+G/T1-Y*C2+A*WQT       Y3590
ULT=ULS            Y3600
VLT=VLS            Y3610
WL T=WL S          Y3620
IF (LBC) GO TO 330  Y3630
VLT=VLS+A*VB      Y3640
WL T=WL S+A*WB    Y3650
RETURN             Y3660
330   UC=0.          Y3670
      VC=0.          Y3680
      WC=0.          Y3690
      WL=0.          Y3700
      WL T=0.         Y3710
      UL T=0.         Y3720
      VL T=0.         Y3730
      UL T=0.         Y3740
      VL T=0.         Y3750
      IF (C.EQ.0.) GO TO 330  Y3760
      RETURN           Y3770
END                Y3780

```

```

Z 10
Z 20
Z 30
Z 40
Z 50
Z 60
Z 70
Z 80
Z 90
Z 100
Z 110
Z 120
Z 130
Z 140
Z 150
Z 160
Z 170

SUBROUTINE TRANS (UR,VR,WR,UL,VL,WL,U,V,W,A)
C
C   TRANSFORM THE THREE COMPONENTS OF VELOCITY FROM THE PANEL
C   COORDINATE SYSTEM TO THE REFERENCE COORDINATE SYSTEM. ALSO COMBINE
C   THE CONTRIBUTIONS OF THE LEFT AND RIGHT WING PANELS AND CALCULATE
C   THE NORMAL VELOCITY AT THE CONTROL POINT.
C
C   COMMON /TRAN/ SIND,COSD,TAND,SINT,COST,CONTD,SINTI,COSTI,CON,BCON,
IDI
C
VW=SINT*(VR+VL)+CONTD*(WR+WL)
U=CON*(COST*(UR+UL)-SINC*VW)/CONTD
V=BCCN*COSD*(CONTD*(VR-VL)-SINT*(WR-WL))
W=BCON*(TAND*(UR+UL)+COST*COSD*VW)/CONTD
A=COSTI*W-SINTI*V-DI*U
RETURN
END

```

OVERLAY(LWB,3,0) PROGRAM SOLVE

SOLVE FOR THE STRENGTHS OF THE BODY SOURCES AND WING VORTICES WHICH SATISFY THE BOUNDARY CONDITION OF TANGENTIAL FLOW AT THE PANEL CONTROL POINTS. ALSO DETERMINE THE CORRESPONDING PRESSURE DISTRIBUTION AND THE FORCES AND MOMENTS ON THE CONFIGURATION.

THE PROGRAM MUST SOLVE A SYSTEM OF LINEAR EQUATIONS OF MAXIMUM ORDER 1200. THE SOLUTION TECHNIQUE SELECTED CAN BE DESCRIBED AS A BLOCKED JACOBI ITERATIVE METHOD. THE 1200 BY 1200 MATRIX IS NATURALLY PARTITIONED INTO FOUR 600 BY 600 BLOCKS. EACH PARTITION IS FURTHER SUBDIVIDED INTO BLOCKS OF MAXIMUM SIZE 60 BY 60. THE MATRIX ELEMENTS IN EACH BLOCK ARE CAREFULLY CHOSEN TO REPRESENT SOME WELL DEFINED FEATURE OF THE ORIGINAL CONFIGURATION. FOR EXAMPLE, A BODY BLOCK REPRESENTS THE INFLUENCE OF ONE RING OF PANELS AROUND THE BODY, WHILE A WING BLOCK REPRESENTS THE INFLUENCE OF ONE CHORDWISE COLUMN OF WING PANELS. FOR WINGS USING THE NON-PLANAR BOUNDARY CONDITION OPTION, THE BLOCK SIZE CORRESPONDS TO THE TOTAL NUMBER OF PANELS ON THE UPPER AND LOWER SURFACES OF THE COLUMN.

THE INITIAL ITERATION CALCULATES THE SINGULARITY STRENGTHS CORRESPONDING TO EACH BLOCK IN ISOLATION. FOR THIS STEP, ONLY THE DIAGONAL BLOCKS ARE PRESENT IN THE AERODYNAMIC MATRIX. ONCE THE INITIAL APPROXIMATION TO THE SINGULARITY STRENGTHS IS DETERMINED, THE INTERFERENCE EFFECT OF EACH BLOCK ON ALL THE OTHERS IS CALCULATED BY MATRIX MULTIPLICATION. THE INCREMENTAL NORMAL VELOCITIES OBTAINED ARE SUBTRACTED FROM THE NORMAL VELOCITIES SPECIFIED BY THE BOUNDARY CONDITIONS. THIS PROCESS IS ITERATED A FIXED NUMBER OF TIMES AT PRESENT. THE NUMBER OF ITERATIONS IS SET IN SUBROUTINE ITRATE.

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COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /POINT/ ARRAY(6000)
COMMON /SCRAT/ U(600),V(600),W(600),A(60,60),DUD(300),GWI(600),
               DUTUX(600)
COMMON /SEG/ NSEG, NR(20), NC(20), DUM(60)
COMMON /VELCCM/ NPGINT,NPART,IMAX,JMAX,NMAX,EX,PRINT,NWTNK
COMMON /FORM/ CN,CT,CNBT,CNS(20),CTS(20),CMS(20)

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COMMON /MATCCM/ MATIN
C
C      DIMENSION U(A(600), VA(600), WA(600), CP(600), NS(600),
C      1 THET(600), DELTA(600), NW(600), NT(600), DEL(600), COSTH AA 430
C      2(600) AA 440
C
C      EQUIVALENCE (UA,A), (VA,A(601)), (WA,A(1201)), (CP,A(1801)), (NS,A AA 450
C      1(2401)), (ARRAY(1801),THET), (AKRAY(2401),DELTA), (NW,U), (NB,V), AA 460
C      2INT,W), (ARRAY(3601),CHORD), (GW,DEL), (GB,COSTH) AA 470
C
C      REAL MACH,NB,NW,NT,NS AA 480
C      INTEGER CCPT,PRINT AA 490
C      LOGICAL LBC,THK,LOWER AA 500
C
C      EM=MACH AA 510
C      NPASS=0 AA 520
C      REWIND 7 AA 530
C      REWIND 8 AA 540
C      ALP=ALPHA/57.2957795 AA 550
C      SINAL=SIN(ALP)
C      COSAL=COS(ALP) AA 560
C
C      CALCULATE NORMAL VELOCITIES REQUIRED TO SATISFY BOUNDARY AA 570
C      CONDITIONS AT WING AND BODY CONTROL POINTS AA 580
C
C      IF (NWING.EQ.0) GO TO 20 AA 590
C      READ (7) ARRAY,CHORD,DZDX AA 600
C      IF (LBC) READ (11) DEL,CCSTH AA 610
C      REWIND 11 AA 620
C      DO 10 I=1,NWING AA 630
C      IF (LBC) TANDEL=DEL(I) AA 640
C      IF (.NOT..LBC) TANDEL=TAN(DELTA(I)) AA 650
C      IF (LBC) CCST=COSTH(I) AA 660
C      IF (.NOT..LBC) COST=COS(THET(I))
C      NW(I)=COSAL*TANDEL-SINAL*COST AA 670
C      IF (NBODY.EQ.0) GO TO 70 AA 680
C      READ (7) ARRAY AA 690
C      REWIND 11 AA 700
C      DO 10 I=1,NWING AA 710
C      IF (LBC) TANDEL=DEL(I)
C      IF (.NOT..LBC) TANDEL=TAN(DELTA(I))
C      IF (LBC) CCST=COSTH(I)
C      IF (.NOT..LBC) COST=COS(THET(I))
C      NB(I)=COSAL*TANDEL-SINAL*COST AA 720
C      IF (NBODY.EQ.0) GO TO 70 AA 730
C      READ (7) ARRAY AA 740
C      REWIND 11 AA 750
C      DO 30 I=1,NBODY AA 760
C      TANDEL=TAN(DELTA(I))
C      NB(I)=COSAL*TANDEL-SINAL*COS(THET(I))
C      IF (.NOT..LBC.JR.NWING.EQ.0) GO TO 70 AA 770
C      IF (.NOT..THK) GO TO 70 AA 780
C      READ (7) ARRAY AA 790
C      REWIND 11 AA 800
C      DO 30 I=1,NBODY AA 810
C      NB(I)=COSAL*TANDEL-SINAL*COS(THET(I))
C      IF (.NOT..LBC.JR.NWING.EQ.0) GO TO 70 AA 820
C      IF (.NOT..THK) GO TO 70 AA 830
C      READ (7) ARRAY AA 840
C      REWIND 11 AA 850
C

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C CALCULATE NORMAL VELOCITIES ON BODY PANELS DUE TO
C WING THICKNESS (PLANAR BOUNDARY CONDITION OPTION)
C
DU 40 I=1,NBODY
READ (8) (UA(IJ),VA(IJ),WA(IJ),J=1,NBODY)
CONTINUE
DU 60 I=1,NBODY
READ (8) (UA(IJ),VA(IJ),WA(IJ),J=1,NWTHK)
READ (8) (UAUDUM,VADUM,WADUM,J=1,NWING)
US=0.
VS=0.
WS=0.
SINT=SIN(THET(I))
COST=COS(THET(I))
DO 50 J=1,NWTHK
US=US+UA(J)*DZTDX(J)
VS=VS+VA(J)*DZTDX(J)
WS=WS+WA(J)*DZTDX(J)
NS(I)=WS*COST-VS*SINT-US*TAN(DELTA(I))
NB(I)=NB(I)-NS(I)*COSAL
REWIND 8
CONTINUE
C SOLVE MATRIX EQUATIONS - DIRECT SOLUTION IF MATRICES
C LESS THAN 60 BY 60, ITERATIVE SOLUTION OTHERWISE
C
IF (NBODY.LE.NMAX.AND.NWING.LE.NMAX) GC TO 80
IF (IMATIN.EQ.1) CALL DIAGIN
REWIND 10
GO TO 90
CALL PARTIN
IF (NBODY.EQ.0.OR.NWING.EQ.0) GO TO 100
CALL ITRATE
CONTINUE
REWIND 7
IF (NWING.EQ.0) GO TO 110
READ (7) ARRAY,CHORD,DZTUX
CONTINUE
NPASS=NPASS+1
IF (NBODY.EQ.0) GO TO 210
C CALCULATE VELOCITY COMPONENTS ON BODY PANELS
C

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DO 120 I=1,NBODY
U(I)=0.
V(I)=0.
W(I)=0.
CONTINUE
DO 130 I=1,NBODY
READ (8) (UA(I),VA(I),WA(I),J=1,NBODY)
IF (INPASS.EQ.2) GO TO 130
DO 130 J=1,NBODY
U(I)=U(I)+UA(J)*GB(J)
V(I)=V(I)+VA(J)*GB(J)
W(I)=W(I)+WA(J)*GB(J)
CONTINUE
IF (INPASS.EQ.1) READ (7) ARRAY
DO 180 I=1,NBODY
IF (NWING.EQ.0) GO TO 170
IF (.NOT.THK) GO TO 150
READ (8) (UA(J),VA(J),WA(J),J=1,NWTHK)
IF (INPASS.EQ.2) GO TO 150
DO 140 J=1,NWTHK
U(I)=U(I)+UA(J)*DZTDX(J)
V(I)=V(I)+VA(J)*DZTDX(J)
W(I)=W(I)+WA(J)*DZTDX(J)
CONTINUE
READ (8) (UA(J),VA(J),WA(J),J=1,NWING)
IF (INPASS.EQ.2) GO TO 180
DO 160 J=1,NWING
U(I)=U(I)+UA(J)*GW(J)
V(I)=V(I)+VA(J)*GW(J)
W(I)=W(I)+WA(J)*GW(J)
CONTINUE
150 NS(I)=W(I)*COS(THET(I))-V(I)*SIN(THET(I))-U(I)*TAN(DELTA(I))
160 CONTINUE
170 IF (INPASS.EQ.2) GO TO 210
IF (ABS(PKINT).LT.2) GO TO 200
WRITE (6,340) ER,ALPHA
WRITE (6,390)
DO 190 N=1,NBODY
WRITE (6,410) N,GB(N),U(N),V(N),W(N),NS(N)
200 CONTINUE
C CALCULATE PRESSURES ON BODY PANELS

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C CALL PRESS (NPASS,EM,ALP,U,V,W,CP,CPSTAG,CPCRIT,CPVAC)
C CALCULATE FORCES AND MOMENT ON BODY
C
C COMPT=1
    CALL FCRMOM (NBODY,NPASS,ALP,COMPT)
    IF (NWING.EQ.0) GO TO 330
C CALCULATE VELOCITY COMPONENTS ON WING PANELS
C
DO 220 I=1,NWING
U(I)=0.
V(I)=0.
W(I)=0.
220
IF (NBODY.EQ.0) GO TO 240
DO 230 I=1,NWING
READ (8) UAI(J),VA(J),WA(J),J=1,NBODY
DO 230 J=1,NBODY
U(I)=U(I)+UAI(J)*GB(J)
V(I)=V(I)+VA(J)*GB(J)
W(I)=W(I)+WA(J)*GB(J)
CONTINUE
230
SGN=1.0
IF (LBC.AND.NPASS.EQ.2) SGN=-1.0
DO 270 I=1,NWING
IF (.NOT.THK) GO TO 260
READ (8) UAI(J),VA(J),WA(J),J=1,NWTHK
DO 250 J=1,NWTHK
U(I)=U(I)+UAI(J)*DZTDX(J)
V(I)=V(I)+VA(J)*DZTDX(J)
W(I)=W(I)+WA(J)*DZTDX(J)*SGN
READ (8) UAI(J),VA(J),WA(J),J=1,NWING
DO 270 J=1,NWING
U(I)=U(I)+UAI(J)*Gw(J)*SGN
V(I)=V(I)+VA(J)*Gw(J)*SGN
W(I)=W(I)+WA(J)*Gw(J)
250
260
CONTINUE
270
IF (IABS(IPRINT).LT.2) GO TO 310
IF (.NOT.LBC) GC TC 280
IF (NPASS.EQ.1) WRITE (6,360) EM,ALPHA
IF (NPASS.EQ.2) WRITE (6,370) EM,ALPHA
GO TO 290

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280      WRITE (6,350) EM,ALPHA          AA2150
290      WRITE (6,400)                  AA2160
DO 300 N=1,NWING
300      WRITE (6,410) N,G(N),U(N),V(N),W(N)
310      CONTINUE

C      CALCULATE PRESSURES ON WING PANELS           AA2170
C      CALL PRESS (NWING,EM,ALP,U,V,W,CP,CPSTAG,CPCRIT,CPVAC) AA2180
C      CALCULATE FORCES AND MOMENT ON WING AND TAIL AA2190
C      COMPT=2                                         AA2200
C      CALL FUNKNUM (NWING,NPASS,ALP,COMPT)          AA2210
C      IF (LBC.ANC.NPASS.EQ.1) GO TO 320            AA2220
C      GO TO 330                                         AA2230
C      REWIND 8                                         AA2240
C      GO TO 110                                         AA2250
C      CONTINUE                                         AA2260
C      WRITE (6,380) CPSTAG,CPCRIT,CPVAC           AA2270
C      REWIND 7                                         AA2280
C      WRITE (6,380) CPSTAG,CPCRIT,CPVAC           AA2290
C      CALL SECOND (TIME)                          AA2300
C      WRITE (6,420) TIME                         AA2310
C      RETURN                                         AA2320
C      FORMAT (1H1,25HVELOCITIES ON BODY, MACH=,F5.3,3X,6HALPHA=,F7.3//) AA2330
C      FORMAT (1H1,25HVELOCITIES ON WING, MACH=,F5.3,3X,6HALPHA=,F7.3//) AA2340
C      FORMAT (1H1,39HVELOCITIES ON WING UPPER SURFACE, MACH=,F5.3,3X,6HA AA2350
C      LPHA=,F7.3//)                                AA2360
C      FORMAT (1H1,39HVELOCITIES ON WING LOWER SURFACE, MACH=,F5.3,3X,6HA AA2370
C      LPHA=,F7.3//)                                AA2380
C      FORMAT (1H0,8HCPCRIT =F10.5,3X,7HCPCRIT =F10.5,3X,7HCPCRIT =F10.5) AA2390
C      FORMAT (1X,5HPANEL,10X,6HSOURCE,10X,2HAXIAL,10X,7HLATERAL,10X,8HVE AA2400
C      LRTICAL,10X,6HNORMAL/2X,3HNO.,10X,8HSTRENGTH,7X,8HVELOCITY,9X,8HVEL AA2410
C      LOCITY,9X,8HVELOCITY,9X,6HVELOCITY)           AA2420
C      FORMAT (1X,5HPANEL,10X,6HVORTEX,10X,5HAXIAL,10X,7HLATERAL,10X,8HVE AA2430
C      LRTICAL/2X,3HNO.,10X,8HSTRENGTH,7X,8HVELOCITY,9X,8HVEL AA2440
C      LOCITY//)                                    AA2450
C      FORMAT (1H *14*7X,F10.5,5X,F10.5,3(7X,F10.5)) AA2460
C      FORMAT (1H0,6HTIME =F10.5)                   AA2470
C      END                                           AA2480
C

```

```

C          SUBROUTINE INVERT (A,IA,NROWS)
C          SIMPLE MATRIX INVERSION ROUTINE BASED ON GAUSS-JORDAN ELIMINATION
C          WITHOUT PIVOTING
C
      REAL A(NROWS,NROWS),PIVCT,T
      INTEGER IPIVOT(115),INDXR(115),INDXC(115)
      N=IA
      DO 10 J=1,N
         IPIVOT(J)=0
      DO 100 I=1,N
         T=0.0
         DO 30 J=1,N
            IF (IPIVOT(J).EQ.1) GO TO 30
         DO 20 K=1,N
            IF (IPIVOT(K).EQ.1) GO TO 20
            IF (.NOT.(ABS(A(I,J,K))-ABS(T).GT.0.0)) GO TO 20
            IROW=J
            ICOL=K
            T=A(J,K)
            CONTINUE
         CONTINUE
            IPIVOT(ICOL)=IPIVOT(ICOL)+1
            IF (IROW.EQ.ICOL) GO TO 50
         DO 40 L=1,N
            T=A(IROW,L)
            A(ICOL,L)=A(ICOL,L)
            A(ICOL,L)=T
            INDXR(L)=IROW
            INDXC(L)=ICOL
            PIVOT=A(ICOL,ICOL)
            IF (PIVOT) 60,130,60
            60   A(ICOL,ICOL)=1.0
            DO 70 L=1,N
               A(ICOL,L)=A(ICOL,L)/PIVOT
            70   DO 90 L=1,N
               IF (L.EQ.ICOL) GO TO 90
               T=A(IL,ICOL)
               A(IL,ICOL)=0.0
               DO 80 M=1,N
                  A(L,M)=A(L,M)-A(ICOL,M)*T
               80   CONTINUE
            90
      10
      20
      30
      40
      50
      60
      70
      80
      90
      AB 10
      AB 20
      AB 30
      AB 40
      AB 50
      AB 60
      AB 70
      AB 80
      AB 90
      AB 100
      AB 110
      AB 120
      AB 130
      AB 140
      AB 150
      AB 160
      AB 170
      AB 180
      AB 190
      AB 200
      AB 210
      AB 220
      AB 230
      AB 240
      AB 250
      AB 260
      AB 270
      AB 280
      AB 290
      AB 300
      AB 310
      AB 320
      AB 330
      AB 340
      AB 350
      AB 360
      AB 370
      AB 380
      AB 390
      AB 400
      AB 410
      AB 420

```

```

100  CONTINUE
    DO 120 J=1,N
      L=N+1-I
      IF ((INDXR(L).EQ.INDXC(L)) GO TO 120
      IROW=INDXR(L)
      ICOL=INDXC(L)
      DO 110 K=1,N
        T=A(K,IROW)
        A(K,IROW)=A(K,ICOL)
        A(K,ICOL)=T
      110  CONTINUE
      120  CONTINUE
C     SUCCESSFUL SOLUTION
C     RETURN
C     CONTINUE
130  CONTINUE
C     SINGULAR MATRIX
C     WRITE (6,140)
C     CALL EXIT
C
C     FORMAT (29H ERROR THE MATRIX IS SINGULAR)
140  END
AB 430
AB 440
AB 450
AB 460
AB 470
AB 480
AB 490
AB 500
AB 510
AB 520
AB 530
AB 540
AB 550
AB 560
AB 570
AB 580
AB 590
AB 600
AB 610
AB 620
AB 630
AB 640
AB 650
AB 660
AB 670
AB 680

```

SUBROUTINE PARTIN

```
C FOR WING-BODY COMBINATIONS, INVERT THE MATRIX PARTITIONS ( PROVIDED
C THE ORDER DOES NOT EXCEED 60).
C
C FOR ISOLATED WINGS OR BODIES, ALSO SOLVE THE BOUNDARY CONDITION
C EQUATIONS AND DETERMINE THE WING VORTEX STRENGTHS OR BODY SOURCE
C STRENGTHS.
C
C
COMMON /PARAH/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /SEG/ NSEG,NR(20),DUD(80)
COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EX,PRINT,NWTHK
COMMON /POINT/ ARRAY(4800)
COMMON /SCRAT/ NW(600),NB(600),NT(600),A(60,60),DUM(300),GM(600),G
1B(600),GT(600)
DIMENSION D(60,60)
EQUIVALENCE (D,ARRAY)
REAL NW,NB,NT
CALL SECOND (TIME)
NDIM=60
WRITE (6,110) TIME
REWIND 9
NPANEL=NBODY+NWING
IF (NWING.EQ.0.OR.NBODY.EQ.0) GO TO 50
IP=0
REWIND 10
DO 10 I=1,NBODY
READ (9) (D(I,J),J=1,NBODY)
CALL INVERT (D,NBODY,NDIM)
WRITE (10) D
DO 20 I=1,NBODY
READ (9) (D(I,J),J=1,NWING)
DO 30 I=1,NWING
READ (9) (D(I,J),J=1,NBODY)
DO 40 I=1,NWING
READ (9) (D(I,J),J=1,NWING)
CALL INVERT (D,NWING,NDIM)
WRITE (10) D
REWIND 9
REWIND 10
GO TO 100
AC 10
AC 20
AC 30
AC 40
AC 50
AC 60
AC 70
AC 80
AC 90
AC 100
AC 110
AC 120
AC 130
AC 140
AC 150
AC 160
AC 170
AC 180
AC 190
AC 200
AC 210
AC 220
AC 230
AC 240
AC 250
AC 260
AC 270
AC 280
AC 290
AC 300
AC 310
AC 320
AC 330
AC 340
AC 350
AC 360
AC 370
AC 380
AC 390
AC 400
AC 410
AC 420
```

```

50  CONTINUE
DO 60 I=1,NPANEL
READ (9) (A(I,J),J=1,NPANEL)
REWIND 9
CALL INVERT (A,NPANEL,NDIM)
IF (NWING.EQ.0) GO TO 80
DO 70 I=1,NWING
GW(I)=0.
DO 70 J=1,NWING
GW(I)=GW(I)+A(I,J)*NW(J)
CONTINUE
GO TO 100
DO 90 I=1,NBODY
GB(I)=0.
DO 90 J=1,NBODY
GB(I)=GB(I)+A(I,J)*NB(J)
CONTINUE
100 CALL SECOND (TIME)
WRITE (6,110) TIME
REWIND 9
RETURN
C
C
110 FORMAT (1HO,6HTIME -F10.5)
END

```

SUBROUTINE DIAGIN

```

C   INVERT THE DIAGONAL BLOCKS OF THE MATRIX.
C
COMMON /PARAM/ NBODY,NSEG,NR(20),DUD(80)
COMMON /SEG/ NSEG,NR(20),DUD(80)
COMMON /VELCOM/ NPOINT,NPART,IMAX,JMAX,NMAX,EM,PRINT,NWTHK,NMBLOK,
1NROW(20),NBBLOK,NBROW(30)
COMMON /POINT/ ARRAY(4800)
DIMENSION D(60,60)
EQUIVALENCE (D,ARRAY)
REWIND 9
REWIND 10
NDIM=60
IF (NBODY.EQ.0) GO TO 50
DO 40 NB=1,NBBLOK
NROW=NBROW(NB)
NCOL=NROW
IF (NBODY.GT.NMAX) GO TO 20
DO 10 I=1,NBODY
READ (9) (D(I,J),J=1,NBODY)
GO TO 30
READ (7) D
CALL INVERT (D,NCOL,NDIM)
WRITE (10) 0
CONTINUE
IF (NWING.EQ.0) GO TO 140
DO 130 NW=1,NMBLOK
NROW=NWROW(NW)
NCOL=NROW
IF (NWING.GT.NMAX) GO TO 110
IF (NBODY.EQ.0) GO TO 90
DO 60 I=1,NBODY
READ (9) (D(I,J),J=1,NBODY)
DO 70 I=1,NBODY
READ (9) (D(I,J),J=1,NWING)
DO 80 I=1,NWING
READ (9) (D(I,J),J=1,NBODY)
DO 90 I=1,NWING
READ (9) (D(I,J),J=1,NWING)
DO 100 I=1,NWING
READ (9) (D(I,J),J=1,NWING)
GO TO 120
READ (7) D
      10 AD 10
      20 AD 20
      30 AD 30
      40 AD 40
      50 AD 50
      60 AD 60
      70 AD 70
      80 AD 80
      90 AD 90
     100 AD 100
     110 AD 110
     120 AD 120
     130 AD 130
     140 AD 140
     150 AD 150
     160 AD 160
     170 AD 170
     180 AD 180
     190 AD 190
     200 AD 200
     210 AD 210
     220 AD 220
     230 AD 230
     240 AD 240
     250 AD 250
     260 AD 260
     270 AD 270
     280 AD 280
     290 AD 290
     300 AD 300
     310 AD 310
     320 AD 320
     330 AD 330
     340 AD 340
     350 AD 350
     360 AD 360
     370 AD 370
     380 AD 380
     390 AD 390
     400 AD 400
     410 AD 410
     420 AD 420

```

```
120 CALL INVERT (D,NCOL,NDIM)
      WRITE (10) 0
      CONTINUE
130   REWIND 10
140   REWIND 9
      REWIND 7
      RETURN
      END
```

```
AD 430
AD 440
AD 450
AD 460
AD 470
AD 480
AD 490
AD 500
```

SUBROUTINE ITRATE

```

C      SOLVE THE BOUNDARY CONDITION EQUATIONS BY AN ITERATIVE METHOD AND
C      DETERMINE THE STRENGTHS OF THE BODY SOURCES AND THE WING, FIN
C      (VERTICAL TAIL), AND CANARD (HORIZONTAL TAIL) VORTICES.
C
C      NOTE THAT THE NUMBER OF ITERATIONS IS FIXED AT PRESENT
C
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA
COMMON /SEG/ NSEG,NR(120),DUD(80)
COMMON /VELCOM/ NPCINT,NPART,IMAX,JMAX,NMAX,EM,PRINT,NWTHK,NWBLOK,
  INROW(120),NBBLOK,NBROW(30)
COMMON /POINT/ D(60,60),DNB(600),DNW(600)
COMMON /SCRAT/ NB(600),NB(600),NT(600),A(600),RW(600),RBI(600),DUM(12100),
  GW(600),GB(600),GT(600)
C
REAL NB,NW,NT
INTEGER PRINT
C
C      SET MAXIMUM NUMBER OF ITERATIONS - IMAX
C
C      IMAX=15
C
C      IT=0
REWIND 9
IF (INBODY.EQ.0) GO TO 20
DO 10 N=1,NBODY
  RB(N)=NB(N)
10   IF (NWING.EQ.0) GO TO 40
    DO 30 N=1,NWING
      RW(N)=NW(N)
30   IT=IT+1
CALL SECCND (TIME)
WRITE (6,240) TIME
  IB=0
  IW=0
  IF (INBODY.EQ.0) GO TO 70
  JS=0
  NBLUK=NBB LCK
  DO 60 NN=1,NBLCK
    NROW=NBRUN(NN)
    NCOL=NROW
AE 10
AE 20
AE 30
AE 40
AE 50
AE 60
AE 70
AE 80
AE 90
AE 100
AE 110
AE 120
AE 130
AE 140
AE 150
AE 160
AE 170
AE 180
AE 190
AE 200
AE 210
AE 220
AE 230
AE 240
AE 250
AE 260
AE 270
AE 280
AE 290
AE 300
AE 310
AE 320
AE 330
AE 340
AE 350
AE 360
AE 370
AE 380
AE 390
AE 400
AE 410
AE 420
20   IF (INBODY.EQ.0) GO TO 70
    JS=0
    NBLUK=NBB LCK
    DO 60 NN=1,NBLCK
      NROW=NBRUN(NN)
      NCOL=NROW

```

```

      READ (10) D
      DO 50 I=1,NROW
        IB=IB+1
        GB(IB)=0.
      DO 50 J=1,NCOL
        JJ=J+JS
        GB(IB)=GB(IB)+D(I,J)*RB(JJ)
        JS=JS+NROW
      CONTINUE
      IF (NWING.EQ.0) GO TO 100
      JS=0
      NBLOCK=NWBLOCK
      DO 90 NN=1,NBLOK
        NROW=NWRDN(NN)
        NCOL=NROW
        READ (10) D
        DO 80 I=1,NROW
          IW=IW+1
          GW(IW)=0.
        DO 80 J=1,NCOL
          JJ=J+JS
          GW(IW)=GW(IW)+D(I,J)*RW(JJ)
        JS=JS+NROW
      CONTINUE
      REWIND 10
      IF (IABS(PRINT).LT.3) GO TO 110
      WRITE (6,250) IT
      IF (INBODY.LE.0) WRITE (6,260) (GB(N),N=1,NBCDY)
      IF (NWING.LE.0) WRITE (6,260) (GW(N),N=1,NWING)
      IF (IT.EC.IMAX) GO TO 230
      IF (INBODY.EQ.0) GO TO 170
      DO 130 I=1,NBODY
        DNB(I)=0.
      READ (9) (A(J),J=1,NBCDY)
      IF (INBODY.LE.NMAX) GO TO 130
      DO 120 J=1,NBODY
        DNB(I)=UNB(I)+A(J)*GB(J)
        RB(I)=NB(I)-DNB(I)
      120   IF (NWING.EQ.0) GO TO 160
      DO 150 I=1,NBODY
        READ (9) (A(J),J=1,NWING)
      DO 140 J=1,NWING

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```

140      DNB(I)=DNB(I)+A(J)*GW(J)
150      RBC(I)=NB(I)-DNB(I)
160      CONTINUE
170      IF (NWING.EQ.0) GO TO 220
DO 190 I=1,NWING
DNW(I)=0.
IF (NBODY.EQ.0) GO TO 190
READ (9) (A(J),J=1,NBODY)
DU 180 J=1,NBODY
180      DNW(I)=DNW(I)+A(J)*GB(J)
RNW(I)=NW(I)-DNW(I)
IF (NWING.LE.NMAX) GO TO 220
DO 210 I=1,NWING
READ (9) (A(J),J=1,NWING)
DU 200 J=1,NWING
DNW(I)=DNW(I)+A(J)*GW(J)
RNW(I)=NW(I)-DNW(I)
210      CONTINUE
220      REWIND 9
IF (IT.LT.IMAX) GO TO 40
230      RETURN
C
C      FORMAT (1H0,6HTIME =F10.5)
240      FORMAT (1H0,3I3)
250      FORMAT (1H ,10F10.5)
260      END
AE1120-

```

```

SUBROUTINE PRESS (NP,XMACH,ARA,U,V,W,CPP,CPSTAG,CPCRIT,CPVAC)
C
C COMPUTE THE PRESSURE COEFFICIENT USING THE EXACT ISENTROPIC
C FORMULA. ALSO COMPUTE THE STAGNATION PRESSURE COEFFICIENT,
C CRITICAL PRESSURE COEFFICIENT, AND VACUUM PRESSURE COEFFICIENT.
C
C
DIMENSION U(1), V(1), W(1), CPP(1)
XM2=XMACH*XMACH
BT2=XM2-1.
CPCRIT=0.
CPSTAG=1.
CPVAC=0.
COSARA=COS(ARA)
SINARA=SIN(ARA)
IF (XM2.EQ.0.) GO TO 10
CON=1.42857/XM2
CON1=.2*XM2
10 DO 30 J=1,NP
UWPM=U(J)*COSARA+W(J)*SINARA
UWIND=1.+UWPM
VWIND=V(J)
WWIND=W(J)*COSARA-U(J)*SINARA
VW2=VWIND*VWIND+WWIND*WWIND
Q2=UWIND*UWIND+VW2
IF (XMACH.EQ.0.) GO TO 20
ARG=1.+CON1*(1.-Q2)
IF (ARG.LT.0.) ARG=0.
CPP(J)=CON*(ARG**3.5-1.)
GO TO 30
CPP(J)=1.-Q2
CONTINUE
IF (XMACH.EQ.0.) GO TO 40
CPSTAG=CON*((1.+CON1)**3.5-1.)
CPCRIT=CON*((5./6.+XM2/6.)*3.5-1.)
CPVAC=CON
CONTINUE
RETURN
END
40

```

```

SUBROUTINE FORMCP (NPAN, NPASS, ALFA, COMPT)
C   C CALCULATE THE FORCE AND MOMENT COEFFICIENTS ON THE BODY, WING,
C   C FIN (VERTICAL TAIL) AND CANARD (HORIZONTAL TAIL)
C
COMMON /PARAM/ NBODY,NWING,NTAIL,LBC,THK,MACH,ALPHA,REFA,REFB,REFC AG 10
1,REFU,REFV,REFZ AG 20
COMMON /HEAD/ TITLE1(8),TITLE2(8) AG 30
COMMON /SEG/ NSEG,NROW(20),NCOL(20),COSS(20),SINS(20),BTE(20),NWT( AG 40
120),SPNW(20),XLEW(20),BLE(20),ZLEW(20) AG 50
COMMON /PCINT/ ARRAY(6000) AG 60
COMMON /SCRAT/ DCN(600),DCM(600),DCT(600),II(600),SIND(600),COSD(6 AG 70
100),GP(600),DUD(300),SINT(600),COST(600),Gw(600),GB(600),GZTDX(600 AG 80
2) AG 90
COMMON /NEWCOM/ KDUM(41),LUCPT(20),XCPT(20) AG 100
COMMON /VELCCM/ NPOINT,NDUM(5),PRINT,NDUN(22) AG 110
COMMON /FORM/ CNW,CTW,CNW,CNB,CTB,CMB,CNS(20),CTS(20),CMS(20) AG 120
DIMENSION XPT(600), YPT(600), THET(600), DELTA(600), SGN AG 130
1(600), AREA(600), CHORD(600), CHO(20), XLE(600), ZLE(600), XC(30,2 AG 140
20) AG 150
C
EQUIVALENCE (ARRAY,XPT), (ARRAY(601),YPT), (ARRAY(1201),ZPT), (ARR AG 160
IAY(1801),THET), (ARRAY(2401),DELTA), (ARRAY(3001),XC,SGN), (ARRAG 170
24801),AREA), (ARRAY(3601),CHORD), (ARRAY(5401),XLE), (CHD,EUD) AG 180
INTEGER COMPT,TEST,PRINT AG 190
REAL MACH AG 200
LOGICAL LBC AG 210
AG 220
C
C NOTE THAT THE WING, CANARD, AND TAIL ARE ALL SEGMENTS OF THE WING AG 230
C IN THIS SUBROUTINE AG 310
C
C EPS=1.0E-6 AG 320
NP=NPNPAG 330
AG 340
C
C COMPT=1 INDICATES BODY FORCE AND MOMENT CALCULATION AG 350
C COMPT=2 INDICATES WING FORCE AND MOMENT CALCULATION AG 360
C
C NPASS=1 FOR THE BODY AG 370
C NPASS=1 FOR THE WING UPPER AND LOWER SURFACES IF THE NON-PLANAR AG 380
C BOUNDARY CONDITION OPTION IS SELECTED AG 390
C
C

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```

C NPASS=1 FOR THE WING UPPER SURFACE IF THE PLANAR BOUNDARY
C CONDITION OPTION IS SELECTED AG 430
C NPASS=2 FOR THE WING LOWER SURFACE IF THE PLANAR BOUNDARY AG 440
C CONDITION OPTION IS SELECTED AG 450
C
C IF (COMPT.EQ.1) XGN=XC(1,1) AG 460
C IF (COMPT.EQ.2.AND.NBODY.GT.0) GO TO 10 AG 470
C
C CNB=0. AG 480
C CTB=0. AG 490
C CMB=0. AG 500
C
10 CONTINUE AG 510
C IF (NBODY.EQ.0.OR.NWING.EQ.0.OR.NPASS.EQ.2) GO TO 20 AG 520
C
REWIND 7 AG 530
C IF (COMPT.EQ.2) READ (7) ARRAY,CHORD,DZUX AG 540
C
20 CONTINUE AG 550
C SIAL=SIN(ALFA) AG 560
C COAL=COS(ALFA) AG 570
C WRITE (6,300) AG 580
C WRITE (6,320) TITLE1,TITLE2 AG 590
C WRITE (6,310) AG 600
C IF (COMPT.EQ.1) WRITE (6,440) AG 610
C IF (.NOT.LBC) GO TO 30 AG 620
C IF (COMPT.EQ.2.AND.NPASS.EQ.1) WRITE (6,470) AG 630
C IF (COMPT.EQ.2.AND.NPASS.EQ.2) WRITE (6,480) AG 640
C
GO TO 40 AG 650
C IF (COMPT.EQ.2) WRITE (6,450) AG 660
C
CONTINUE AG 670
C WRITE (6,330) MACH,ALPHA AG 680
C WRITE (6,340) AG 690
C IF (LBC.AND.COMPT.GT.1) GO TO 60 AG 700
C DO 50 I=1,NPAN AG 710
C SGN(I)=1.0 AG 720
C
50 SIND(I)=SIN(DELTA(I)) AG 730
C COSD(I)=COS(DELTA(I)) AG 740
C SINT(I)=SIN(THET(I)) AG 750
C COST(I)=COS(THET(I)) AG 760
C
60 GO TU 80 AG 770
C
CONTINUE AG 780
C AG 790
C
AG 800
C AG 810
C FOR THE PLANAR BOUNDARY CONDITION OPTION CALCULATE THE WING CAMBER AG 820
C AND THICKNESS SLOPES AT CENTER OF PANELS, AND (X,Y,Z) COORDINATES AG 830
C OF CENTRAL POINT AG 840
C AG 850

```

```

I=0          AG 860
J=0          AG 870
DU 70 N=1,NSEG AG 880
NC=NCOL(N)    AG 890
NR=NROW(N)    AG 900
NR1=NR+1      AG 910
DU 70 M=1,NC   AG 920
DO 70 L=1,NR1  AG 930
J=J+1        AG 940
IF (L.EQ.NR1) GO TO 70
I=I+1        AG 950
SGN(I)=1.0
IF (INPASS.EQ.2) SGN(I)=-1.0
DELC=(DELTA(J)*DELTA(J+1))*0.5
DELZ=(DZDX(J)+DZDX(J+1))*0.5
IF (INPASS.EQ.1) TAND=DELC+DELZ
IF (INPASS.EQ.2) TAND=DELC-DELZ
SIND(I)=TAND/SQRT(1.+TAND*TANU)
COSD(I)=SQRT(1.-SIND(I)*SIND(I))
SINT(I)=SIN(S(N))
COST(I)=COS(S(N))
XS=XOPT(N)
PT=XS
IF ((LOCPT(N).NE.0) PT=XS*FLOAT(NR-L)/FLOAT(NR-1)
RL=.5+PT
RT=.5-PT
IF (LUCPT(N).NE.0) CP(I)=CP(J)*RL+CP(J+1)*RT
IF (INPASS.EQ.2) GO TO 70
XPT(I)=(XLE(J)+XLE(J+1))*0.5
YPT(I)=YPT(J)
ZPT(I)=ZPT(J)
CONTINUE
IF (COMPT.EQ.2) NP=I
CONTINUE
IF (INPASS.EQ.2.CR.COMPT.EQ.1) GO TO 110
C
C CALCULATE CHORD LENGTH OF EACH COLUMN OF PANELS ON WING
C
I=0          AG1170
J=0          AG1180
DO 90 N=1,NSEG AG1190
NC=NCOL(N)    AG1200
NR=NROW(N)    AG1210
AG1220        AG1230
AG1240        AG1250
AG1260        AG1270
AG1280        AG1290

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```

DO 90 M=1,NC
J=J+1
CHD(J)=0.
KS=2
IF (LBC) KS=1
DO 90 K=1,KS
DO 90 L=1,NR
I=I+1
IF (K.EQ.1) CHD(J)=CHD(J)+CHORD(I)
IF (K.EQ.2) SGN(I)= -1.0
CONTINUE
I=0
J=0
C
C ASSOCIATE THE LEADING EDGE COORDINATES AND CHORD LENGTHS OF EACH
C COLUMN OF PANELS WITH THE INDIVIDUAL PANELS IN THE COLUMN
C
DO 100 N=1,NSEG
NC=NCOL(N)
NR=NROW(N)
DO 100 M=1,NC
J=J+1
KS=2
IF (LBC) KS=1
DO 100 K=1,KS
DO 100 L=1,NR
I=I+1
ZLE(I)=ZLEM(I)
XLE(I)=XLEM(I)
CHORD(I)=CHD(J)
CONTINUE
100 CONTINUE
IF (NPASS.EQ.2) GO TO 120
CN=0.
CT=0.
CM=0.
GO TU 130
120 CN=CNk
CT=CTk
CM=CMM
IP=0
C
C CALCULATE THE FORCES AND MOMENT ACTING ON EACH PANEL AND SUM OVER

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C THE ENTIRE COMPONENT
C
DU 160 I=1,NP
IP=IP+1
XP=XPT(I)
YP=YPT(I)
ZP=ZPT(I)
F1=CUSD(I)*COST(I)
F2=SIND(I)
FAK=AREA(I)*SIGN(I)
IF (LBC.AND.CCMPI.GT.1.AND.COSD(I).NE.0.) FAK=FAK/COSD(I)
IF (ABS(YP).LT.EPS) FAK=0.5*FAK
DCN(I)=CP(I)*F1*FAK
DCT(I)=CP(I)*F2*FAK
DCM(I)=DCN(I)*(REFX-XP)-DCT(I)*(REFZ-ZP)
XQ=XP
YQ=YP
ZQ=ZP
IF (COMPT.EQ.2) GO TO 140
C
C NONDIMENSIONALIZE BODY PANEL CONTROL POINT COORDINATES
C X COORDINATES ARE DIVIDED BY THE BODY REFERENCE LENGTH
C Y AND Z COORDINATES ARE DIVIDED BY THE BODY REFERENCE DIAMETER
C
XQ=(XP-XCN)/REFL
YQ=YP/REFD
ZQ=ZP/REFD
GO TU 150
C
C NUNDIMENSIONALIZE WING PANEL CONTROL POINT COORDINATES
C X AND Z COORDINATES ARE DIVIDED BY THE REFERENCE CHJKD
C Y COORDINATES ARE DIVIDED BY THE REFERENCE SEMISPA
C
140 IF (CHURC(I).NE.0.) XQ=(XP-XLE(I))/CHORD(I)
IF (REFB.NE.0.) YQ=YP/REFB
IF (CHURC(I).NE.0.) ZQ=(ZP-ZLE(I))/CHORD(I)
CONTINUE
WRITE (6,350) IP,XP,YP,ZP,XQ,YQ,ZQ,CP(I),DCN(I),DCT(I),DCM(I),IP
CN=CN+DCN(I)
CT=CT+DCT(I)
CM=CM+DCM(I)
CONTINUE
IF (COMPT.GT.1) GO TO 170

```

```

C      STORE BODY FORCES AND MOMENT          AG2150
C
C      CNB=CN                                AG2160
C      CTB=CT                                AG2170
C      CMB=CM                                AG2180
C      GO TO 180                             AG2190
C      CONTINUE                               AG2200
C
C      STORE WING FORCES AND MOMENT          AG2210
C
C      CNW=CN                                AG2220
C      CTW=CT                                AG2230
C      CMW=CM                                AG2240
C
C      CNW=CN                                AG2250
C      CTW=CT                                AG2260
C      CMW=CM                                AG2270
C
C      IF (LBC.AND.NPASS.EQ.1) GO TO 200    AG2280
C      CONTINUE                               AG2290
C
C      WRITE (6,300)                           AG2300
C      WRITE (6,360)                           AG2310
C      IF (COMPT.EC.1) WRITE (6,440)           AG2320
C      IF (COMPT.EC.2) WRITE (6,450)           AG2330
C
C      COMPUTE NORMAL AND TANGENTIAL (AXIAL)   AG2340
C      FORCE COEFFICIENTS, PITCHING          AG2350
C      MOMENT COEFFICIENT, LIFT AND DRAG        AG2360
C      COEFFICIENT, AND CENTER OF              AG2370
C      PRESSURE OF COMPONENT                  AG2380
C
C      IT=0                                    AG2390
C      CN=2.*CN/REFA                          AG2400
C      CT=2.*CT/REFA                          AG2410
C      CM=2.*CM/REFA                          AG2420
C
C      CL=CN*CCAL-CT*SIAL                   AG2430
C      CD=CN*SIAL+CT*COAL                   AG2440
C
C      DXN=0.                                 AG2450
C
C      IF (CL.NE.0.) DXN=CM/CL               AG2460
C      IF (COMPT.EC.1) WRITE (6,380) REFa,REFb,REFl
C      IF (COMPT.EC.2) WRITE (6,370) REFa,REFb,REFc
C      WRITE (6,390) REFx,REFz
C      WRITE (6,400) CN,CT,CM,CL,CD,DXN
C
C      CONTINUE                               AG2510
C
C      IF (COMPT.EC.1) GO TO 290             AG2520
C      IF (LBC.AND.NPASS.EQ.1) GO TO 210
C      IF (NBODY.EQ.0.OR.IT.GT.0) GO TO 210
C      IT=IT+1
C      CN=CNB+CNW

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```

CT=CTB+CTh
CN=CMB+CWN
WRITE (0,3C0)
WRITE (6,360)
WRITE (6,460)
GO TO 190
IF (PRINT.EQ.0) GO TO 290
IF (LBC.AND.NPASS.EQ.1) GO TO 220
WRITE (0,300)
WRITE (6,420)
WRITE (6,450)
CONTINUE
J=0
K=0
I2=0
I2=0
210
C COMPUTE SECTION FORCES AND MOMENT FOR WING IF THE PRINT OPTION IS
C NCZERO
C
DU 280 N=1,NSEG
NR=NROW(N)
NR2=NR*2
NC=NCOL(N)
DU 280 M=1,NC
J=J+1
K=K+1
I1=I2+1
IF (LBC) I2=I2+NR
IF (*.NUT.LBC) I2=I2+NR2
I2=I2+1
IF (I2.LT.4) GO TO 230
IF (LBC.AND.NPASS.EQ.1) GO TO 230
I2=1
CONTINUE
WRITE (6,3C0)
WRITE (6,420)
WRITE (6,450)
220
C
DEL=Y=SPN(J)
XL=XLEW(J)
IF (LBC.AND.NPASS.EQ.1) GO TO 240
WRITE (0,410)
WRITE (6,430) DEL,Y,REFC,XL
230
AG2580
AG2590
AG2600
AG2610
AG2620
AG2630
AG2640
AG2650
AG2660
AG2670
AG2680
AG2690
AG2700
AG2710
AG2720
AG2730
AG2740
AG2750
AG2760
AG2770
AG2780
AG2790
AG2800
AG2810
AG2820
AG2830
AG2840
AG2850
AG2860
AG2870
AG2880
AG2890
AG2900
AG2910
AG2920
AG2930
AG2940
AG2950
AG2960
AG2970
AG2980
AG2990
AG3000

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```

240    CONTINUE
      IF (LBC.AND.NPASS.EQ.2) GO TO 250
      CN=0.
      CT=0.
      CM=0.
      GU TU 260
      CN=CNS(K)
      CT=CTSI(K)
      CM=CMSS(K)
      CONTINUE
      AG3010
      AG3020
      AG3030
      AG3040
      AG3050
      AG3060
      AG3070
      AG3080
      AG3090
      AG3100
      AG3110
      AG3120
      AG3130
      AG3140
      AG3150
      AG3160
      AG3170
      AG3180
      AG3190
      AG3200
      AG3210
      AG3220
      AG3230
      AG3240
      AG3250
      AG3260
      AG3270
      AG3280
      AG3290
      AG3300
      AG3310
      AG3320
      AG3330
      AG3340
      AG3350
      AG3360
      AG3370
      AG3380
      AG3390
      AG3400
      AG3410
      AG3420
      AG3430

C     SUM THE FORCES AND MOMENT ACTING ON EACH PANEL AND SECTION, AND
C     STORE RESULTS
C
C     00 270 I=11,12
C     CN=CN+DCN(I)
C     CT=CT+DCT(I)
C     CM=CM+DCM(I)
C
C     CONTINUE
C     CNS(K)=CN
C     CTS(K)=CT
C     CMS(K)=CM
      IF (LBC.AND.NPASS.EQ.1) GO TO 280
C
C     COMPUTE NORMAL AND TANGENTIAL (AXIAL) FORCE COEFFICIENTS, PITCHING
C     MOMENT COEFFICIENT, LIFT AND DRAG COEFFICIENT, AND CENTER OF
C     PRESSURE OF SECTION
C
C     H1=1./ (DELY*CHD(J))
C     H2=H1/REF C
C     CN=CN*H1
C     CT=CT*H1
C     CM=CM*H2
C     CL=CN*CDAL-CT*SIAL
C     CD=CN*SIAL+CT*COAL
      DXN=0.
      IF (CL.NE.0.) DXN=CM/CL
      WRITE (6,400) CN,CT,CM,CL,CD,DXN
      CONTINUE
      CONTINUE
      RETURN
      280
      290
      C
      C

```

```

300 FORMAT (1H1)
310 FORMAT (/,10X,40HINTEGRATION OF THE PRESSURE DISTRIBUTION,/)
320 FORMAT (10X,8A10/10X,8A10)
330 FORMAT (/,10X,6H MACH= ,F8.4,/ ,10X,6H ALPHA= ,F8.4)
340 FORMAT (1X,5H PCINT,9X,1HX,9X,1HY,9X,1HZ,9X,3HX/C,9X,4H2Y/B,9X,3HZ/
1C,9X,2HCP,9X,2HGN,9X,2HCT,9X,2HCM,5X,5HPOINT /)
350 FORMAT (1X,16.10F11.5,16)
360 FORMAT (///,10X,18HTOTAL COEFFICIENTS,/,10X,18(1H-))
370 FORMAT (10X,5HREFA=,F14.4,3X,5HREFB=,F14.4,3X,5HREFC=,F14.4)
380 FORMAT (10X,5HREFA=,F14.4,3X,5HREFD=,F14.4,3X,5HREFL=,F14.4)
390 FORMAT (/,10X,5HREFX=,F14.4,3X,5HREFZ=,F14.4)
400 FORMAT (/,10X,3HCL=,F14.4,/,10X,3HCT=,F14.4,/,10X,3HCM=,F14.4,/,10
1X,3HCL=,F14.4,/,10X,3HCD=,F14.4,/,5X,4H XCP=,F14.4)
410 FORMAT (//)
420 FORMAT (10X,20H SECTION COEFFICIENTS,/,10X,20(1H-))
430 FORMAT (10X,5HDELY=,F14.4,3X,5HREFL=,F14.4,3X,4HXL E=,F14.4)
440 FORMAT (10X,11HCN THE BODY,/)
450 FORMAT (10X,11HCN THE WING,/)
460 FORMAT (10X,29HCN THE COMPLETE CONFIGURATION,/)
470 FORMAT (10X,25HCN THE WING UPPER SURFACE,/)
480 FORMAT (10X,25HCN THE WING LOWER SURFACE,/)
END

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AG3440
AG3450
AG3460
AG3470
AG3480
AG3490
AG3500
AG3510
AG3520
AG3530
AG3540
AG3550
AG3560
AG3570
AG3580
AG3590
AG3600
AG3610
AG3620
AG3630
AG3640
AG3650-

APPENDIX III

SAMPLE CASE

UNIFIED SUBSONIC-SUPERSONIC AERODYNAMICS PROGRAM

VERSION A00

LIST OF INPUT CARDS

00000000011111111122222222333333334444444445555555556666666677777777778
1234567890123456789012345678901234567890123456789012345678901234567890

000000000111111112222222333333333444444445555555556666666677777777778
1234567890123456789012345678901234567890123456789012345678901234567890

UGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING

WING PANEL CORNER POINT COORDINATES
1 AND 3 INDICATE WING PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAILING-EDGE POINTS

PANEL	X ₁	Y ₁	Z ₁	X ₂	Y ₂	Z ₂	X ₃	Y ₃	Z ₃	X ₄	Y ₄	Z ₄
1	15.59483	1.66700	0.00000	16.48370	1.66700	0.00000	17.11500	2.97000	0.00000	17.91700	2.97000	0.00000
2	16.48370	1.66700	0.00000	17.37257	1.66700	0.00000	17.91700	2.97000	0.00000	18.71900	2.97000	0.00000
3	17.37257	1.66700	0.00000	18.26143	1.66700	0.00000	18.71900	2.97000	0.00000	19.52100	2.97000	0.00000
4	18.26143	1.66700	0.00000	19.15030	1.66700	0.00000	19.52100	2.97000	0.00000	20.32300	2.97000	0.00000
5	19.15030	1.66700	0.00000	20.03917	1.66700	0.00000	20.32300	2.97000	0.00000	21.12500	2.97000	0.00000
6	20.03917	1.66700	0.00000	20.92803	1.66700	0.00000	21.12500	2.97000	0.00000	21.92700	2.97000	0.00000
7	20.92803	1.66700	0.00000	21.81690	1.66700	0.00000	21.92700	2.97000	0.00000	22.72900	2.97000	0.00000
8	21.81690	1.66700	0.00000	22.70577	1.66700	0.00000	22.72900	2.97000	0.00000	23.53100	2.97000	0.00000
9	22.70577	1.66700	0.00000	23.59463	1.66700	0.00000	23.53100	2.97000	0.00000	24.33300	2.97000	0.00000
10	23.59463	1.66700	0.00000	24.48350	1.66700	0.00000	24.33300	2.97000	0.00000	25.13500	2.97000	0.00000
11	17.11500	2.97000	0.00000	17.91700	2.97000	0.00000	19.91500	5.37000	0.00000	20.55700	5.37000	0.00000
12	17.91700	2.97000	0.00000	18.71900	2.97000	0.00000	20.55700	5.37000	0.00000	21.19900	5.37000	0.00000
13	18.71900	2.97000	0.00000	19.52100	2.97000	0.00000	21.19900	5.37000	0.00000	21.84100	5.37000	0.00000
14	19.52100	2.97000	0.00000	20.32300	2.97000	0.00000	21.84100	5.37000	0.00000	22.48300	5.37000	0.00000
15	20.32300	2.97000	0.00000	21.12500	2.97000	0.00000	22.48300	5.37000	0.00000	23.12500	5.37000	0.00000
16	21.12500	2.97000	0.00000	21.92700	2.97000	0.00000	23.12500	5.37000	0.00000	23.76700	5.37000	0.00000
17	21.92700	2.97000	0.00000	22.72900	2.97000	0.00000	23.76700	5.37000	0.00000	24.40900	5.37000	0.00000
18	22.72900	2.97000	0.00000	23.53100	2.97000	0.00000	24.40900	5.37000	0.00000	25.05100	5.37000	0.00000
19	23.53100	2.97000	0.00000	24.33300	2.97000	0.00000	25.05100	5.37000	0.00000	25.69300	5.37000	0.00000
20	24.33300	2.97000	0.00000	25.13500	2.97000	0.00000	25.69300	5.37000	0.00000	26.33500	5.37000	0.00000
21	19.91500	5.37000	0.00000	20.55700	5.37000	0.00000	22.66833	7.73000	0.00000	23.15300	7.73000	0.00000
22	20.55700	5.37000	0.00000	21.19900	5.37000	0.00000	23.15300	7.73000	0.00000	23.63767	7.73000	0.00000
23	21.19900	5.37000	0.00000	21.84100	5.37000	0.00000	23.63767	7.73000	0.00000	24.12233	7.73000	0.00000
24	21.84100	5.37000	0.00000	22.48300	5.37000	0.00000	24.12233	7.73000	0.00000	24.60700	7.73000	0.00000
25	22.48300	5.37000	0.00000	23.12500	5.37000	0.00000	24.60700	7.73000	0.00000	25.09167	7.73000	0.00000
26	23.12500	5.37000	0.00000	23.76700	5.37000	0.00000	25.09167	7.73000	0.00000	25.57633	7.73000	0.00000
27	23.76700	5.37000	0.00000	24.40900	5.37000	0.00000	25.57633	7.73000	0.00000	26.06100	7.73000	0.00000
28	24.40900	5.37000	0.00000	25.05100	5.37000	0.00000	26.06100	7.73000	0.00000	26.54567	7.73000	0.00000
29	25.05100	5.37000	0.00000	25.69300	5.37000	0.00000	26.54567	7.73000	0.00000	27.03033	7.73000	0.00000
30	25.69300	5.37000	0.00000	26.33500	5.37000	0.00000	27.03033	7.73000	0.00000	27.51500	7.73000	0.00000
31	22.66833	7.73000	0.00000	23.15300	7.73000	0.00000	25.43333	10.10000	0.00000	25.76000	10.10000	0.00000
32	23.15300	7.73000	0.00000	23.63767	7.73000	0.00000	25.76000	10.10000	0.00000	26.08667	10.10000	0.00000
33	23.63767	7.73000	0.00000	24.12233	7.73000	0.00000	26.08667	10.10000	0.00000	26.41333	10.10000	0.00000
34	24.12233	7.73000	0.00000	24.60700	7.73000	0.00000	26.41333	10.10000	0.00000	26.74000	10.10000	0.00000
35	24.60700	7.73000	0.00000	25.09167	7.73000	0.00000	26.74000	10.10000	0.00000	27.06667	10.10000	0.00000
36	25.09167	7.73000	0.00000	25.57633	7.73000	0.00000	27.06667	10.10000	0.00000	27.39333	10.10000	0.00000
37	25.57633	7.73000	0.00000	26.06100	7.73000	0.00000	27.39333	10.10000	0.00000	27.72000	10.10000	0.00000
38	26.06100	7.73000	0.00000	26.54567	7.73000	0.00000	27.72000	10.10000	0.00000	28.04667	10.10000	0.00000
39	26.54567	7.73000	0.00000	27.03033	7.73000	0.00000	28.04667	10.10000	0.00000	28.37333	10.10000	0.00000
40	27.03033	7.73000	0.00000	27.51500	7.73000	0.00000	28.37333	10.10000	0.00000	28.70000	10.10000	0.00000
41	25.43333	10.10000	0.00000	25.76000	10.10000	0.00000	27.65000	12.00000	0.00000	27.85000	12.00000	0.00000
42	25.76000	10.10000	0.00000	26.08667	10.10000	0.00000	27.85000	12.00000	0.00000	28.05000	12.00000	0.00000
43	26.08667	10.10000	0.00000	26.41333	10.10000	0.00000	28.05000	12.00000	0.00000	28.25000	12.00000	0.00000
44	26.41333	10.10000	0.00000	26.74000	10.10000	0.00000	28.25000	12.00000	0.00000	28.45000	12.00000	0.00000
45	26.74000	10.10000	0.00000	27.06667	10.10000	0.00000	28.45000	12.00000	0.00000	28.65000	12.00000	0.00000
46	27.06667	10.10000	0.00000	27.39333	10.10000	0.00000	28.65000	12.00000	0.00000	28.85000	12.00000	0.00000
47	27.39333	10.10000	0.00000	27.72000	10.10000	0.00000	28.85000	12.00000	0.00000	29.05000	12.00000	0.00000
48	27.72000	10.10000	0.00000	28.04667	10.10000	0.00000	29.05000	12.00000	0.00000	29.25000	12.00000	0.00000
49	28.04667	10.10000	0.00000	28.37333	10.10000	0.00000	29.25000	12.00000	0.00000	29.45000	12.00000	0.00000
50	28.37333	10.10000	0.00000	28.70000	10.10000	0.00000	29.45000	12.00000	0.00000	29.65000	12.00000	0.00000

WING PANEL CONTROL POINTS AND INCLINATION ANGLES

POINT	X CP	Y CP	Z CP	THETA	CAMBER SLOPE	THICKNESS SLOPE
1	16.34190	2.30734	0.00000	0.00000	0.00000	.17879
2	17.18808	2.30734	0.00000	0.00000	0.00000	.05696
3	18.03425	2.30734	0.00000	0.00000	0.00000	.03265
4	18.88043	2.30734	0.00000	0.00000	0.00000	.01709
5	19.72661	2.30734	0.00000	0.00000	0.00000	.00315
6	20.57279	2.30734	0.00000	0.00000	0.00000	-.01379
7	21.41896	2.30734	0.00000	0.00000	0.00000	-.02918
8	22.26514	2.30734	0.00000	0.00000	0.00000	-.03946
9	23.11132	2.30734	0.00000	0.00000	0.00000	-.04623
10	23.95749	2.30734	0.00000	0.00000	0.00000	-.04704
11	24.80367	2.30734	0.00000	0.00000	0.00000	-.04710
12	18.46329	4.12568	0.00000	0.00000	0.00000	.17879
13	19.18825	4.12568	0.00000	0.00000	0.00000	.05696
14	19.91320	4.12568	0.00000	0.00000	0.00000	.03265
15	20.63816	4.12568	0.00000	0.00000	0.00000	.01709
16	21.36311	4.12568	0.00000	0.00000	0.00000	.00315
17	22.08607	4.12568	0.00000	0.00000	0.00000	-.01379
18	22.81302	4.12568	0.00000	0.00000	0.00000	-.02918
19	23.53798	4.12568	0.00000	0.00000	0.00000	-.03946
20	24.26293	4.12568	0.00000	0.00000	0.00000	-.04623
21	24.98788	4.12568	0.00000	0.00000	0.00000	-.04704
22	25.71284	4.12568	0.00000	0.00000	0.00000	-.04710
23	21.22759	6.49507	0.00000	0.00000	0.00000	.17879
24	21.79458	6.49507	0.00000	0.00000	0.00000	.05696
25	22.36158	6.49507	0.00000	0.00000	0.00000	.03265
26	22.92857	6.49507	0.00000	0.00000	0.00000	.01709
27	23.49557	6.49507	0.00000	0.00000	0.00000	.00315
28	24.06256	6.49507	0.00000	0.00000	0.00000	-.01379
29	24.62956	6.49507	0.00000	0.00000	0.00000	-.02918
30	25.19655	6.49507	0.00000	0.00000	0.00000	-.03946
31	25.76355	6.49507	0.00000	0.00000	0.00000	-.04623
32	26.33054	6.49507	0.00000	0.00000	0.00000	-.04704
33	26.89756	6.49507	0.00000	0.00000	0.00000	-.04710
34	23.96109	8.83808	0.00000	0.00000	0.00000	.17879
35	24.37188	8.83808	0.00000	0.00000	0.00000	.05696
36	24.78268	8.83808	0.00000	0.00000	0.00000	.03265
37	25.19347	8.83808	0.00000	0.00000	0.00000	.01709
38	25.60427	8.83808	0.00000	0.00000	0.00000	.00315
39	26.01506	8.83808	0.00000	0.00000	0.00000	-.01379
40	26.42586	8.83808	0.00000	0.00000	0.00000	-.02918
41	26.83665	8.83808	0.00000	0.00000	0.00000	-.03946
42	27.24745	8.83808	0.00000	0.00000	0.00000	-.04623
43	27.65824	8.83808	0.00000	0.00000	0.00000	-.04704
44	28.06904	8.83808	0.00000	0.00000	0.00000	-.04710
45	26.45281	10.97384	0.00000	0.00000	0.00000	.17879
46	26.72122	10.97384	0.00000	0.00000	0.00000	.05696
47	26.98963	10.97384	0.00000	0.00000	0.00000	.03265
48	27.25805	10.97384	0.00000	0.00000	0.00000	.01709
49	27.52646	10.97384	0.00000	0.00000	0.00000	.00315
50	27.79487	10.97384	0.00000	0.00000	0.00000	-.01379
51	28.06328	10.97384	0.00000	0.00000	0.00000	-.02918
52	28.33169	10.97384	0.00000	0.00000	0.00000	-.03946
53	28.60010	10.97384	0.00000	0.00000	0.00000	-.04623
54	28.86851	10.97384	0.00000	0.00000	0.00000	-.04704
55	29.13692	10.97384	0.00000	0.00000	0.00000	-.04710

WING PANEL AREAS AND CHORDS

PANEL	AREA	CHORD
1	1.10160	.84618
2	1.10160	.84618
3	1.10160	.84618
4	1.10160	.84618
5	1.10160	.84618
6	1.10160	.84618
7	1.10160	.84618
8	1.10160	.84618
9	1.10160	.84618
10	1.10160	.84618
11	1.73280	.72495
12	1.73280	.72495
13	1.73280	.72495
14	1.73280	.72495
15	1.73280	.72495
16	1.73280	.72495
17	1.73280	.72495
18	1.73280	.72495
19	1.73280	.72495
20	1.73280	.72495
21	1.32947	.56700
22	1.32947	.56700
23	1.32947	.56700
24	1.32947	.56700
25	1.32947	.56700
26	1.32947	.56700
27	1.32947	.56700
28	1.32947	.56700
29	1.32947	.56700
30	1.32947	.56700
31	.96143	.41079
32	.96143	.41079
33	.96143	.41079
34	.96143	.41079
35	.96143	.41079
36	.96143	.41079
37	.96143	.41079
38	.96143	.41079
39	.96143	.41079
40	.96143	.41079
41	.50033	.26841
42	.50033	.26841
43	.50033	.26841
44	.50033	.26841
45	.50033	.26841
46	.50033	.26841
47	.50033	.26841
48	.50033	.26841
49	.50033	.26841
50	.50033	.26841

BODY PANEL CORNER POINT COORDINATES
 1 AND 3 INDICATE BODY PANEL LEADING-EDGE POINTS, 2 AND 4 INDICATE TRAILING-EDGE POINTS

PANEL	X ₁	Y ₁	Z ₁	X ₂	Y ₂	Z ₂	X ₃	Y ₃	Z ₃	X ₄	Y ₄	Z ₄
1	0.00000	0.00000	0.00000	1.50000	.00000	-40622	0.00000	0.00000	0.00000	1.50000	.28724	-.28724
2	0.00000	0.00000	0.00000	1.50000	.28724	-.28724	0.00000	0.00000	0.00000	1.50000	.40622	.00000
3	0.00000	0.00000	0.00000	1.50000	.40622	.00000	0.00000	0.00000	0.00000	1.50000	.28724	.28724
4	0.00000	0.00000	0.00000	1.50000	.28724	.28724	0.00000	0.00000	0.00000	1.50000	-.00000	.00000
5	1.50000	.00000	-.40622	4.50000	.00000	-1.04487	1.50000	.28724	-.28724	4.50000	-.73883	-.73883
6	1.50000	.28724	-.28724	4.50000	.73883	-.73883	1.50000	.40622	.00000	4.50000	1.04487	.00000
7	1.50000	.40622	.00000	4.50000	1.04487	.00000	1.50000	.28724	-.28724	4.50000	.73883	.73883
8	1.50000	.28724	.28724	4.50000	.73883	.73883	1.50000	-.00000	.40622	4.50000	.73883	.73883
9	4.50000	.00000	-1.04487	7.50000	.00000	-1.45730	4.50000	.73883	-.73883	7.50000	-.00000	1.04487
10	4.50000	.73883	-.73883	7.50000	1.03047	-1.03047	4.50000	1.04487	.00000	7.50000	1.03047	-1.03047
11	4.50000	1.04487	.00000	7.50000	1.45730	.00000	4.50000	.73883	-.73883	7.50000	1.03047	.00000
12	4.50000	.73883	.73883	7.50000	1.03047	1.03047	4.50000	-.00000	1.04487	7.50000	-.00000	1.45730
13	7.50000	.00000	-1.45730	10.50000	.00000	-1.65030	7.50000	1.03047	-1.03047	10.50000	1.16694	-1.16694
14	7.50000	1.03047	-1.03047	10.50000	1.16694	-1.16694	7.50000	1.45730	.00000	10.50000	1.65030	.00000
15	7.50000	1.45730	.00000	10.50000	1.65030	.00000	7.50000	1.03047	1.03047	10.50000	1.16694	1.16694
16	7.50000	1.03047	1.03047	10.50000	1.16694	1.16694	7.50000	-.00000	1.45730	10.50000	1.16694	1.16694
17	10.50000	.00000	-1.65030	11.66700	.00000	-1.66670	10.50000	1.16694	1.16694	10.50000	-.00000	1.65030
18	10.50000	1.16694	-1.16694	11.66700	1.17854	1.17854	10.50000	1.65030	.00000	11.66700	1.17854	-1.17854
19	10.50000	1.65030	.00000	11.66700	1.66670	.00000	10.50000	1.16694	1.16694	11.66700	1.17854	.00000
20	10.50000	1.16694	1.16694	11.66700	1.17854	1.17854	10.50000	-.00000	1.65030	11.66700	1.17854	1.17854
21	11.66700	.00000	-1.66670	15.59480	.00000	-1.66670	11.66700	1.17854	1.17854	15.59480	1.17854	-1.17854
22	11.66700	1.17854	-1.17854	15.59480	1.17854	-1.17854	11.66700	1.66670	.00000	15.59480	1.66670	.00000
23	11.66700	1.66670	.00000	15.59480	1.66670	.00000	11.66700	1.17854	1.17854	15.59480	1.17854	1.17854
24	11.66700	1.17854	1.17854	15.59480	1.17854	1.17854	11.66700	1.17854	1.17854	15.59480	1.17854	1.17854
25	15.59480	.00000	-1.66670	17.37260	.00000	-1.66670	15.59480	1.17854	-1.17854	17.37260	1.66670	.00000
26	15.59480	1.17854	-1.17854	17.37260	1.17854	-1.17854	15.59480	1.66670	.00000	17.37260	1.17854	-1.17854
27	15.59480	1.66670	.00000	17.37260	1.66670	.00000	15.59480	1.17854	1.17854	17.37260	1.66670	.00000
28	15.59480	1.17854	1.17854	17.37260	1.17854	1.17854	15.59480	1.17854	1.17854	17.37260	1.17854	1.17854
29	17.37260	.00000	-1.66670	19.15030	.00000	-1.66670	17.37260	1.17854	-1.17854	19.15030	1.17854	-1.17854
30	17.37260	1.17854	-1.17854	19.15030	1.17854	-1.17854	17.37260	1.66670	.00000	19.15030	1.66670	.00000
31	17.37260	1.66670	.00000	19.15030	1.66670	.00000	17.37260	1.17854	1.17854	19.15030	1.66670	.00000
32	17.37260	1.17854	1.17854	19.15030	1.17854	1.17854	17.37260	1.66670	.00000	19.15030	1.17854	1.17854
33	19.15030	.00000	-1.66670	20.92800	.00000	-1.66670	19.15030	1.17854	-1.17854	20.92800	1.17854	-1.17854
34	19.15030	1.17854	-1.17854	20.92800	1.17854	-1.17854	19.15030	1.66670	.00000	20.92800	1.66670	.00000
35	19.15030	1.66670	.00000	20.92800	1.66670	.00000	19.15030	1.17854	1.17854	20.92800	1.17854	1.17854
36	19.15030	1.17854	1.17854	20.92800	1.17854	1.17854	19.15030	-.00000	1.66670	20.92800	1.17854	1.17854
37	20.92800	.00000	-1.66670	22.70580	.00000	-1.66670	20.92800	1.17854	1.17854	22.70580	1.17854	-1.17854
38	20.92800	1.17854	-1.17854	22.70580	1.17854	-1.17854	20.92800	1.66670	.00000	22.70580	1.17854	-1.17854
39	20.92800	1.66670	.00000	22.70580	1.66670	.00000	20.92800	1.17854	1.17854	22.70580	1.66670	.00000
40	20.92800	1.17854	1.17854	22.70580	1.17854	1.17854	20.92800	1.17854	1.17854	22.70580	1.17854	1.17854
41	22.70580	.00000	-1.66670	24.48350	.00000	-1.66670	22.70580	1.17854	-1.17854	24.48350	1.66670	.00000
42	22.70580	1.17854	-1.17854	24.48350	1.17854	-1.17854	22.70580	1.66670	.00000	24.48350	1.17854	-1.17854
43	22.70580	1.66670	.00000	24.48350	1.66670	.00000	22.70580	1.17854	1.17854	24.48350	1.66670	.00000
44	22.70580	1.17854	1.17854	24.48350	1.17854	1.17854	22.70580	1.66670	.00000	24.48350	1.17854	1.17854
45	24.48350	.00000	-1.66670	26.28000	.00000	-1.66670	24.48350	1.17854	-1.17854	26.28000	1.66670	.00000
46	24.48350	1.17854	-1.17854	26.28000	1.17854	-1.17854	24.48350	1.66670	.00000	26.28000	1.17854	-1.17854
47	24.48350	1.66670	.00000	26.28000	1.66670	.00000	24.48350	1.17854	1.17854	26.28000	1.66670	.00000
48	24.48350	1.17854	1.17854	26.28000	1.17854	1.17854	24.48350	1.17854	1.17854	26.28000	1.17854	1.17854
49	26.28000	.00000	-1.66670	29.40000	.00000	-1.66670	26.28000	1.17854	1.17854	29.40000	1.66670	.00000
50	26.28000	1.17854	-1.17854	29.40000	1.17854	-1.17854	26.28000	1.66670	.00000	29.40000	1.17854	-1.17854
51	26.28000	1.66670	.00000	29.40000	1.66670	.00000	26.28000	1.17854	1.17854	29.40000	1.66670	.00000
52	26.28000	1.17854	1.17854	29.40000	1.17854	1.17854	26.28000	1.17854	1.17854	29.40000	1.17854	1.17854
53	29.40000	.00000	-1.66670	33.00000	.00000	-1.66670	29.40000	1.17854	1.17854	33.00000	1.66670	.00000
54	29.40000	1.17854	-1.17854	33.00000	1.17854	-1.17854	29.40000	1.66670	.00000	33.00000	1.17854	-1.17854
55	29.40000	1.66670	.00000	33.00000	1.66670	.00000	29.40000	1.17854	1.17854	33.00000	1.66670	.00000
56	29.40000	1.17854	1.17854	33.00000	1.17854	1.17854	29.40000	1.17854	1.17854	33.00000	1.17854	1.17854
57	33.00000	.00000	-1.66670	36.50000	.00000	-1.66670	33.00000	1.17854	-1.17854	36.50000	1.66670	.00000
58	33.00000	1.17854	-1.17854	36.50000	1.17854	-1.17854	33.00000	1.66670	.00000	36.50000	1.17854	-1.17854
59	33.00000	1.66670	.00000	36.50000	1.66670	.00000	33.00000	1.17854	1.17854	36.50000	1.66670	.00000
60	33.00000	1.17854	1.17854	36.50000	1.17854	1.17854	33.00000	1.17854	1.17854	36.50000	1.17854	1.17854

BODY PANEL CONTROL POINT COORDINATES

POINT	X CP	Y CP	Z CP
1	1.00000	.09575	-.23116
2	1.00000	.23116	-.09575
3	1.00000	.23116	.09575
4	1.00000	.09575	.23116
5	3.22006	.27308	-.65928
6	3.22006	.65928	-.27308
7	3.22006	.65928	.27308
8	3.22006	.27308	.65928
9	6.08242	.44633	-1.07754
10	6.08242	1.07754	-.44633
11	6.08242	.44633	1.07754
12	6.08242	.44633	1.07754
13	9.03105	.55006	-1.32796
14	9.03105	1.32796	-.55006
15	9.03105	1.32796	.55006
16	9.03105	.55006	1.32796
17	11.08446	.58637	-1.41563
18	11.08446	1.41563	-.58637
19	11.08446	1.41563	.58637
20	11.08446	.58637	1.41563
21	13.63090	.58927	-1.42262
22	13.63090	1.42262	-.58927
23	13.63090	1.42262	.58927
24	13.63090	.58927	1.42262
25	16.48370	.58927	-1.42262
26	16.48370	1.42262	-.58927
27	16.48370	1.42262	.58927
28	16.48370	.58927	1.42262
29	18.26145	.58927	-1.42262
30	18.26145	1.42262	-.58927
31	18.26145	1.42262	.58927
32	18.26145	.58927	1.42262
33	20.03915	.58927	-1.42262
34	20.03915	1.42262	-.58927
35	20.03915	1.42262	.58927
36	20.03915	.58927	1.42262
37	21.81690	.58927	-1.42262
38	21.81690	1.42262	-.58927
39	21.81690	1.42262	.58927
40	21.81690	.58927	1.42262
41	23.59465	.58927	-1.42262
42	23.59465	1.42262	-.58927
43	23.59465	1.42262	.58927
44	23.59465	.58927	1.42262
45	25.38175	.58927	-1.42262
46	25.38175	1.42262	-.58927
47	25.38175	1.42262	.58927
48	25.38175	.58927	1.42262
49	27.84000	.58927	-1.42262
50	27.84000	1.42262	-.58927
51	27.84000	1.42262	.58927
52	27.84000	.58927	1.42262
53	31.20000	.58927	-1.42262
54	31.20000	1.42262	-.58927
55	31.20000	1.42262	.58927
56	31.20000	.58927	1.42262
57	34.75000	.58927	-1.42262
58	34.75000	1.42262	-.58927
59	34.75000	1.42262	.58927
60	34.75000	.58927	1.42262

BODY PANEL AREAS AND INCLINATION ANGLES

PANEL	AREA	DELTA	THETA
1	.24037	.24517	-2.74889
2	.24037	.24517	-1.96350
3	.24037	.24517	-1.17810
4	.24037	.24517	-.39270
5	1.69784	.19420	-2.74889
6	1.69784	.19420	-1.96350
7	1.69784	.19420	-1.17810
8	1.69784	.19420	-.39270
9	2.89570	.12634	-2.74889
10	2.89570	.12634	-1.96350
11	2.89570	.12634	-1.17810
12	2.89570	.12634	-.39270
13	3.57398	.05937	-2.74889
14	3.57398	.05937	-1.96350
15	3.57398	.05937	-1.17810
16	3.57398	.05937	-.39270
17	1.48147	.01298	-2.74889
18	1.48147	.01298	-1.96350
19	1.48147	.01298	-1.17810
20	1.48147	.01298	-.39270
21	5.01045	0.00000	-2.74889
22	5.01045	0.00000	-1.96350
23	5.01045	0.00000	-1.17810
24	5.01045	0.00000	-.39270
25	2.26783	0.00000	-2.74889
26	2.26783	0.00000	-1.96350
27	2.26783	0.00000	-1.17810
28	2.26783	0.00000	-.39270
29	2.26770	0.00000	-2.74889
30	2.26770	0.00000	-1.96350
31	2.26770	0.00000	-1.17810
32	2.26770	0.00000	-.39270
33	2.26770	0.00000	-2.74889
34	2.26770	0.00000	-1.96350
35	2.26770	0.00000	-1.17810
36	2.26770	0.00000	-.39270
37	2.26783	0.00000	-2.74889
38	2.26783	0.00000	-1.96350
39	2.26783	0.00000	-1.17810
40	2.26783	0.00000	-.39270
41	2.26770	0.00000	-2.74889
42	2.26770	0.00000	-1.96350
43	2.26770	0.00000	-1.17810
44	2.26770	0.00000	-.39270
45	2.29168	0.00000	-2.74889
46	2.29168	0.00000	-1.96350
47	2.29168	0.00000	-1.17810
48	2.29168	0.00000	-.39270
49	3.97999	0.00000	-2.74889
50	3.97999	0.00000	-1.96350
51	3.97999	0.00000	-1.17810
52	3.97999	0.00000	-.39270
53	4.59229	0.00000	-2.74889
54	4.59229	0.00000	-1.96350
55	4.59229	0.00000	-1.17810
56	4.59229	0.00000	-.39270
57	4.46473	0.00000	-2.74889
58	4.46473	0.00000	-1.96350
59	4.46473	0.00000	-1.17810
60	4.46473	0.00000	-.39270

PARTITION = 1 TIME = 86.64100
INFLUENCE OF BODY ON BODY

PARTITION = 2 TIME = 116.86700
INFLUENCE OF WING ON BODY

PARTITION = 3 TIME = 146.28100
INFLUENCE OF BODY ON WING

PARTITION = 4 TIME = 173.92100
INFLUENCE OF WING ON WING

TIME = 204.25900

TIME = 206.69900

TIME = 224.44500

VELOCITIES ON BODY, MACH=2.010 ALPHA= 0.000

PANEL NO.	SOURCE STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY	NORMAL VELOCITY
1	.19642	-.09678	.08648	-.20879	.25020
2	.19642	-.09678	.20879	-.08648	.25020
3	.19642	-.09678	.20879	.08648	.25020
4	.19642	-.09678	.08648	.20879	.25020
5	.17261	-.07016	.06998	-.16896	.19668
6	.17261	-.07016	.16896	-.06998	.19668
7	.17261	-.07016	.16896	.06998	.19668
8	.17261	-.07016	.06998	.16896	.19668
9	.11296	-.03539	.04689	-.11319	.12701
10	.11296	-.03539	.11319	-.04689	.12701
11	.11296	-.03539	.11319	.04689	.12701
12	.11296	-.03539	.04689	.11319	.12701
13	.05198	-.00181	.02270	-.05481	.05944
14	.05198	-.00181	.05481	-.02270	.05944
15	.05198	-.00181	.05481	.02270	.05944
16	.05198	-.00181	.02270	.05481	.05944
17	-.02286	.02050	.00507	-.01224	.01298
18	-.02286	.02050	.01224	-.00507	.01298
19	-.02286	.02050	.01224	.00507	.01298
20	-.02286	.02050	.00507	.01224	.01298
21	-.00277	.01807	.00000	.00000	-.00000
22	-.00277	.01807	.00000	.00000	-.00000
23	-.00277	.01807	-.00000	.00000	-.00000
24	-.00277	.01807	-.00000	.00000	-.00000
25	.02891	.00714	.00000	.00000	-.00000
26	.02891	.00714	-.00000	-.00000	.00000
27	.02891	.00714	.00000	-.00000	-.00000
28	.02891	.00714	-.00000	.00000	-.00000
29	-.00208	.00751	-.00000	-.00000	-.00000
30	.02371	-.00814	-.00807	-.01949	-.00000
31	.02371	-.00814	-.00807	.01949	-.00000
32	-.00208	.00751	.00000	-.00000	.00000
33	-.02323	.00037	-.01946	-.00806	.00000
34	.01089	.00055	-.00635	-.01534	-.00000
35	.01089	.00055	-.00635	.01534	-.00000
36	-.02323	.00037	-.01946	.00806	.00000
37	-.04014	-.00101	-.01001	-.00415	.00000
38	-.01999	.01434	.00025	.00060	.00000
39	-.01999	.01434	.00025	-.00060	.00000
40	-.04014	-.00101	-.01001	.00415	.00000
41	.00854	-.00006	.00244	.00101	-.00000
42	-.00627	.01918	.00711	.01716	.00000
43	-.00627	.01918	.00711	-.01716	.00000
44	.00854	-.00006	.00244	-.00101	.00000
45	.03622	.00587	.01490	.00617	-.00000
46	-.01324	.01811	.01223	.02952	.00000
47	-.01324	.01811	.01223	-.02952	.00000
48	.03622	.00587	.01490	-.00617	-.00000
49	.01694	.01450	.02036	.00843	-.00000
50	-.06066	.00777	.00965	.02329	.00000
51	-.06066	.00777	.00965	-.02329	.00000
52	.01694	.01450	.02036	-.00843	-.00000
53	.03094	.01317	.02397	.00993	.00000
54	-.05393	.01141	.01118	.02698	.00000
55	-.05393	.01141	.01118	-.02698	.00000
56	.03094	.01317	.02397	-.00993	.00000
57	.01268	.00842	.02074	.00859	.00000
58	-.07801	.00925	.01240	.02993	.00000
59	-.07801	.00925	.01240	-.02993	.00000
60	.01268	.00842	.02074	-.00859	.00000

OGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION

ON THE BODY

POINT	X	Y	Z	X/C	2Y/B	Z/C	CP	CN	CT	CM	POINT
1	1.00000	.09575	-.23116	.02740	.02875	-.06942	.15199	.03274	.00887	.44669	1
2	1.00000	.23116	-.09575	.02740	.06942	-.02875	.15199	.01356	.00887	.26787	2
3	1.00000	.23116	.09575	.02740	.06942	.02875	.15199	-.01356	.00887	.26787	3
4	1.00000	.09575	.23116	.02740	.02875	.06942	.15199	-.03274	.00887	.44669	4
5	3.22006	.27308	-.65928	.08822	.08201	-.19798	.11288	.17374	.03699	3.03221	5
6	3.22006	.65928	-.27308	.08822	.19798	-.08201	.11288	.07197	.03699	1.25598	6
7	3.22006	.65928	.27308	.08822	.19798	.08201	.11288	-.07197	.03699	-1.25598	7
8	3.22006	.27308	.65928	.08822	.08201	.19798	.11288	-.17374	.03699	-3.03222	8
9	6.08242	.44633	-1.07754	.16664	.13403	-.32359	.05759	.15283	.02101	2.22865	9
10	6.08242	1.07754	-.44633	.16664	.32359	-.13403	.05759	.06330	.02101	.92314	10
11	6.08242	1.07754	.44633	.16664	.32359	.13403	.05759	-.06330	.02101	-.92314	11
12	6.08242	.44633	1.07754	.16664	.13403	.32359	.05759	-.15283	.02101	-2.22865	12
13	9.03105	.55006	-1.32796	.24743	.16518	-.39879	.00010	.00034	.00002	.00392	13
14	9.03105	1.32796	-.55006	.24743	.39879	-.16518	.00010	.00014	.00002	.00163	14
15	9.03105	1.32796	.55006	.24743	.39879	.16518	.00010	-.00014	.00002	-.00163	15
16	9.03105	.55006	1.32796	.24743	.16518	.39879	.00010	-.00034	.00002	-.00392	16
17	11.08446	.58637	-1.41563	.30368	.17609	-.42511	-.03988	-.05458	-.00077	-.52986	17
18	11.08446	1.41563	-.58637	.30368	.42511	-.17609	-.03988	-.02261	-.00077	-.21948	18
19	11.08446	1.41563	.58637	.30368	.42511	.17609	-.03988	.02261	-.00077	.21948	19
20	11.08446	.58637	1.41563	.30368	.17609	.42511	-.03988	.05458	-.00077	.52986	20
21	13.63090	.58927	-1.42262	.37345	.17696	-.42721	-.03515	-.16270	0.00000	-1.16854	21
22	13.63090	1.42262	-.58927	.37345	.42721	-.17696	-.03515	-.06739	0.00000	-.48402	22
23	13.63090	1.42262	.58927	.37345	.42721	.17696	-.03515	.06739	0.00000	.48402	23
24	13.63090	.58927	1.42262	.37345	.17696	.42721	-.03515	.16270	0.00000	1.16854	24
25	16.48370	.58927	-1.42262	.45161	.17696	-.42721	-.01413	-.02960	0.00000	-.12817	25
26	16.48370	1.42262	-.58927	.45161	.42721	-.17696	-.01413	-.01226	0.00000	-.05309	26
27	16.48370	1.42262	.58927	.45161	.42721	.17696	-.01413	.01226	0.00000	.05309	27
28	16.48370	.58927	1.42262	.45161	.17696	.42721	-.01413	.02960	0.00000	.12817	28
29	18.26145	.58927	-1.42262	.50031	.17696	-.42721	-.01486	-.03112	0.00000	-.07942	29
30	18.26145	1.42262	-.58927	.50031	.42721	-.17696	.01602	.01390	0.00000	.03547	30
31	18.26145	1.42262	.58927	.50031	.42721	.17696	.01602	-.01390	0.00000	-.03547	31
32	18.26145	.58927	1.42262	.50031	.17696	.42721	-.01486	.03112	0.00000	.07942	32
33	20.03915	.58927	-1.42262	.54902	.17696	-.42721	-.00118	-.00248	0.00000	-.00192	33
34	20.03915	1.42262	-.58927	.54902	.42721	-.17696	-.00137	-.00119	0.00000	-.00092	34
35	20.03915	1.42262	.58927	.54902	.42721	.17696	-.00137	.00119	0.00000	.00092	35
36	20.03915	.58927	1.42262	.54902	.17696	.42721	-.00118	.00248	0.00000	.00192	36
37	21.81690	.58927	-1.42262	.59772	.17696	-.42721	.00191	.00400	0.00000	-.00401	37
38	21.81690	1.42262	-.58927	.59772	.42721	-.17696	-.02805	-.02434	0.00000	.02443	38
39	21.81690	1.42262	.58927	.59772	.42721	.17696	-.02805	.02434	0.00000	-.02443	39
40	21.81690	.58927	1.42262	.59772	.17696	.42721	-.00191	-.00400	0.00000	.00401	40
41	23.59465	.58927	-1.42262	.64643	.17696	-.42721	-.0010	-.00022	0.00000	-.00061	41
42	23.59465	1.42262	-.58927	.64643	.42721	-.17696	-.03756	-.03259	0.00000	.09066	42
43	23.59465	1.42262	.58927	.64643	.42721	.17696	-.03756	.03259	0.00000	-.09066	43
44	23.59465	.58927	1.42262	.64643	.17696	.42721	-.00010	-.00022	0.00000	.00061	44
45	25.38175	.58927	-1.42262	.69539	.17696	-.42721	-.01188	-.02515	0.00000	.11491	45
46	25.38175	1.42262	-.58927	.69539	.42721	-.17696	-.03616	-.03171	0.00000	.14490	46
47	25.38175	1.42262	.58927	.69539	.42721	.17696	-.03616	.03171	0.00000	-.14490	47
48	25.38175	.58927	1.42262	.69539	.17696	.42721	-.01188	.02515	0.00000	-.11491	48
49	27.84000	.58927	-1.42262	.76274	.17696	-.42721	-.02881	-.10593	0.00000	.74438	49
50	27.84000	1.42262	-.58927	.76274	.42721	-.17696	-.01596	-.02431	0.00000	.17085	50
51	27.84000	1.42262	.58927	.76274	.42721	.17696	-.01596	.02431	0.00000	-.17085	51
52	27.84000	.58927	1.42262	.76274	.17696	.42721	-.02881	.10593	0.00000	.74438	52
53	31.20000	.58927	-1.42262	.85479	.17696	-.42721	-.02645	-.11222	0.00000	.116565	53
54	31.20000	1.42262	-.58927	.85479	.42721	-.17696	-.02323	-.04083	0.00000	.42408	54
55	31.20000	1.42262	.58927	.85479	.42721	.17696	-.02323	.04083	0.00000	-.42408	55
56	31.20000	.58927	1.42262	.85479	.17696	.42721	-.02645	.11222	0.00000	-.16565	56
57	34.75000	.58927	-1.42262	.95205	.17696	-.42721	-.01712	-.07061	0.00000	.98404	57
58	34.75000	1.42262	-.58927	.95205	.42721	-.17696	-.01924	-.03288	0.00000	.45826	58
59	34.75000	1.42262	.58927	.95205	.42721	.17696	-.01924	.03288	0.00000	-.45826	59
60	34.75000	.58927	1.42262	.95205	.17696	.42721	-.01712	.07061	0.00000	-.98404	60

TOTAL COEFFICIENTS

ON THE BODY

REFA= 144.0000 REFD= 3.3300 REFL= 36.5000

REFX= 20.8130 REFL= 0.0000

CN= .0000

CT= .0037

CM= -.0000

CL= .0000

CD= .0037

XCP= -1.5870

VELOCITIES ON WING UPPER SURFACE, MACH=2.010 ALPHA= 0.000

PANEL NO.	VORTEX STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY
1	-.00000	-.12191	.14872	.17879
2	-.00000	.02325	-.06309	.05696
3	.00000	.00695	-.03468	.03265
4	.00000	.00518	-.02398	.01709
5	-.00000	.00868	-.01760	.00315
6	-.00000	.01821	-.02061	-.01379
7	-.00000	.02206	-.01522	-.02918
8	.00000	.02414	-.00917	-.03946
9	.00000	.02864	-.01025	-.04623
10	-.00000	.02582	-.00434	-.04704
11	-.00000	.02247	.00164	-.04710
12	.00000	-.12687	.15178	.17879
13	-.00000	-.03264	.04060	.05696
14	-.00000	-.00618	.00164	.03265
15	-.00000	.02367	-.05002	.01709
16	-.00000	.01651	-.03580	.00315
17	.00000	.02284	-.04163	-.01379
18	.00000	.02992	-.04226	-.02918
19	-.00000	.03571	-.04406	-.03946
20	-.00000	.03733	-.04154	-.04623
21	-.00000	.03439	-.03595	-.04704
22	-.00000	.03269	-.03250	-.04710
23	-.00000	-.12591	.14680	.17879
24	-.00000	-.03502	.04206	.05696
25	.00000	-.01856	.02123	.03265
26	-.00000	-.00934	.00966	.01709
27	-.00000	.00056	-.00363	.00315
28	-.00000	.02291	-.03670	-.01379
29	-.00000	.04714	-.07500	-.02918
30	-.00000	.04349	-.06282	-.03946
31	-.00000	.04270	-.05353	-.04623
32	-.00000	.04277	-.05200	-.04704
33	-.00000	.04111	-.04856	-.04710
34	-.00000	-.12906	.15068	.17879
35	.00000	-.03764	.04531	.05696
36	-.00000	-.01850	.01967	.03265
37	-.00000	-.00791	.00540	.01709
38	-.00000	-.00023	-.00397	.00315
39	-.00000	.01061	-.01688	-.01379
40	.00000	.01939	-.02695	-.02918
41	-.00000	.02434	-.03331	-.03946
42	-.00000	.02815	-.03980	-.04623
43	-.00000	.02809	-.04334	-.04704
44	.00000	.03065	-.04243	-.04710
45	-.00000	-.14159	.17134	.17879
46	-.00000	-.04752	.06159	.05696
47	-.00000	-.01946	.02050	.03265
48	-.00000	-.01057	.00896	.01709
49	-.00000	-.00287	-.00036	.00315
50	.00000	.00763	-.01249	-.01379
51	.00000	.01648	-.02250	-.02918
52	-.00000	.02364	-.03263	-.03946
53	-.00000	.02826	-.04052	-.04623
54	-.00000	.02754	-.04298	-.04704
55	-.00000	.02755	-.04707	-.04710

UGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION
ON THE WING UPPER SURFACE

POINT	MACH= 2.0100	ALPHA= 0.0000	X	Y	Z	X/C	2Y/B	Z/C	CP	CN	CT	CM	POINT
1	16.76499	2.30734	0.00000	.05000	.19228	0.00000	.07831	-.08627	.01017	-.34921	1		
2	17.61117	2.30734	0.00000	.15000	.19228	0.00000	-.03365	.03707	-.00166	.11869	2		
3	18.45734	2.30734	0.00000	.25000	.19228	0.00000	-.01353	.01490	-.00037	.03511	3		
4	19.30352	2.30734	0.00000	.35000	.19228	0.00000	-.01427	.01572	-.00016	.02373	4		
5	20.14970	2.30734	0.00000	.45000	.19228	0.00000	-.02670	.02941	.00016	.01951	5		
6	20.99587	2.30734	0.00000	.55000	.19228	0.00000	-.03980	.04384	.00094	-.00802	6		
7	21.84205	2.30734	0.00000	.65000	.19228	0.00000	-.04580	.05046	.00173	-.05192	7		
8	22.68823	2.30734	0.00000	.75000	.19228	0.00000	-.05237	.05769	.00247	-.10819	8		
9	23.53441	2.30734	0.00000	.85000	.19228	0.00000	-.05418	.05969	.00278	.16243	9		
10	24.38058	2.30734	0.00000	.95000	.19228	0.00000	-.04851	.05343	.00252	-.19063	10		
11	18.82577	4.12568	0.00000	.05000	.34381	0.00000	.14091	-.24418	.02878	-.48523	11		
12	19.55072	4.12568	0.00000	.15000	.34381	0.00000	.03717	-.06441	.00289	-.08131	12		
13	20.27568	4.12568	0.00000	.25000	.34381	0.00000	-.01839	.03187	-.00079	.01712	13		
14	21.00063	4.12568	0.00000	.35000	.34381	0.00000	-.04017	.07065	-.00071	.01326	14		
15	21.72559	4.12568	0.00000	.45000	.34381	0.00000	-.03961	.06864	.00037	-.06264	15		
16	22.45054	4.12568	0.00000	.55000	.34381	0.00000	-.05263	.09119	.00196	-.14933	16		
17	23.17550	4.12568	0.00000	.65000	.34381	0.00000	-.06497	.11258	.00386	-.26596	17		
18	23.90045	4.12568	0.00000	.75000	.34381	0.00000	-.07210	.12494	.00535	-.38575	18		
19	24.62541	4.12568	0.00000	.85000	.34381	0.00000	-.07093	.12292	.00573	-.46861	19		
20	25.35036	4.12568	0.00000	.95000	.34381	0.00000	-.06657	.11534	.00543	-.52336	20		
21	21.51108	6.49507	0.00000	.05000	.54126	0.00000	.14331	-.19052	.02246	.13300	21		
22	22.07808	6.49507	0.00000	.15000	.54126	0.00000	.05227	-.06950	.00311	.08792	22		
23	22.66507	6.49507	0.00000	.25000	.54126	0.00000	-.02754	-.03662	.00091	.06708	23		
24	23.21207	6.49507	0.00000	.35000	.54126	0.00000	-.00870	-.01157	.00012	.02776	24		
25	23.77906	6.49507	0.00000	.45000	.54126	0.00000	-.02337	.03107	.00017	-.09215	25		
26	24.34606	6.49507	0.00000	.55000	.54126	0.00000	-.06915	.09194	.00198	-.32482	26		
27	24.91305	6.49507	0.00000	.65000	.54126	0.00000	-.08921	.11860	.00407	-.48628	27		
28	25.48005	6.49507	0.00000	.75000	.54126	0.00000	-.08484	.11279	.00483	-.52638	28		
29	26.04704	6.49507	0.00000	.85000	.54126	0.00000	-.08398	.11164	.00521	-.58435	29		
30	26.61404	6.49507	0.00000	.95000	.54126	0.00000	-.08242	.10958	.00516	-.63568	30		
31	24.16649	8.83808	0.00000	.05000	.73651	0.00000	.14910	-.14335	.01690	.48071	31		
32	24.57728	8.83808	0.00000	.15000	.73651	0.00000	-.05497	-.05285	.00237	.19893	32		
33	24.98808	8.83808	0.00000	.25000	.73651	0.00000	-.02608	-.02507	.00062	.10468	33		
34	25.39887	8.83808	0.00000	.35000	.73651	0.00000	-.00806	-.00775	.00008	.03552	34		
35	25.80967	8.83808	0.00000	.45000	.73651	0.00000	-.01044	.01004	.00005	-.05018	35		
36	26.22046	8.83808	0.00000	.55000	.73651	0.00000	-.03020	.02904	.00062	-.15701	36		
37	26.63126	8.83808	0.00000	.65000	.73651	0.00000	-.04417	.04247	.00146	-.24711	37		
38	27.04205	8.83808	0.00000	.75000	.73651	0.00000	-.05322	.05117	.00219	-.31873	38		
39	27.45285	8.83808	0.00000	.85000	.73651	0.00000	-.05728	.05507	.00257	-.36568	39		
40	27.86364	8.83808	0.00000	.95000	.73651	0.00000	-.05967	.05737	.00270	-.40449	40		
41	26.58702	10.97384	0.00000	.05000	.91449	0.00000	.16990	-.08500	.01002	.49082	41		
42	26.85543	10.97384	0.00000	.15000	.91449	0.00000	.06594	-.03299	.00148	.19936	42		
43	27.12384	10.97384	0.00000	.25000	.91449	0.00000	-.02978	-.01490	.00037	.09402	43		
44	27.39225	10.97384	0.00000	.35000	.91449	0.00000	-.01342	-.00672	.00007	.04419	44		
45	27.66066	10.97384	0.00000	.45000	.91449	0.00000	-.00483	-.00242	.00001	-.01656	45		
46	27.92907	10.97384	0.00000	.55000	.91449	0.00000	-.02441	.01221	.00026	-.08692	46		
47	28.19748	10.97384	0.00000	.65000	.91449	0.00000	-.04067	.02035	.00070	-.15026	47		
48	28.46589	10.97384	0.00000	.75000	.91449	0.00000	-.05268	.02636	.00113	-.20172	48		
49	28.73430	10.97384	0.00000	.85000	.91449	0.00000	-.05689	.02847	.00133	-.22549	49		
50	29.00271	10.97384	0.00000	.95000	.91449	0.00000	-.05653	.02828	.00133	-.23164	50		

VELOCITIES ON WING LOWER SURFACE, MACH=2.010 ALPHA= 0.000

PANEL NO.	VORTEX STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY
1	-.00000	-.12191	.14872	-.17879
2	-.00000	.02325	-.06309	-.05696
3	.00000	.00695	-.03468	-.03265
4	.00000	.00518	-.02358	-.01709
5	.00000	.00868	-.01760	-.00315
6	-.00000	.01821	-.02061	.01379
7	-.00000	.02206	-.01522	.02918
8	.00000	.02414	-.00917	.03946
9	.00000	.02864	-.01025	.04623
10	.00000	.02582	-.00434	.04704
11	-.00000	.02247	.00144	.04710
12	-.00000	-.12687	.15178	-.17879
13	-.00000	-.03264	.04060	-.05696
14	-.00000	-.00618	.00164	-.03265
15	-.00000	.02367	-.05002	-.01709
16	-.00000	.01651	-.03580	-.00315
17	-.00000	.02284	-.04163	.01379
18	.00000	.02992	-.04226	.02918
19	-.00000	.03571	-.04406	.03946
20	-.00000	.03733	-.04194	.04623
21	-.00000	.03439	-.03555	.04704
22	-.00000	.03269	-.03250	.04710
23	-.00000	-.12591	.14680	-.17879
24	-.00000	-.03502	.04206	-.05696
25	-.00000	-.01856	.02123	-.03265
26	-.00000	-.00934	.00966	-.01709
27	-.00000	.00056	-.00363	-.00315
28	-.00000	.02291	-.03670	.01379
29	-.00000	.04714	-.07500	.02918
30	-.00000	.04349	-.06282	.03946
31	-.00000	.04270	-.05353	.04623
32	-.00000	.04277	-.05200	.04704
33	-.00000	.04111	-.04856	.04710
34	-.00000	-.12906	.15068	-.17879
35	.00000	-.03764	.04531	-.05696
36	-.00000	-.01850	.01967	-.03265
37	-.00000	-.00791	.00540	-.01709
38	-.00000	-.00023	-.00397	-.00315
39	-.00000	.01061	-.01688	.01379
40	.00000	.01939	-.02695	.02918
41	-.00000	.02434	-.03331	.03946
42	-.00000	.02815	-.03980	.04623
43	-.00000	.02809	-.04334	.04704
44	-.00000	.03065	-.04243	.04710
45	-.00000	-.14159	.17134	-.17879
46	-.00000	-.04752	.06159	-.05696
47	.00000	-.01946	.02050	-.03265
48	.00000	-.01057	.00896	-.01709
49	-.00000	-.00287	-.00036	-.00315
50	.00000	.00763	-.01249	.01379
51	.00000	.01648	-.02250	.02918
52	-.00000	.02364	-.03263	.03946
53	-.00000	.02826	-.04052	.04623
54	-.00000	.02754	-.04298	.04704
55	-.00000	.02755	-.04707	.04710

OGIVE CYLINDER BCODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION
ON THE WING LOWER SURFACE

POINT	MACH= 2.0100	ALPHA= 0.0000	X	Y	Z	X/C	2Y/B	Z/C	CP	CN	CT	CM	POINT
1	16.76499	2.30734	0.00000	.05000	.19228	0.00000	.07831	.08627	.01017	.34921	1		
2	17.61117	2.30734	0.00000	.15000	.19228	0.00000	-.03365	-.03707	-.00166	-.11869	2		
3	18.45734	2.30734	0.00000	.25000	.19228	0.00000	-.01353	-.01490	-.00037	-.03511	3		
4	19.30352	2.30734	0.00000	.35000	.19228	0.00000	-.01427	-.01572	-.00016	-.02373	4		
5	20.14970	2.30734	0.00000	.45000	.19228	0.00000	-.02670	-.02941	.00016	-.01951	5		
6	20.99587	2.30734	0.00000	.55000	.19228	0.00000	-.03980	-.04384	.00094	.00802	6		
7	21.84205	2.30734	0.00000	.65000	.19228	0.00000	-.04580	-.05046	-.00173	-.05192	7		
8	22.68823	2.30734	0.00000	.75000	.19228	0.00000	-.05237	-.05769	-.00247	.10819	8		
9	23.53441	2.30734	0.00000	.85000	.19228	0.00000	-.05418	-.05969	-.00278	.16243	9		
10	24.38058	2.30734	0.00000	.95000	.19228	0.00000	-.04851	-.05343	.00252	.19063	10		
11	16.82577	4.12568	0.00000	.05000	.34381	0.00000	.14091	.24418	.02878	.48523	11		
12	19.55072	4.12568	0.00000	.15000	.34381	0.00000	.03717	.06441	.00289	.08131	12		
13	20.27568	4.12568	0.00000	.25000	.34381	0.00000	-.01839	-.03187	-.00079	-.01712	13		
14	21.00063	4.12568	0.00000	.35000	.34381	0.00000	-.04077	-.07065	-.00071	.01326	14		
15	21.72559	4.12568	0.00000	.45000	.34381	0.00000	-.03961	-.06864	.00037	.06266	15		
16	22.45054	4.12568	0.00000	.55000	.34381	0.00000	-.05263	-.09119	.00196	.14933	16		
17	23.17550	4.12568	0.00000	.65000	.34381	0.00000	-.06497	-.11258	.00386	.26596	17		
18	23.90045	4.12568	0.00000	.75000	.34381	0.00000	-.07210	-.12494	.00535	.38575	18		
19	24.62541	4.12568	0.00000	.85000	.34381	0.00000	-.07093	-.12292	.00573	.46661	19		
20	25.35036	4.12568	0.00000	.95000	.34381	0.00000	-.06657	-.11534	.00543	.52336	20		
21	21.51108	6.49507	0.00000	.05000	.54126	0.00000	.14331	.19052	.02246	-.13300	21		
22	22.07808	6.49507	0.00000	.15000	.54126	0.00000	-.05227	.06950	.00311	-.08792	22		
23	22.64507	6.49507	0.00000	.25000	.54126	0.00000	.02754	.03662	.00091	-.06708	23		
24	23.21207	6.49507	0.00000	.35000	.54126	0.00000	-.00870	.01157	.00012	-.02776	24		
25	23.77906	6.49507	0.00000	.45000	.54126	0.00000	-.02337	-.03107	.00017	.09215	25		
26	24.34606	6.49507	0.00000	.55000	.54126	0.00000	-.06915	-.09194	.00198	.32482	26		
27	24.91305	6.49507	0.00000	.65000	.54126	0.00000	-.08921	-.11860	.00407	.48628	27		
28	25.48005	6.49507	0.00000	.75000	.54126	0.00000	-.08484	-.11279	.00483	.52638	28		
29	26.04704	6.49507	0.00000	.85000	.54126	0.00000	-.08398	-.11164	.00521	.58435	29		
30	26.61404	6.49507	0.00000	.95000	.54126	0.00000	-.08242	-.10958	.00516	.63568	30		
31	24.16649	8.83808	0.00000	.05000	.73651	0.00000	.14910	.14335	.01690	-.48071	31		
32	24.57728	8.83808	0.00000	.15000	.73651	0.00000	.05497	.05285	.00237	-.19893	32		
33	24.98808	8.83808	0.00000	.25000	.73651	0.00000	-.02608	-.02507	.00062	-.10468	33		
34	25.39887	8.83808	0.00000	.35000	.73651	0.00000	-.00806	-.00775	.00008	-.03552	34		
35	25.80967	8.83808	0.00000	.45000	.73651	0.00000	-.01044	-.01004	.00005	.05018	35		
36	26.22046	8.83808	0.00000	.55000	.73651	0.00000	-.03020	-.02904	.00062	.15701	36		
37	26.63126	8.83808	0.00000	.65000	.73651	0.00000	-.04617	-.04247	.00146	.24711	37		
38	27.04205	8.83808	0.00000	.75000	.73651	0.00000	-.05322	-.05117	.00219	.31873	38		
39	27.45285	8.83808	0.00000	.85000	.73651	0.00000	-.05728	-.05507	.00257	.36568	39		
40	27.86364	8.83808	0.00000	.95000	.73651	0.00000	-.05967	-.05737	.00270	.40449	40		
41	26.58702	10.97384	0.00000	.05000	.91449	0.00000	-.16990	.08500	.01002	-.49082	41		
42	26.85543	10.97384	0.00000	.15000	.91449	0.00000	-.04594	.03299	.00148	-.19936	42		
43	27.12384	10.97384	0.00000	.25000	.91449	0.00000	.02978	.01490	.00037	.09402	43		
44	27.39225	10.97384	0.00000	.35000	.91449	0.00000	.01342	.00672	.00007	-.04419	44		
45	27.66066	10.97384	0.00000	.45000	.91449	0.00000	-.00483	-.00242	.00001	.01656	45		
46	27.92907	10.97384	0.00000	.55000	.91449	0.00000	-.02441	-.01221	.00026	.08692	46		
47	28.19748	10.97384	0.00000	.65000	.91449	0.00000	-.04067	-.02035	.00070	.15026	47		
48	28.46589	10.97384	0.00000	.75000	.91449	0.00000	-.05268	-.02636	.00113	.20172	48		
49	28.73430	10.97384	0.00000	.85000	.91449	0.00000	-.05689	-.02847	.00133	.22549	49		
50	29.00271	10.97384	0.00000	.95000	.91449	0.00000	-.05653	-.02828	.00133	.23164	50		

TOTAL COEFFICIENTS

ON THE WING

REFA=	144.0000	REFB=	12.0000	REFC=	6.8900
REFX=	20.8130	REFZ=	0.0000		
CN=	-.0000				
CT=	.0046				
CM=	.0000				
CL=	-.0000				
CD=	.0046				
XCP=	-.1056				

TOTAL COEFFICIENTS

ON THE COMPLETE CONFIGURATION

REFA=	144.0000	REFB=	12.0000	REFC=	6.8900
REFX=	20.8130	REFZ=	0.0000		
CN=	.0000				
CT=	.0083				
CM=	-.0000				
CL=	.0000				
CD=	.0083				
XCP=	-3.5710				

SECTION COEFFICIENTS

ON THE WING

DELY=	1.3030	REFL=	6.8900	XLE=	16.3419
CN=	-.0000				
CT=	.0034				
CM=	-.0000				
CL=	-.0000				
CD=	.0034				
XCP=	.3338				

DELY=	2.4000	REFL=	6.8900	XLE=	18.4633
CN=	-.0000				
CT=	.0061				
CM=	.0000				
CL=	-.0000				
CD=	.0061				
XCP=	-.1551				

DELY=	2.3600	REFL=	6.8900	XLE=	21.2276
CN=	-.0000				
CT=	.0072				
CM=	.0000				
CL=	-.0000				
CD=	.0072				
XCP=	-.4477				

SECTION COEFFICIENTS

ON THE WING

DELY=	2.3700	REFL=	6.8900	XLE=	23.9611
CN=	-.0000				
CT=	.0061				
CM=	.0000				
CL=	-.0000				
CD=	.0061				
XCP=	-.6329				

DELY=	1.9000	REFL=	6.8900	XLE=	26.4528
CN=	.0000				
CT=	.0065				
CM=	.0000				
CL=	.0000				
CD=	.0065				
XCP=	3.0337				

CPSTAG = 2.45650 CPCRIT = 1.13092 CPVAC = -.35360

TIME = 253.82300

TIME = 256.24700

TIME = 274.05300

VELOCITIES ON BODY, MACH=2.010 ALPHA= 5.000

PANEL NO.	SOURCE STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY	NORMAL VELOCITY
1	.29821	-.12592	.12742	-.27006	.32977
2	.23814	-.10863	.24926	-.06568	.28260
3	.15320	-.08418	.16672	.10663	.21590
4	.09313	-.06689	.04488	.14592	.16873
5	.29647	-.09585	.11639	-.23061	.27645
6	.22353	-.08065	.21498	-.03868	.22928
7	.12038	-.05914	.12165	.10076	.16258
8	.04744	-.04393	.02305	.10602	.11541
9	.25703	-.05884	.09712	-.17579	.20705
10	.17238	-.04502	.16318	-.00891	.15988
11	.05267	-.02549	.06234	.08451	.09318
12	-.03198	-.01167	-.00371	-.04973	.04601
13	.22872	-.01979	.07956	-.11702	.13973
14	.12507	-.00925	.11155	.02886	.09256
15	-.02150	.00564	-.00234	.07409	.02586
16	-.12515	.01618	-.03433	-.00781	-.02131
17	.16034	.00840	.06631	-.07381	.09346
18	.05307	.01544	.07345	.05586	.04629
19	-.09862	.02540	-.04907	.06596	-.02042
20	-.20589	.03245	-.05621	-.04942	-.06759
21	.19295	.01318	.06479	-.06032	.08052
22	.07831	.01601	.06479	.06925	.03335
23	-.08383	.02000	-.06479	.06925	-.03335
24	-.19848	.02282	-.06479	-.06032	-.08052
25	.23512	.00731	.06586	-.05996	.08052
26	.11426	.00720	.06586	.07137	.03335
27	-.05666	.00703	-.06586	.07137	-.03335
28	-.17752	.00692	-.06586	-.05996	-.08052
29	-.15629	.00058	-.00204	-.08800	.08052
30	-.07665	-.03603	.00504	-.07486	.03330
31	.12388	.01975	-.02128	-.03592	-.03340
32	.15214	.01440	.00204	-.08800	-.08052
33	.00748	-.03345	-.02645	-.09813	.08054
34	.00491	-.03148	-.02400	-.14499	.03331
35	.01679	.03255	.01123	-.11439	-.03340
36	-.05376	.03414	-.01240	-.08200	-.08050
37	.05941	-.04515	-.01938	-.09522	.08056
38	-.00215	-.00961	-.00666	-.10331	.03338
39	-.03768	.03816	.00723	-.10454	-.03333
40	-.13940	.04306	-.00056	-.08689	-.08049
41	-.10269	-.01962	.03603	-.07224	.08053
42	-.09683	-.01116	.01946	.04030	.03340
43	.08433	.04942	-.00515	-.07459	-.03330
44	.11970	.01950	-.03113	-.07425	-.08051
45	.09772	-.03097	.01107	-.08255	.08050
46	-.03546	-.03552	-.01010	-.11170	.03342
47	.00907	.07167	.03465	-.17065	-.03329
48	-.02556	.04271	.01866	-.09491	-.08054
49	.04061	-.02359	.04121	-.07005	.08049
50	-.06008	-.00391	.03051	-.01369	.03343
51	-.06077	.01942	-.01112	-.06012	-.03328
52	-.00687	.05255	-.00061	-.08694	-.08055
53	.16146	-.00624	.06860	-.05875	.08053
54	-.03317	-.00266	.04641	.02451	.03349
55	-.07429	.02541	-.02383	-.02926	-.03321
56	-.09979	.03250	-.02073	-.07855	-.08051
57	.16721	.00258	.06929	-.05867	.08053
58	-.01301	.01136	.06502	.06939	.03351
59	-.14241	.00707	-.03996	.00974	-.03319
60	-.14195	.01420	-.02790	-.07559	-.08051

OGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION

ON THE BODY

POINT	X	Y	Z	X/C	2Y/B	Z/C	CP	CN	CT	CM	POINT
1	1.00000	.09575	-.23116	.02740	.02875	-.06942	.23352	.05031	.01362	.99362	1
2	1.00000	.23116	-.09575	.02740	.06942	-.02875	.17365	.01550	.01013	.30604	2
3	1.00000	.23116	.09575	.02740	.06942	.02875	.11402	-.01017	.00665	-.20096	3
4	1.00000	.09575	.23116	.02740	.02875	.06942	.08674	-.01869	.00506	-.36905	4
5	3.22006	.27308	-.65928	.08822	.08201	-.19798	.18116	.27883	.05936	4.86624	5
6	3.22006	.65928	-.27308	.08822	.19798	-.08201	.12674	.08080	.04153	1.41019	6
7	3.22006	.65928	.27308	.08822	.19798	.08201	.07717	-.04920	.02529	-.85865	7
8	3.22006	.27308	.65928	.08822	.08201	.19798	.05850	-.09004	.01917	-1.57145	8
9	6.08242	.44633	-1.07754	.16664	.13403	-.32359	.11548	.30647	.04213	4.46908	9
10	6.08242	1.07754	-.44633	.16664	.32359	-.13403	.06657	.07318	.02429	1.06719	10
11	6.08242	1.07754	.44633	.16664	.32359	.13403	.02498	-.02746	.00911	-.40042	11
12	6.08242	-.44633	1.07754	.16664	.32359	.13403	.01211	-.03215	.00442	-.46878	12
13	9.03105	.55006	-1.32796	.24743	.16518	-.39879	.04100	.13514	.00869	1.58062	13
14	9.03105	1.32796	-.55006	.24743	.39879	-.16518	.00005	.00006	.00001	.00073	14
15	9.03105	1.32796	.55006	.24743	.39879	.16518	-.02880	.03933	-.00611	.45998	15
16	9.03105	.55006	1.32796	.24743	.16518	.39879	-.03132	.10324	-.00664	1.20759	16
17	11.08466	.58637	-1.41563	.30368	.17609	-.42511	.01359	-.01860	-.00026	-.18057	17
18	11.08466	1.41563	-.58637	.30368	.42511	-.17609	-.04685	-.02656	-.00090	-.25787	18
19	11.08466	1.41563	.58637	.30368	.42511	.17609	-.04477	.03672	-.00125	.35647	19
20	11.08466	.58637	1.41563	.30368	.17609	.42511	-.05882	.08050	-.00113	.78153	20
21	13.63090	.58927	-1.42262	.37345	.17696	-.42721	-.02320	-.10738	0.00000	-.77118	21
22	13.63090	1.42262	-.58927	.37345	.42721	-.17656	-.05041	-.09667	0.00000	-.69426	22
23	13.63090	1.42262	.58927	.37345	.42721	.17696	-.05761	.11046	0.00000	-.79336	23
24	13.63090	.58927	1.42262	.37345	.17696	.42721	-.04146	.19190	0.00000	1.37824	24
25	16.48370	.56927	-1.42262	.45161	.17696	-.42721	-.01193	-.02500	0.00000	-.10824	25
26	16.48370	1.42262	-.56927	.45161	.42721	-.17696	-.03493	-.03031	0.00000	-.13124	26
27	16.48370	1.42262	.56927	.45161	.42721	.17696	-.03462	.03005	0.00000	.13009	27
28	16.48370	.56927	1.42262	.45161	.17696	.42721	-.01116	.02338	0.00000	.10121	28
29	18.26145	.58927	-1.42262	.50031	.17696	-.42721	.00649	.01359	0.00000	.03468	29
30	18.26145	1.42262	-.58927	.50031	.42721	-.17696	-.08422	.07309	0.00000	.18649	30
31	18.26145	1.42262	.58927	.50031	.42721	.17696	-.03398	.02949	0.00000	.07524	31
32	18.26145	.58927	1.42262	.50031	.17696	.42721	-.02084	.04367	0.00000	.11142	32
33	20.03915	.58927	-1.42262	.54902	.17696	-.42721	.07774	.15268	0.00000	.12604	33
34	20.03915	1.42262	-.58927	.54902	.42721	-.17696	.06984	.06061	0.00000	.04690	34
35	20.03915	1.42262	.58927	.54902	.42721	.17696	-.05572	.04836	0.00000	.03742	35
36	20.03915	.58927	1.42262	.54902	.17696	.42721	-.05800	.12152	0.00000	.09404	36
37	21.81690	.58927	-1.42262	.59772	.17696	-.42721	.10655	.21906	0.00000	-.21991	37
38	21.81690	1.42262	-.58927	.59772	.42721	-.17696	.02705	.02348	0.00000	-.02357	38
39	21.81690	1.42262	.58927	.59772	.42721	.17696	-.06541	.05676	0.00000	-.05698	39
40	21.81690	.58927	1.42262	.59772	.17696	.42721	-.07379	.15461	0.00000	-.15522	40
41	23.59465	.58927	-1.42262	.64643	.17696	-.42721	.04685	.09816	0.00000	-.27305	41
42	23.59465	1.42262	-.58927	.64643	.42721	-.17656	.02789	.02420	0.00000	-.06733	42
43	23.59465	1.42262	.58927	.64643	.42721	.17696	-.08500	.07377	0.00000	-.20520	43
44	23.59465	.58927	1.42262	.64643	.17696	.42721	-.03171	.06643	0.00000	-.18478	44
45	25.38175	.58927	-1.42262	.69539	.17696	-.42721	.07302	.15461	0.00000	.70637	45
46	25.38175	1.42262	-.58927	.69539	.42721	-.17656	.08247	.07233	0.00000	.33046	46
47	25.38175	1.42262	.58927	.69539	.42721	.17696	-.12755	.11186	0.00000	.51105	47
48	25.38175	.58927	1.42262	.69539	.17696	.42721	-.07352	.15565	0.00000	-.71114	48
49	27.84000	.58927	-1.42262	.76274	.17696	-.42721	.05484	.20165	0.00000	-.141697	49
50	27.84000	1.42262	-.58927	.76274	.42721	-.17656	.00912	.01390	0.00000	-.09766	50
51	27.84000	1.42262	.58927	.76274	.42721	.17696	-.03128	.04764	0.00000	-.33476	51
52	27.84000	.58927	1.42262	.76274	.17696	.42721	-.09019	.33164	0.00000	-.233045	52
53	31.20000	.58927	-1.42262	.85479	.17696	-.42721	.01468	.06230	0.00000	-.64709	53
54	31.20000	1.42262	-.58927	.85479	.42721	-.17696	-.00172	-.00303	0.00000	.03142	54
55	31.20000	1.42262	.58927	.85479	.42721	.17696	-.04535	.07970	0.00000	-.82789	55
56	31.20000	.58927	1.42262	.85479	.17696	.42721	-.05531	.23467	0.00000	-.243756	56
57	34.75000	.58927	-1.42262	.95205	.17696	-.42721	-.00317	-.01308	0.00000	.18229	57
58	34.75000	1.42262	-.58927	.95205	.42721	-.17636	-.04199	-.07174	0.00000	.99979	58
59	34.75000	1.42262	.58927	.95205	.42721	.17656	-.01723	.02943	0.00000	-.41022	59
60	34.75000	.58927	1.42262	.95205	.17696	.42721	-.02134	.08802	0.00000	-.122679	60

TOTAL COEFFICIENTS

ON THE BODY

REFA=	144.0000	REFD=	3.3300	REFL=	36.5000
REFX=	20.8130	REFZ=	0.0000		
CN=	.0526				
CT=	.0035				
CM=	.0053				
CL=	.0521				
CD=	.0081				
XCP=	.1021				

VELOCITIES ON WING UPPER SURFACE, MACH=2.010 ALPHA= 5.000

PANEL NO.	VORTEX STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY
1	.22408	-.00993	.01805	.09163
2	.20022	.12328	-.18020	-.03020
3	.16902	.09144	-.13524	-.05450
4	.12030	.06533	-.09981	-.07007
5	.07135	.04435	-.07099	-.08401
6	.03408	.03523	-.05783	-.10095
7	.03636	.04023	-.05336	-.11633
8	.06207	.05516	-.05672	-.12661
9	.07180	.06449	-.06097	-.13338
10	.08669	.06911	-.05953	-.13419
11	.11014	.07749	-.06001	-.13426
12	.16587	-.04398	.05506	.09163
13	.16609	.05036	-.05625	-.03020
14	.17415	.08086	-.09951	-.05450
15	.16984	.10855	-.14900	-.07007
16	.15922	.09612	-.12989	-.08401
17	.13547	.09057	-.12543	-.10095
18	.10343	.08163	-.11324	-.11633
19	.06977	.07059	-.10269	-.12661
20	.05319	.06391	-.09504	-.13338
21	.04661	.05768	-.08707	-.13419
22	.04233	.05383	-.08245	-.13426
23	.14925	-.05133	.05979	.09163
24	.14901	.03945	-.04483	-.03020
25	.15071	.05676	-.06657	-.05450
26	.15332	.06729	-.07945	-.07007
27	.15678	.07891	-.09435	-.08401
28	.16070	.10322	-.12910	-.10095
29	.16060	.12730	-.16727	-.11633
30	.15640	.12167	-.15367	-.12661
31	.14846	.11695	-.14177	-.13338
32	.13225	.10889	-.13537	-.13419
33	.11211	.05716	-.12656	-.13426
34	.14331	-.05743	.06712	.09163
35	.14342	.03404	-.03833	-.03020
36	.14370	.05333	-.06412	-.05450
37	.14424	.06417	-.07864	-.07007
38	.14474	.07211	-.08825	-.08401
39	.14546	.08331	-.10147	-.10095
40	.14666	.09269	-.11202	-.11633
41	.14815	.09839	-.11893	-.12661
42	.14990	.10307	-.12600	-.13338
43	.15198	.10406	-.13016	-.13419
44	.15348	.10761	-.12978	-.13426
45	.14022	-.07147	.08651	.09163
46	.14038	.02268	-.02033	-.03020
47	.14054	.05080	-.06147	-.05450
48	.14085	.05984	-.07314	-.07007
49	.14119	.06769	-.08261	-.08401
50	.14151	.07836	-.09488	-.10095
51	.14182	.08737	-.10503	-.11633
52	.14215	.05469	-.11528	-.12661
53	.14254	.09951	-.12328	-.13338
54	.14289	.09895	-.12564	-.13419
55	.14325	.09913	-.13002	-.13426

OGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION
ON THE WING UPPER SURFACE

POINT	MACH= 2.0100	ALPHA= 5.0000	X	Y	Z	X/C	ZY/B	Z/C	CP	CN	CT	CM	POINT
1	16.76499	2.30734	0.00000	.05000	.19228	0.00000	-.10958	.12071	-.01423	.48864	1		
2	17.61117	2.30734	0.00000	.15000	.19228	0.00000	-.18922	.20844	-.00934	.66740	2		
3	18.45734	2.30734	0.00000	.25000	.19228	0.00000	-.14170	.15610	-.00388	.36772	3		
4	19.30352	2.30734	0.00000	.35000	.19228	0.00000	-.09971	.10984	-.00111	.16580	4		
5	20.14970	2.30734	0.00000	.45000	.19228	0.00000	-.07159	.07887	.00042	.05231	5		
6	20.99587	2.30734	0.00000	.55000	.19228	0.00000	-.06742	.07427	.00160	.01358	6		
7	21.84205	2.30734	0.00000	.65000	.19228	0.00000	-.08517	.09383	.00322	.09655	7		
8	22.68823	2.30734	0.00000	.75000	.19228	0.00000	-.10645	.11727	.00502	.21991	8		
9	23.53441	2.30734	0.00000	.85000	.19228	0.00000	-.11814	.13014	.00607	.35417	9		
10	24.38058	2.30734	0.00000	.95000	.19228	0.00000	-.12830	.14133	.00665	.50421	10		
11	18.82577	4.12568	0.00000	.05000	.34381	0.00000	-.01494	.02588	-.00305	.05143	11		
12	19.55072	4.12568	0.00000	.15000	.34381	0.00000	-.11757	.20373	-.00913	.25717	12		
13	20.27568	4.12568	0.00000	.25000	.34381	0.00000	-.16626	.28810	-.00716	.15480	13		
14	21.00063	4.12568	0.00000	.35000	.34381	0.00000	-.17911	.31036	-.00314	.05823	14		
15	21.72559	4.12568	0.00000	.45000	.34381	0.00000	-.16501	.28593	.00152	.26094	15		
16	22.45054	4.12568	0.00000	.55000	.34381	0.00000	-.15367	.26627	.00572	.43603	16		
17	23.17550	4.12568	0.00000	.65000	.34381	0.00000	-.13760	.23844	.00818	.56330	17		
18	23.90045	4.12568	0.00000	.75000	.34381	0.00000	-.12315	.21339	.00914	.65883	18		
19	24.62541	4.12568	0.00000	.85000	.34381	0.00000	-.11204	.19414	.00905	.74012	19		
20	25.35036	4.12568	0.00000	.95000	.34381	0.00000	-.10303	.17853	.00840	.81004	20		
21	21.51108	6.49507	0.00000	.05000	.54126	0.00000	.00257	-.00342	.00040	.00239	21		
22	22.07808	6.49507	0.00000	.15000	.54126	0.00000	-.08677	.11535	-.00517	.14593	22		
23	22.66507	6.49507	0.00000	.25000	.54126	0.00000	-.1058	.14701	-.00366	.26934	23		
24	23.21207	6.49507	0.00000	.35000	.54126	0.00000	-.12933	.17194	-.00174	.41251	24		
25	23.77906	6.49507	0.00000	.45000	.54126	0.00000	-.15894	.21131	-.00112	.62676	25		
27	24.91305	6.49507	0.00000	.55000	.54126	0.00000	-.19700	.26191	.00563	.92533	26		
28	25.48005	6.49507	0.00000	.65000	.54126	0.00000	-.21101	.28052	.00963	-1.15017	27		
29	26.04704	6.49507	0.00000	.75000	.54126	0.00000	-.20309	.27001	.01157	-1.26013	28		
30	26.61404	6.49507	0.00000	.85000	.54126	0.00000	-.19389	.25777	.01202	-1.34916	29		
31	24.16649	8.83808	0.00000	.95000	.73651	0.00000	-.17989	.23916	.01126	-1.38737	30		
32	24.57728	8.83808	0.00000	.05000	.73651	0.00000	.01376	-.01323	.00156	.04436	31		
33	24.98808	8.83808	0.00000	.15000	.73651	0.00000	-.07874	.07570	-.00339	-.28496	32		
34	25.39887	8.83808	0.00000	.25000	.73651	0.00000	-.10507	.10102	-.00251	-.42175	33		
35	25.40967	8.83808	0.00000	.35000	.73651	0.00000	-.12121	.11654	-.00118	-.53442	34		
36	26.22066	8.83808	0.00000	.45000	.73651	0.00000	-.13736	.13206	.00070	-.65988	35		
37	26.63126	8.83808	0.00000	.55000	.73651	0.00000	-.15448	.14852	.00319	-.80313	36		
38	27.04205	8.83808	0.00000	.65000	.73651	0.00000	-.16686	.16043	.00551	-.93341	37		
39	27.45285	8.83808	0.00000	.75000	.73651	0.00000	-.17540	.16863	.00722	-1.05041	38		
40	27.86364	8.83808	0.00000	.85000	.73651	0.00000	-.18025	.17330	.00808	-1.15065	39		
41	26.58702	10.97384	0.00000	.95000	.73651	0.00000	-.18353	.17646	.00831	-1.24413	40		
42	26.85543	10.97384	0.00000	.05000	.91449	0.00000	-.03823	-.01913	.00225	.11044	41		
43	27.12384	10.97384	0.00000	.15000	.91449	0.00000	-.06559	.03282	-.00147	.19831	42		
44	27.39225	10.97384	0.00000	.25000	.91449	0.00000	-.09898	.04952	-.00123	.31252	43		
45	27.66066	10.97384	0.00000	.35000	.91449	0.00000	-.11357	.05682	-.00057	.37386	44		
46	27.92907	10.97384	0.00000	.45000	.91449	0.00000	-.12942	.06475	.00034	.44341	45		
47	28.19748	10.97384	0.00000	.55000	.91449	0.00000	-.14007	.07308	.00157	.52006	46		
48	28.46549	10.97384	0.00000	.65000	.91449	0.00000	-.15978	.07994	.00274	.59032	47		
49	28.73430	10.97384	0.00000	.75000	.91449	0.00000	-.17000	.08505	.00364	.65091	48		
50	29.00271	10.97384	0.00000	.85000	.91449	0.00000	-.17392	.08702	.00406	.68928	49		
			.95000	.91449	0.00000	-.17421	.08716	.00410	-.71385	50			

VELOCITIES ON WING LOWER SURFACE, MACH=2.010 ALPHA= 5.000

PANEL NO.	VORTEX STRENGTH	AXIAL VELOCITY	LATERAL VELOCITY	VERTICAL VELOCITY
1	.22408	-.23401	.27568	-.26595
2	.20022	-.07694	.05618	-.14412
3	.16902	-.07758	.06587	-.11981
4	.12030	-.05497	.05258	-.10424
5	.07135	-.02700	.03570	-.09031
6	.03408	.00115	.01657	-.07336
7	.03636	.00387	.02286	-.05798
8	.06207	-.00691	.03836	-.04770
9	.07180	-.00731	.04059	-.04093
10	.08669	-.01757	.05057	-.04012
11	.11014	-.03265	.06299	-.04006
12	.16587	-.20984	.24857	-.26595
13	.16609	-.11573	.13752	-.14412
14	.17415	-.09329	.10285	-.11981
15	.16984	-.06128	.04905	-.10424
16	.15922	-.06311	.05825	-.09031
17	.13547	-.04490	.04213	-.07336
18	.10343	-.02179	.02868	-.05798
19	.06977	.00082	.01455	-.04770
20	.05319	.01072	.01115	-.04093
21	.04661	.01107	.01517	-.04012
22	.04233	.01151	.01750	-.04006
23	.14925	-.20058	.23392	-.26595
24	.14901	-.10955	.12903	-.14412
25	.15071	-.09395	.10910	-.11981
26	.15332	-.08603	.09883	-.10424
27	.15678	-.07786	.08716	-.09031
28	.16070	-.05748	.05580	-.07336
29	.16040	-.03310	.01739	-.05798
30	.15640	-.03473	.02806	-.04770
31	.14848	-.03154	.03468	-.04093
32	.13225	-.02336	.03135	-.04012
33	.11211	-.01495	.02941	-.04006
34	.14331	-.20075	.23432	-.26595
35	.14342	-.10938	.12899	-.14412
36	.14370	-.09038	.10350	-.11981
37	.14424	-.08007	.08952	-.10424
38	.14474	-.07263	.08038	-.09031
39	.14546	-.06215	.06778	-.07336
40	.14666	-.05397	.05819	-.05798
41	.14815	-.04976	.05237	-.04770
42	.14990	-.04683	.04647	-.04093
43	.15198	-.04792	.04356	-.04012
44	.15398	-.04636	.04500	-.04006
45	.14022	-.21168	.25309	-.26595
46	.14038	-.11769	.14344	-.14412
47	.14054	-.08974	.10248	-.11981
48	.14085	-.08102	.09111	-.10424
49	.14119	-.07349	.08196	-.09031
50	.14151	-.06315	.06996	-.07336
51	.14182	-.05445	.06007	-.05798
52	.14215	-.04746	.05006	-.04770
53	.14254	-.04303	.04231	-.04093
54	.14289	-.04393	.03996	-.04012
55	.14325	-.04412	.03598	-.04006

OGIVE CYLINDER BODY WITH 45 DEGREE SWEEP NACA 65A004 MID-WING
SINGULARITY PANELING FOR SAMPLE CASE

INTEGRATION OF THE PRESSURE DISTRIBUTION
ON THE WING LOWER SURFACE

POINT	X	Y	Z	X/C	2Y/B	Z/C	CP	CN	CT	CM	POINT
1	16.76499	2.30734	0.00000	.05000	.19228	0.00000	.25517	.32516	.03833	1.31626	1
2	17.61117	2.30734	0.00000	.15000	.19228	0.00000	.17381	.19147	.00858	.61305	2
3	18.45734	2.30734	0.00000	.25000	.19228	0.00000	.14959	.16478	.00410	.38817	3
4	19.30352	2.30734	0.00000	.35000	.19228	0.00000	.09354	.10304	.00104	.15554	4
5	20.14970	2.30734	0.00000	.45000	.19228	0.00000	.03394	.03738	-.00020	.02480	5
6	20.99587	2.30734	0.00000	.55000	.19228	0.00000	.00168	.00185	-.00004	-.00034	6
7	21.84205	2.30734	0.00000	.65000	.19228	0.00000	.00857	.00944	-.00032	-.00971	7
8	22.68823	2.30734	0.00000	.75000	.19228	0.00000	.01865	.02054	-.00088	-.03852	8
9	23.53441	2.30734	0.00000	.85000	.19228	0.00000	.02880	.03172	-.00148	-.08633	9
10	24.38058	2.30734	0.00000	.95000	.19228	0.00000	.05438	.05990	-.00282	-.21371	10
11	16.82577	4.12568	0.00000	.05000	.34381	0.00000	.31460	.54513	.06426	1.08331	11
12	19.55072	4.12568	0.00000	.15000	.34381	0.00000	.22655	.39257	.01759	.49553	12
13	20.27568	4.12568	0.00000	.25000	.34381	0.00000	.17245	.29882	.00743	.16056	13
14	21.00063	4.12568	0.00000	.35000	.34381	0.00000	.14107	.24445	.00247	-.04587	14
15	21.72559	4.12568	0.00000	.45000	.34381	0.00000	.12247	.21221	-.00113	-.19366	15
16	22.45054	4.12568	0.00000	.55000	.34381	0.00000	.07674	.13297	-.00286	-.21776	16
17	23.17550	4.12568	0.00000	.65000	.34381	0.00000	.02777	.04812	-.00165	-.11367	17
18	23.90045	4.12568	0.00000	.75000	.34381	0.00000	-.00584	-.01011	.00043	.03122	18
19	24.62541	4.12568	0.00000	.85000	.34381	0.00000	-.01631	-.02825	.00132	.10772	19
20	25.35036	4.12568	0.00000	.95000	.34381	0.00000	-.01720	-.02980	.00140	.13520	20
21	21.51108	6.49507	0.00000	.05000	.54126	0.00000	.30197	.40146	.04732	-.28025	21
22	22.07808	6.49507	0.00000	.15000	.54126	0.00000	.22019	.29274	.01312	-.37033	22
23	22.64507	6.49507	0.00000	.25000	.54126	0.00000	.15751	.26258	.00653	.48107	23
24	23.21207	6.49507	0.00000	.35000	.54126	0.00000	.18127	.24099	.00244	.57815	24
25	23.77906	6.49507	0.00000	.45000	.54126	0.00000	.15125	.20109	-.00107	-.59643	25
26	24.34664	6.49507	0.00000	.55000	.54126	0.00000	.10311	.13708	-.00295	-.48431	26
27	24.91305	6.49507	0.00000	.65000	.54126	0.00000	.07770	.10330	-.00354	-.42354	27
28	25.48005	6.49507	0.00000	.75000	.54126	0.00000	.07472	.09934	-.00426	-.46362	28
29	26.04704	6.49507	0.00000	.85000	.54126	0.00000	.06182	.08219	-.00383	-.43018	29
30	26.61404	6.49507	0.00000	.95000	.54126	0.00000	.04414	.05868	-.00276	-.34040	30
31	24.16649	8.83808	0.00000	.05000	.73651	0.00000	.30182	.29018	.03420	.97310	31
32	24.57728	8.83808	0.00000	.15000	.73651	0.00000	.21633	.20799	.00932	.78293	32
33	24.98808	8.83808	0.00000	.25000	.73651	0.00000	.18771	.18047	.00449	-.75347	33
34	25.39887	8.83808	0.00000	.35000	.73651	0.00000	.16950	.16296	.00165	.74733	34
35	25.80967	8.83808	0.00000	.45000	.73651	0.00000	.15022	.14442	-.00077	-.72164	35
36	26.22046	8.83808	0.00000	.55000	.73651	0.00000	.12952	.12452	-.00268	-.67336	36
37	26.63126	8.83808	0.00000	.65000	.73651	0.00000	.11537	.11092	-.00381	-.64536	37
38	27.04205	8.83808	0.00000	.75000	.73651	0.00000	.10711	.10298	-.00441	-.64146	38
39	27.45285	8.83808	0.00000	.85000	.73651	0.00000	.10512	.10106	-.00471	-.67103	39
40	27.86364	8.83808	0.00000	.95000	.73651	0.00000	.10462	.10059	-.00473	-.70920	40
41	26.58702	10.97384	0.00000	.05000	.91449	0.00000	.31663	.15832	.01866	.91414	41
42	26.85543	10.97384	0.00000	.15000	.91449	0.00000	.22349	.11182	.00501	.67565	42
43	27.12384	10.97384	0.00000	.25000	.91449	0.00000	.18804	.09408	.00234	.59373	43
44	27.39225	10.97384	0.00000	.35000	.91449	0.00000	.17134	.08573	.00087	.56403	44
45	27.66066	10.97384	0.00000	.45000	.91449	0.00000	.15208	.07609	-.00041	.52104	45
46	27.92907	10.97384	0.00000	.55000	.91449	0.00000	.13093	.06551	-.00141	-.46617	46
47	28.19748	10.97384	0.00000	.65000	.91449	0.00000	.11329	.05668	-.00195	.41859	47
48	28.46589	10.97384	0.00000	.75000	.91449	0.00000	.10052	.05029	-.00215	.38490	48
49	28.73430	10.97384	0.00000	.85000	.91449	0.00000	.09666	.04836	-.00226	.38310	49
50	29.00271	10.97384	0.00000	.95000	.91449	0.00000	.09814	.04910	-.00231	-.40212	50

TOTAL COEFFICIENTS

ON THE WING

REFA=	144.0000	REFB=	12.0000	REFC=	6.8900
REFX=	20.8130	REFZ=	0.0000		
CN=	.1969				
CT=	.0046				
CM=	-.0705				
CL=	.1957				
CD=	.0217				
XCP=	-.3600				

TOTAL COEFFICIENTS

ON THE COMPLETE CONFIGURATION

REFA=	144.0000	REFB=	12.0000	REFC=	6.8900
REFX=	20.8130	REFZ=	0.0000		
CN=	.2495				
CT=	.0081				
CM=	-.0651				
CL=	.2479				
CD=	.0298				
XCP=	-.2628				

SECTION COEFFICIENTS

ON THE WING

DELY= 1.3030 REFL= 6.8900 XLE= 16.3419
CN=.1974 CT=.0037 CM=.0356 CL=-.1963 CD=.0209 XCP=.1812

DELY= 2.4000 REFL= 6.8900 XLE= 18.4633
CN=.2305 CT=.0063 CM=-.0135 CL=.2291 CD=.0263 XCP=-.0590

DELY= 2.3600 REFL= 6.8900 XLE= 21.2276
CN=.2843 CT=.0069 CM=-.1299 CL=.2846 CD=.0318 XCP=-.4563

SECTION COEFFICIENTS

ON THE WING

DELY= 2.3700 REFL= 6.8900 XLE= 23.9611
CN=.2841 CT=.0058 CM=-.2140 CL=.2825 CD=.0305 XCP=-.7577

DELY= 1.9000 REFL= 6.8900 XLE= 26.4528
CN=.2732 CT=.0062 CM=-.2762 CL=.2716 CD=.0300 XCP=-1.0171

CPSTAG = 2.45650 CPCRIT = 1.13092 CPVAC = -.35360
TIME = 303.80100



REFERENCES

1. Craiden, C. B.; Description of a Digital Computer Program for Aircraft Configuration Plots. NASA TM X-2074, September, 1970.

